

*For the Advanced Computer User*

# Micro/Systems Journal™

## *TurboCharge Your 8086/8088 Computer*

see pages 32-43

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November / December 1985

Vol. 1 / No. 5

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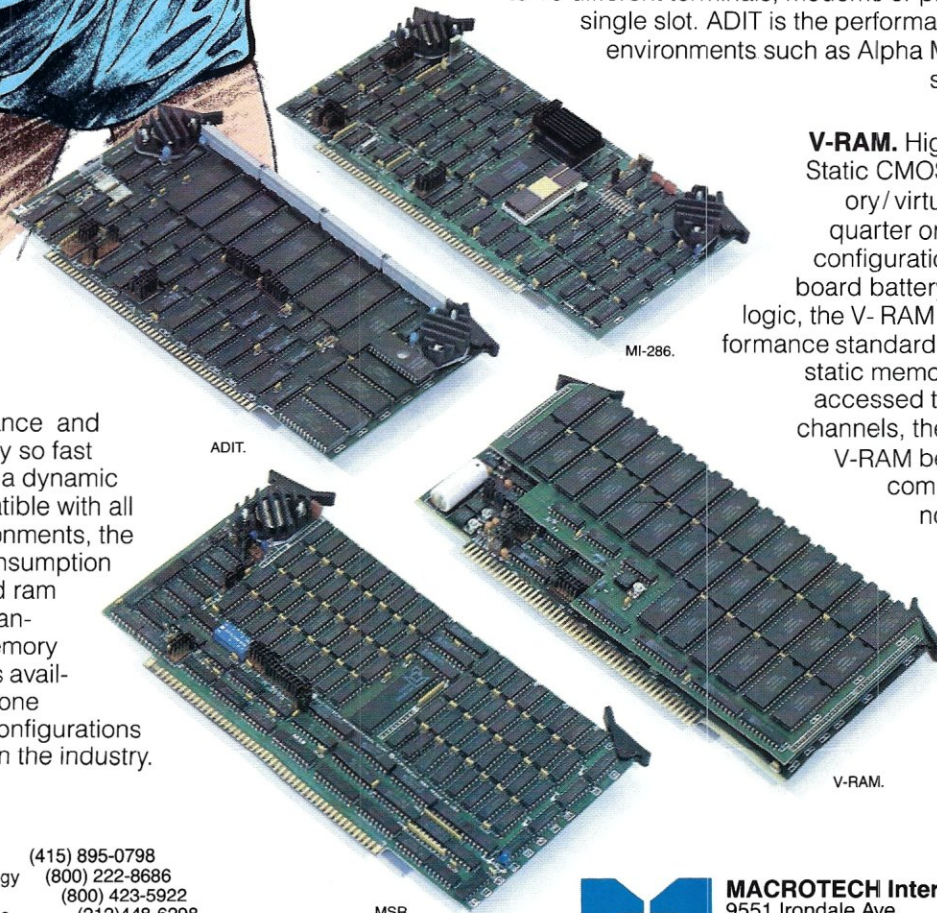


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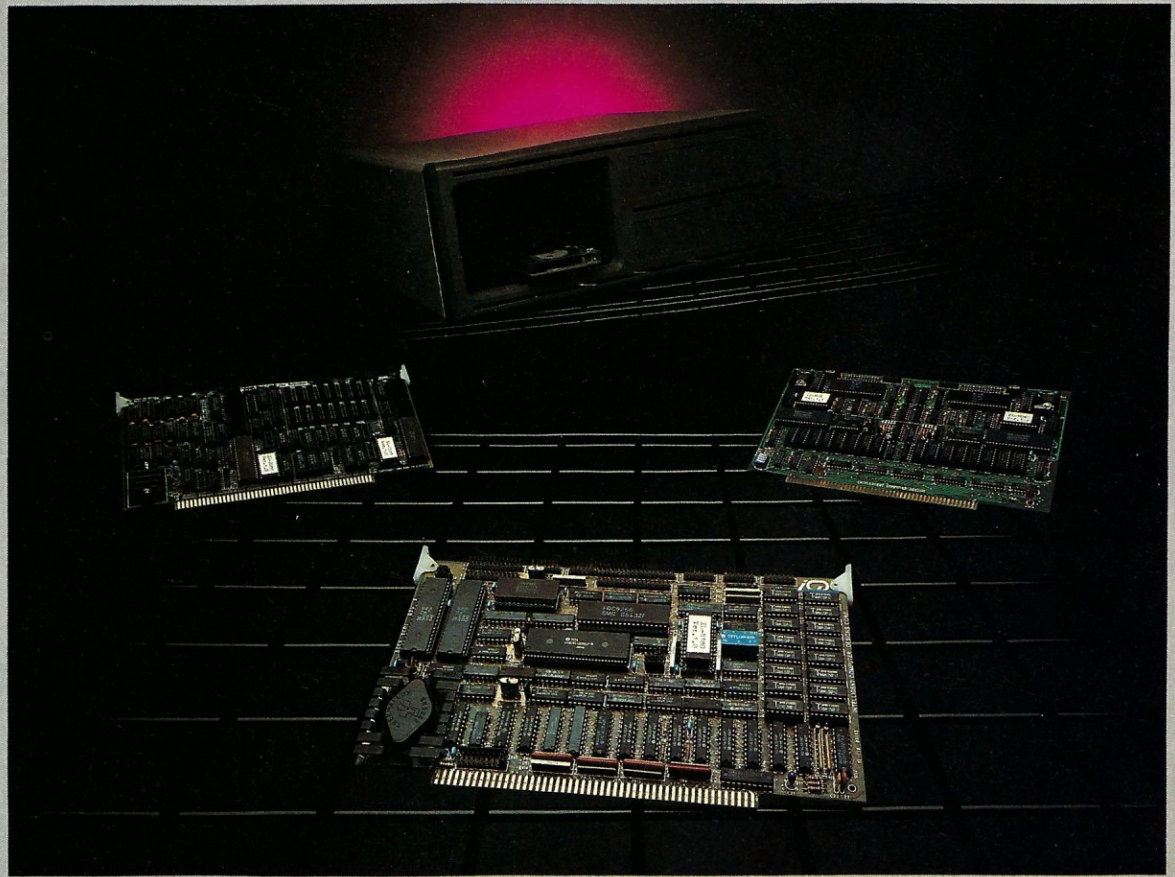
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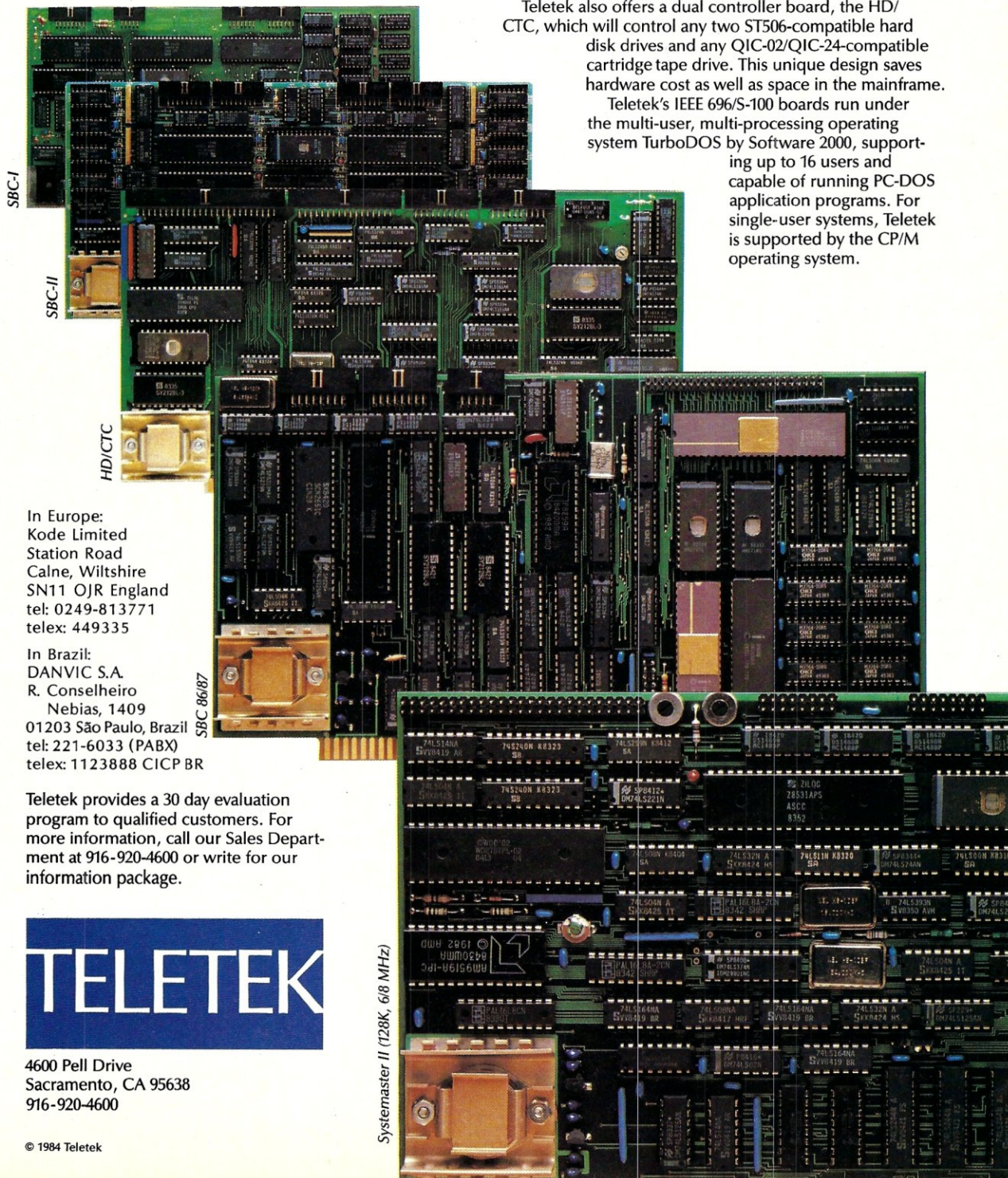
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U.S.	\$20	\$35
Canada & Mexico	\$28	\$52
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ADVERTISING RATES: Available on request. Call (201) 522-9347 or write to: M/SJ, Box 1192, Mountainside, NJ 07092.

CHANGE OF ADDRESS: Please send old label and new address to: Micro/Systems Journal, Box 1192, Mountainside, NJ 07092.

CORRESPONDENCE: Address all letters to: M/SJ, Box 1192, Mountainside, NJ 07092. The editor may also be contacted via MCI Mail (SLIBES).

Micro/Systems Journal (ISSN #8750-9482) is published bi-monthly by Libes Inc., 995 Chimney Ridge, Springfield NJ 07081. Second Class postage is paid at Springfield, NJ and at additional offices. **POSTMASTER:** send address changes to MICRO/SYSTEMS JOURNAL, PO Box 1192, Mountainside NJ 07092.

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| MS-DOS, XENIX       | Microsoft                       |
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| 68000, 68010, 68020 | Motorola                        |

# Editor's Page

by Sol Libes



## FUTURE DIRECTIONS FOR MICROSOFT'S OPERATING SYSTEMS

Operating System (OS) software is the silent foundation of all computer systems. At its most elemental level, this software enables the loading and running of application programs as well as communications between the program, keyboard, display and peripheral devices, e.g. printers. Operating-system software designed for use with a disk-type, software-storage device is called a "Disk Operating System" or DOS. DOS software usually has additional features, such as the ability to show the user what is available on the disk.

Microsoft is, without a doubt, the leading supplier of microcomputer OS and DOS software, having five OS and DOS packages currently in use by microcomputer-system manufacturers. They are called packages because in addition to the OS or DOS program they also contain utility programs which the OS or DOS can use to add functions to the OS or DOS (e.g. format a disk).

Microsoft's five OS and DOS packages include, of course, PC-DOS and MS-DOS for use on the IBM-PC and IBM-PC compatibles. Microsoft has also created XENIX (a Unix, multi-user, multi-processing DOS), MSX (for low-cost, Z80, cassette-based, home-computer systems), and MSX-DOS (for low-cost, Z80, disk-based, home-computer systems). Microsoft has also created two MS-DOS extensions: MS-Windows (an MS-DOS environment for applications' software which uses bit-mapped graphics and a mouse) and MS-Net (a networking extension for MS-DOS). Microsoft thus has the broadest line of microcomputer, operating-systems' software currently available.

At a recent National Computer Conference, Steve Ballmer, Vice President of Marketing at Microsoft, gave some insight into Microsoft's system-software strategies. The following discussion is based, in large measure, on his talk.

### SOFTWARE & SYSTEM COMPATIBILITY

Microsoft is attempting to provide upward compatibility among all its operating systems, something no other system software producer has ever really attempted. Microsoft has adopted a philosophy that all new versions of operating systems must be able to run software written for earlier versions...this is called "upward" compatibility.

Microsoft is also attempting to provide compatibility between operating systems. Their greatest concern appears to be compatibility between MS-DOS, PC-DOS, and XENIX. Thus, they have attempted, wherever possible, to provide the same functionality, hierarchical file system, and the same memory management scheme in each DOS.

Microsoft claims they already have source-code compatibility between systems. Thus applications' software written in a Microsoft, high-level language can be compiled for either PC-DOS, MS-DOS, or XENIX. They are also working on binary-level compatibility so that applications' software can run under either operating system without compilation or modification.

Microsoft is also promising networking compatibility between users of different DOS kernels to guarantee software reliability. This means that what one user does on his

system does not affect data on another system in the network.

### DATA RELIABILITY

As systems become more complex with multi-tasking and networking capabilities data, reliability becomes increasingly more difficult. Thus a protection system is needed to insure that data is not altered inadvertently.

For example, current 8088- or 8086-based systems do not provide any hardware protection, allowing any program to take command of the system at any time and do anything that it wants. Thus, in a networking system, there is no way of certifying that data at any one workstation is reliable.

The Intel, 80286 microprocessor includes on-board protection. Thus, Microsoft will, in all likelihood, introduce multi-tasking DOS exclusively for 80286-based systems with data reliability features.

### OPERATING SYSTEM PHILOSOPHIES

MSX and MSX-DOS are Microsoft's home-computer versions of OS and DOS, respectively. They are very small, single-user, single-tasking systems with very friendly user interfaces. They are currently being used by several Japanese, personal-computer manufacturers in their consumer-oriented systems. These systems are being exported to countries other than the U.S. The price wars that have occurred in the U.S.-consumer, computer marketplace have made them hesitate.

PC and MS-DOS are Microsoft's office-worker versions of DOS. They are also single-user systems. Although the current versions of MS-DOS and PC-DOS are single-tasking systems, the next versions are expected to be capable of multi-tasking. Thus, a user will be able to handle communications, electronic mail, or networking tasks in the background. These new versions are also expected to have an advanced easy-to-use interface.

XENIX has been designed by Microsoft to serve as a multi-user operating system for transaction-processing in a small business environment (data-base access). It provides a customizable user shell so that software developers can create turnkey systems to hide the OS from the user altogether.

### LOOKING TO THE FUTURE

Microsoft expects the Intel 8086, 80286, and 80386 (32-bits) to be the dominant microprocessors. As discussed earlier, the 286 includes hardware, memory-protection logic to

insure data integrity in multi-processing systems. There is no doubt that the 386 will include even more powerful memory-management features.

The likelihood is that the new versions of PC-DOS and MS-DOS will require more memory. Thus, we can expect that the typical memory size on the new 286-based systems will be in the megabyte range. Considering that we will have in memory the DOS kernel, the networking support, a window manager, and applications such as mail programs, integrated packages (Symphony, etc.), talking about kilobyte sized memory will become a thing of the past.

The current IBM-PC with its slow, 8088-based processor, 640K sized memory, and primitive, memory-management system, will be inadequate for the next generation of desk-top office workstations.

Microsoft is also expected to introduce a new version of PC/MS-DOS for the 8088 and 8086 systems currently in use. Expect this new version to include a more robust, memory-management system that provides for relocation of code, swapping of code, and virtual memory.

Microsoft is also expected to make the new versions of MS-PC/MS-DOS more modular. The new versions of the operating systems are expected to be dynamic. Modules will be moved in and out of memory as they are needed. As a form of dynamic linking, sometimes called "late binding", essentially any piece of the operating system will be available at run time. This is expected to allow binary compatibility between PC/MS-DOS and XENIX by linking in the appropriate OS, service library at run-time.

Microsoft has indicated it has already begun initial development of versions of MS-DOS and XENIX for Intel, 80386-based systems. Intel has already furnished preliminary data on the device to key users and is promising samples shortly with limited production to begin in early '86. Considering that Microsoft is already at work on operating systems for the device, it appears that the 386 versions of PC/MS-DOS and XENIX will be released in early 1986.

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# News, Views & Gossip

by Sol Libes

## GOSSIP

**IBM** is expected to change the motherboard in the AT soon. Look for the new board to contain 640K of RAM.....gone will be piggy-backed chips. Also expect some new VLSI chips to shrink the chip count. And a System V version of Xenix for the AT is due very early next year.....Big Blue is finally expected to introduce its laptop machine in the first half of '86. Expect it to use a CMOS 80286, 3.5" drives, and back-lit screen.....IBM is reportedly asking floppy disk drive vendors to quote on 3.5", double-sided drives storing 1.6Mbytes unformatted and 1.2Mbytes formatted.

**Digital Research** has reportedly sold a significant minority interest (estimated at about 12%) to Northern Telecom Inc., a Nashville Tennessee telecommunications company for about \$6 million. It is also rumored that Motorola will take another "minority" interest in DRI to help it through its hard times. Olivetti is already an investor in DRI. NT is using GEM in their 68000-based Meridian computers and Motorola sells DRI's languages for the 68000. DRI reported approximately \$40 million in gross revenue for its last fiscal year, down from the previous year's \$55 million.

**Borland International**, of Turbo-Pascal fame, seeking to enlarge its business, is expected to shortly introduce Basic, Assembler, C, Modula-2, and Pascal for the Commodore Amiga. SideKick-Plus and a word-processing package are expected early next year. Borland, which started strictly as a mail-order vendor, now gets over 70% of its revenue from dealers.

**Intel** has disclosed that it is hard at work developing the 80486 microprocessor which will be upward compatible with the 80386, 80286, and 8086 microprocessors.

**Texas Instruments** demoed the prototype of a new graphics IC at a recent conference. Called the TMS34070, it integrates 3 DACs, a video processor, ROM, and RAM. A color look-up table allows the displaying of 16 colors from a 4,096 palette on each line that can be changed line by line for an 800 by 600

pixel display. A similar chip is expected from INMOS.

Early next year **Kodak** is expected to begin sampling a 9-Gbyte, table-top size, optical-disk system. Although the systems from Sony, Hitachi, and NEC have higher capacities, they are much larger in size.

**Sony** is reported to be developing 1.6 and 2Mbyte versions of their popular 3.5" floppy disks. The units, which feature 135 tracks/inch and 17.4Kbits/inch, are expected to be in production some time next year.

## AT NOT DOING WELL

Sales of the IBM AT are reportedly not doing well and many dealers are already offering significant discounts and special deals on them, only a little over a year since its introduction.

It appears to be a repeat of the PC/XT story. IBM did not anticipate the great demand for the unit. Hence, there was a severe shortage of units when it was introduced. IBM upped production substantially at the same time that the clone makers started shipping. The result.....a glut of ATs and AT-clones.

A further problem for IBM has been reports of reliability problems with the machine, the high price of the system, and compatibility problems with the PC/XT. This has resulted in a "window of opportunity" for the AT- and XT-clone makers.

In the meantime, IBM dealers are crying the blues, claiming that IBM is flooding an already saturated market with PC's and XT's. They claim that large-volume dealers, who are forced to take at least 400 systems/month in order to maintain an additional 8% discount, are discounting (typically 28-30%) or dumping on the grey market (which despite IBM's attempts to stamp it out is still flourishing). IBM is also appointing more large-volume dealers and forcing dealers to take a product mix that includes portables and PCjrs which have accumulated in IBM's warehouses. These IBM tactics are squeezing many of the smaller independent dealers out of business.

## APPLE NEWS

There are rumors that Apple is hard

at work on two new products - a portable "Flat-Mac" and a "Color-Mac" using the 68010 processor. There are also rumors that an "open-Mac" with slots for plug-in cards and detailed technical info will be introduced shortly.

In the meantime, sales of the Macintosh are lagging despite rebates (\$150 and \$250), customer sweepstake contests (grand prize \$100,000), promotional giveaways (free bicycle with a specific system configuration), additional bulk discounts, and salesmen incentives (\$50 per system sold). And, Lotus' Jazz, an integrated software package, has not boosted sales as expected. The package has proved difficult to use on a machine designed to be easy to use.

Apple has still not penetrated the corporate market where IBM now reigns supreme. Here the largest applications are word processing, spreadsheet use, and data-base management. Thus, the lack of an internal, hard-disk system, slow speed of operation, inability to upgrade the system internally, as well as network with IBM systems has proved to be a handicap.

Although the Mac has achieved some success in the home market, it now has competition from Atari and Commodore who are now offering Mac features at Apple-II prices.

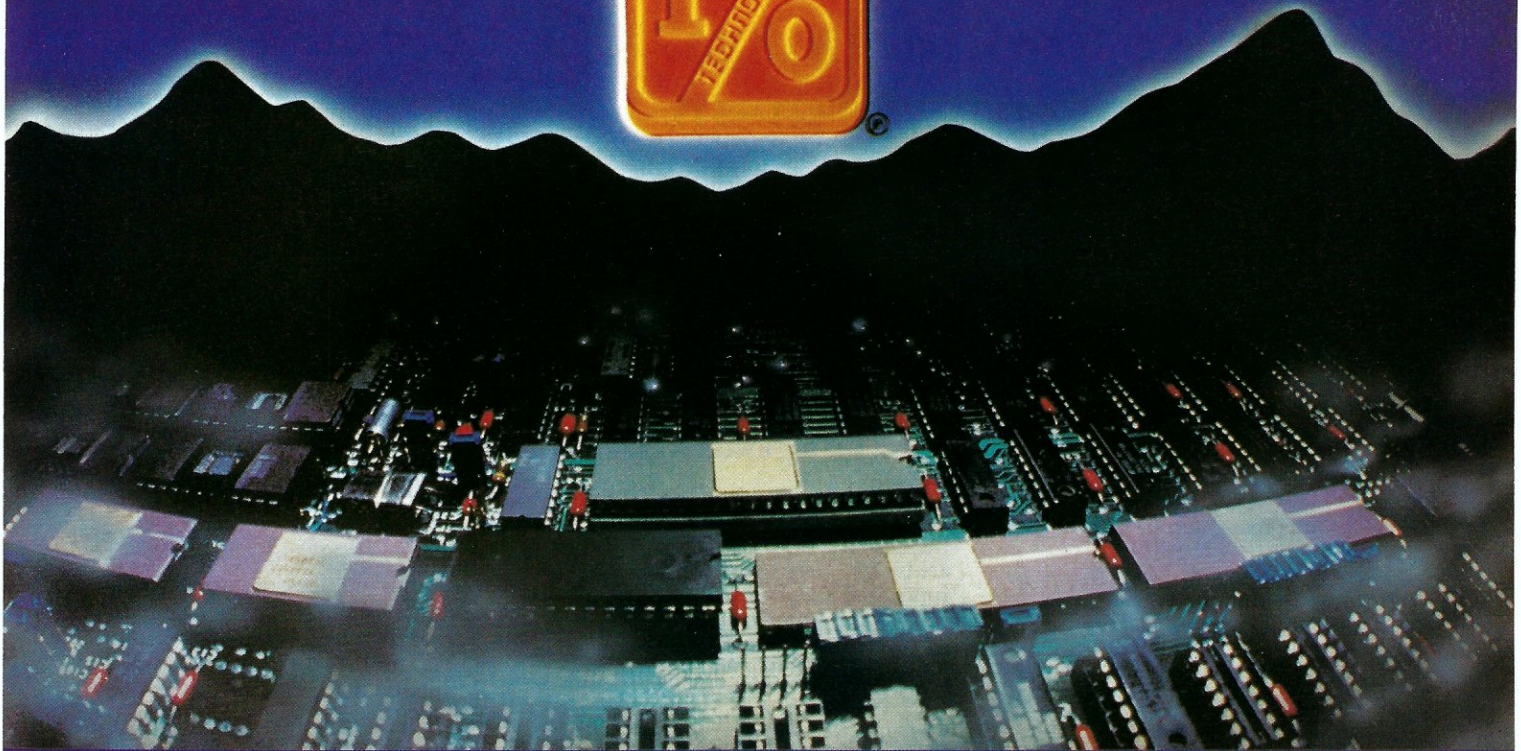
## ZCPR NEWS

The ZCPR3 printed manual is finally available. All users of ZCPR and those interested in running it on their Z80-based systems should get a copy. It's \$19.95+\$4 S&H and is available from: Echelon Inc., 101 First St, Los Altos CA 94022, tel:(415)948-3820.

I think that Echelon is doing a terrific job with ZCPR3. All those users of CP/M who have been deserted by Digital Research's failure to upgrade CP/M-80, now have Echelon providing a host of upgrades, advanced software-development tools and advanced utilities. Echelon has also introduced an upgraded version of CP/M for systems using the new Z80-compatible, Hitachi-HD64180 microprocessor (see last issue of MS/J; we expect to review this operating system in an upcoming issue).

Another thing that impresses me about Echelon is their user support. They publish a "Z-News" newsletter twice a month providing a great deal of information to ZCPR users as well as support a number of RBBS (Remote Bulletin Board Systems) around the country. These RBBS's are referred to

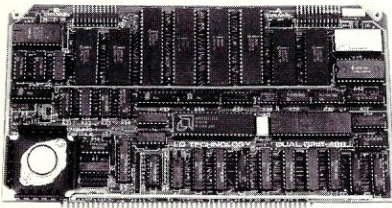




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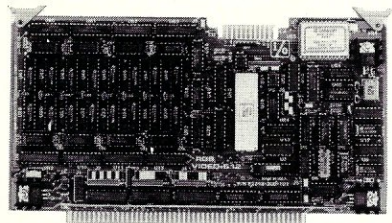
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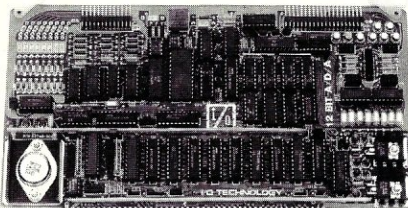
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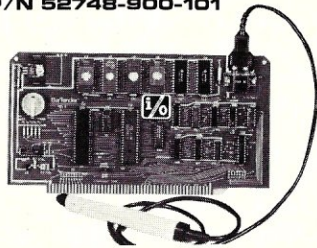


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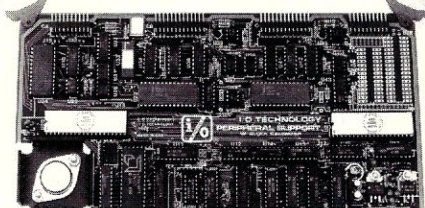
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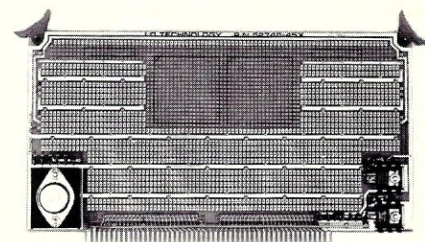
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unplugged from the wall) and check the slow-blow fuse inside the case. It is mounted in a fuse holder. Incidentally, this fuse is not an IBM-replaceable item. If you bring your PC/XT/AT into an IBM service center for repair and they find the power supply is defective they replace it without checking the internal fuse (a replacement power supply is \$290!).

## TRON IS COMING

TRON (The Real-time Operating Nucleus) is an operating system being developed by a group, headed by Professor Ken Sakamura, at the University of Tokyo (considered the MIT of Japan). TRON has already been licensed by NEC, Mitsubishi, Matsushita, Xerox Japan, and Canon.

TRON is expected to be a full-blown, enhanced operating system specifically designed to take advantage of 32-bit microprocessor chips such as the Motorola 68020. TRON is planned as an operating-system nucleus contained in a single ROM with other ROMs containing different system and application interfaces. TRON will feature fast real-time response and task-switching. NEC is expected to be the first to introduce a TRON system, sometime next year.

## NOTEWORTHY BULLETIN BOARDS

Dan Wise's "Cleveland County BBS" (Shelby NC) has 45 different sections including S-100, CP/M, and UNIX/XENIX and callers can chat with "Willard" (artificial intelligence). The BBS runs 7 days 24 hrs, and there is no time limit. Call (704)482-8012.

Mike Connick (Reston VA) runs a BBS devoted to C at (703)476-9459.

## RANDOM BITS

The **Forth Interest Group (FIG)** will hold the "Forth Modification Laboratory" conference at the Asilomar Conference Grounds, Pacific Grove CA, Nov 29-Dec 1, to discuss and share new proposals to enhance the Forth Language. For more info, call (408)277-0668 or write FIG, Box 8231, San Jose CA 95155.

**Teletek** (4600 Pell Dr., Sacramento CA 95838; (916)920-4600) is now offering an MS-DOS emulator (non-hardware specific) which runs under TurboDOS. Graphics capability is being explored.

**Intel** reports that it has begun shipping versions of the 80286 which run at clock speeds of 10-12.5Mhz.

**Intercontinental Micro Systems** has acquired the manufacturing rights to **Musys'** S-100 product line.

as "Z-Nodes". Two of the Z-Node operators are developing a full data-link, satellite-relay function to network Z-Nodes. For more information on Z-Nodes, contact Echelon or log into one of the Z-Nodes. Here are some of the Z-Node phone numbers:

(415)489-9005 CA (Z-Node Central)  
(915)755-3342 TX

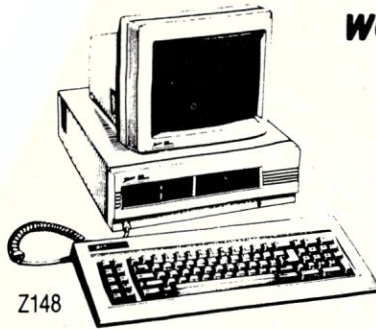
## SERVICING AN IBM-PC

Users who service their own PC or clone might be interested in obtaining a

copy of the Howard W. Sams "Computerfact" package (\$39.95 at most electronic-parts suppliers). It includes complete schematics, circuit-board photos with all components identified, and troubleshooting instructions. It covers the PC motherboard, power supply, keyboard, display, floppy-disk controllers, and several other optional cards.

Here is another service hint. The PC's power supply is enclosed in its own case. If your power supply fails, try opening the case (with power plug

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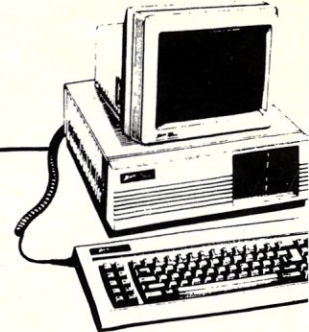
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Please send your letters to: Micro/Systems Journal, Box 1192, Mountainside NJ 07092.

Dear Mr. Libes,

"Structured Programming with M80" (July/August '85) has some interesting constructs. However, preferring BASIC to PASCAL as a structured language, I have enclosed an INSTR and ON n GOSUB!GOTO, which could probably be modified to IN [list] and sort of a version of CASE. Oh yes, in the REPEAT code on page 32, it certainly will; BC is the counter, but HL is being checked for zero. LDIR is a repeat and even CPI can be used if followed by JP PE for a test loop or zeroing a block. Both take up quite a bit less space than the code presented.

The previous issue had an interesting article on Loadable BIOS drivers for CP/M. Although in SLCLR, on page 70, ANA A ! JP SL50 should have probably been a JZ SL50. In debugging CCP replacements a number of techniques were developed to allow the code to be dropped into RAM without altering the disk image. Since the loader takes less than one record it was easier to include it in the code rather than as a separate program. As a small example, a Z80 register dump is enclosed. It contains a few useful routines including the HEX routine, macros to do page relocatable code, a Z80 cpu test, and an exit for those who try to type a .COM file. The code was assembled using a conditional restart as the trap (RST 38h). If this is to be used with a vanilla version of DDT or ZSID it is recommended that the restart number be changed. A 8088 version of INSTR is also included.

L. Barker

*Regretfully we did not have the space available to publish the code enclosed with this letter. We suggest readers who wish copies contact Mr. Barker at Box 135, Chicago IL 60690.*

Dear Mr. Libes:

Shame on you for printing Charles Prohaska's *patch* in the July/August issue! The binary-to-ASCII-hex conversion that he *fixed* dates back (at least) to '77 or '78, when an 8080 version appeared as a "byte-saving programming trick" in Dr. Dobbs Journal. It works perfectly as originally written.

Either Mr. Prohaska has a very sick processor in his system, or he never actually ran his code, but condemned it based on his (mis)understanding of the written source. The relevant instructions are:

```
ADD A,90H
DAA
ADC A,40H
DAA
```

Contrary to his assertion, binary 1010 (for example) is correctly converted to ASCII "A". This first addition gives hex 9A (decimal 100). The decimal-adjust leaves 0 in the accumulator and *sets the carry flag*, as is necessary for multi-byte BCD additions. The following add-with-carry therefore gives not 40, as he claims, but 41.

Bill Snyder, Richardson TX

*We would also like to thank Patrick O'Leary, County Kildare Ireland and L. Barker, Chicago IL for also picking up this error and pointing it out to us. -*

Dear Sol:

Has DRI gone to outer space?

Perhaps some readers might enjoy the dump (shown in the box below) of the Digital Research Concurrent PCDOS 4.1 embedded copyright message.

Alex K. H. Soya, Melbourne Beach FL

```
OA>SID86
SID86 1.0
#RCHDIR.CHD

START      END
2D40:0000 2D40:097F
#D80

2D40:0080 E9 3B 00 43 4F 50 59 52 49 47 48 54 28 63 29 20 .;.COPYRIGHT(c)
2D40:0090 31 39 38 35 2C 20 49 4E 54 45 52 47 41 4C 41 43 1985, INTERGALAC
2D40:00A0 54 49 43 20 44 49 47 49 54 41 4C 20 52 45 53 45 TIC DIGITAL RESE
2D40:00B0 41 52 43 48 20 20 30 32 2F 32 39 2F 38 35 B1 0C ARCH 02/29/85..
2D40:00C0 E8 A2 03 80 E7 FD 80 FF 14 75 05 80 FB 32 73 0B .....u...2a.
2D40:00D0 BA 8F 01 E8 8B 03 B1 00 E8 8A 03 B1 6E B2 00 E8 .....n...
2D40:00E0 83 03 B1 2D B2 FF E8 7C 03 8A 0E 80 00 80 F9 00 .....l.....
2D40:00F0 75 03 E9 37 03 BE 80 00 BF 0F 01 8A 04 32 E4 FE u...7.....2..
2D40:0100 C0 8B C8 F3 A4 BF 0F 01 4E FE 0D 80 3C 20 74 F8 .....N...< t.
2D40:0110 80 3C 09 74 F3 FE 05 C6 44 01 00 BF 5C 00 C6 45 .<t.....D...\.E
2D40:0120 0C 00 C6 05 00 BE 0F 01 8A 0C 46 8A 04 3C 20 74 .....F...< t
2D40:0130 04 3C 09 75 05 46 FE C9 EB F1 80 F9 05 75 6B 81 .<.u.F.....uk.
```

Sol:

When a magazine really works, it speaks so personally and appropriately to its readers that they make it their own, taking personal offense at the less-effective articles and taking pride in the good ones. Such magazines don't belong to their publishers or editors but to their devoted readers. The staff are the caretakers.

So the gut reaction of us readers when Ziff-Davis cancelled Computers and Electronics and Microsystems was that they had no right. In a legal sense they certainly had every right, but in a more important sense I think the gut reaction is the correct one. They had no right.

Thanks for keeping our Micro[ ]Systems [Journal] alive.

Mike Swaine  
Editor Dr. Dobb's Journal

P.S.: Yes, I think you're crazy.

Dear Sol:

I enjoyed "The CP/M Bus" in the May/June issue. Reading Bruce Ratoff's choices of favorite public domain programs started me thinking what were my most useful CP/M programs. I came up with at least a half a dozen in a few minutes.

My favorite is a directory program that has been named "D". It produces an alphabetical listing in a vertical format with file size and disk space included. The horizontal version, SDIR, is much harder to read and I do not use it. Next on the list is my file manipulation program DISK 7.6, that someone named "T". I really like the CRC verification feature on the copy command.

For handling library files I have gotten used to NULU10 and will get NULU11 off the board shortly. I figure this is really a matter of which library utility program you use. For handling the squeezed files off of bulletin boards, I find that NSWP207 is great. The view function for looking at squeezed files is very useful and

eliminates the need to unsqueeze before you can read the file. It also has unsqueeze and the usual file manipulation features.

For viewing ASCII files, the similar programs BISHOW-2 and BISHOW31 replace the CP/M TYPE command. BISHOW31 will even unsqueeze squeezed files. They both allow the forward and backward viewing of files. A gem with limited application but very useful is SORTDIR3 for alphabetizing the disk directory. It is useful for programs like BASIC where the FILES command does not sort the file names but rather just displays them like the CP/M DIR command.

There is one utility I have not been able to locate, a screen dump utility. I know there is one specifically for the KayPro, DUMP24.

Bob Phelps, Westerville OH

Dear Sol:

I enjoyed reading Steven Bosak's "Scientific & Technical Word Processors" (Part 1) so much that I took the liberty of calling him about PS, my *secret WP program*. The **PS Technical Word Processor** was written by Murray Sargent, author of *IBM PC From the Inside Out* (Addison-Wesley). Murray is a Professor of physics at the University of Arizona. He developed the PS for his papers but the project (like most computer projects) expanded over time.

PS is based on Phoenix's PMATE programmer's editor, but Murray has turned it into a powerful, menu-driven, proportionately-spaced, what-you-see-is-what-you-get word processor complete with mail-merge. Unlike most other technical editors, PS is most at home on Diablo-compatible daisywheel printers from the 1620 on up - and the proportionately-spaced text appears on the screen as well! Although I don't do scientific WP, I use PS for everything from general correspondence to our 500-page RUN/C manual. I don't think there is a more powerful, more flexible, faster word processing package available on any system.

Mr. Bosak agreed to take a look at PS and he should have it by now. I hope some day it will be possible to let your readers know about PS so they can compare it themselves to the other scientific packages on the market.

Todd Katz, Age of Reason Co., NY NY

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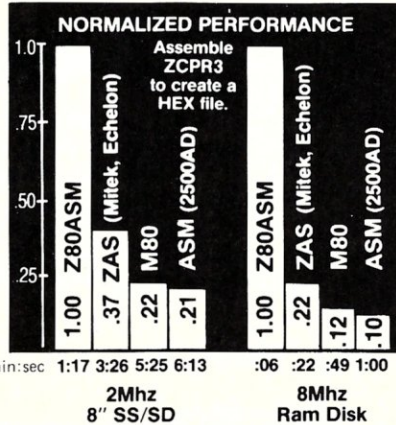
*Computer Language, Feb. 85*

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*Edward Joyce, User's Guide #15*

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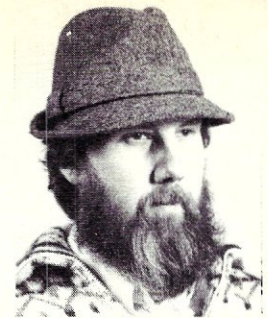


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# Turbo Pascal Corner

by David W. Carroll



This column features tips and techniques for using Turbo Pascal productively on MS/PC-DOS and CP/M microcomputer systems. It discusses typical problems and their solutions. Reader suggestions, comments, and questions are encouraged. Address them to: Turbo Pascal Corner, Box 699, Pine Grove CA 95665.

In this issue we will discuss some advanced machine level interface techniques with Turbo Pascal, primarily DOS calls, command line parameters, and wild card file names. This article will address MSDOS operations and the next issue will address the same processes in CP/M Turbo Pascal systems.

## DOS CALLS

Calls to MS-PC-DOS, in Turbo Pascal, are performed using either the INTR procedure or the MSDOS procedure. Both provide a software interrupt and pass a register record variable to the system, presetting the CPU registers and returning any parameters upon termination of the interrupt. MSDOS(regs) is actually a shorthand notation for the INTR(\$21,regs) procedure, and the two can be used interchangeably. The MSDOS call can only be used to access DOS functions, while the INTR call can access any software interrupt, including the BIOS routines.

The register record variable is set up like this:

```
type
  regtype = record
    (ax,bx,cx,dx,bp,si,di,ds,es,flags:
     integer);
  end;
var
  regs : regtype;
```

or a free union variant record can be used to allow accessing and setting the registers either as word or byte values. The variant part of the record is automatically selected by the field identifier used.

```
type
  regpack = record
    case integer of
      1: (ax,bx,cx,dx,bp,si,di,ds,es,
         flags: integer);
      2: (al,ah,bl,bh,cl,ch,d1,dh : byte)
    end;
var
  regs : regpack;
```

## Advanced Machine Level Interface Techniques

### COMMAND LINE

Up to 127 bytes of command line parameters, if any, are located at ABSOLUTE CSEG:\$80 when an MS-DOS Turbo Pascal program begins. They must be copied to a program variable as the first action of the program or all but 32 bytes will be lost.

```
type
  comstr = string[127];
var
  buffer : comstr;
  comline : comstr absolute cseg:$80;
begin
  buffer := comline; {This must be first}
  {statement in main program block.}
```

As with an user entered data, the command line parameters should be parsed and validated in your program.

### WILD CARDS

The use of wild cards for file names in MS-DOS Turbo Pascal programs is not discussed in the *Turbo Reference Manual* or in the *Turbo Tutor* tutorial from Borland, so it is an often requested topic. There are two main considerations when using wild card file names - first, to properly parse and translate the entered wild card filename to produce an acceptable search mask or File Control Block (FCB) for DOS; and second, to find all the filenames that match the requested search mask.

MS-DOS allows two wild card characters (? and \*) in filenames, but some internal DOS functions only recognize the ? wild card character. DOS provides a built-in parsing function (\$29) can be used to generate a correct search mask from a filename string with or without wild cards.

Version 2.0, and later, of DOS provide two sets of functions for accessing directory information, one using FCBs much like CP/M and the other using DOS file handles. To be compatible with earlier DOS 1.X versions, the FCB function calls will be

used here. Refer to Section 5 of the PC-DOS 2.1 Technical Manual for more information.

The basic technique is the same as is used in a directory list program. A DTA (disk transfer area) is set up for the disk operations using the set DTA DOS function call (\$1A). An unopened FCB is set up (containing the search mask) and passed to the get first entry DOS function (\$11). If found, the name is returned in the current DTA. Then subsequent calls (using the same FCB) are made to the get next directory entry DOS function (\$12) until no match is found. In this application, instead of listing the filenames to the screen, each is used as a parameter specifying the file for processing by the program.

However, the DTA area used by the directory calls getfirst and getnext MUST be preserved if other disk accesses are done between directory calls. This is accomplished by using two DTA variables and switching between them. Then any required disk operations may be done by the routines which process each file found without destroying the directory search data.

The following program uses all of the above concepts to provide a general form for wild card file processing. The process used here is a simple page format list to printer routine for listing program source files. To use this design for other file processing tasks, simply replace the LISTPROC function with your own (and change the call in procedure FIND), using a similar file open technique and returning an error code of zero if no problems were encountered, non-zero if an error occurred.

*This program and some 300 other Turbo Pascal and public domain programs are available 24 hours a day for free downloading on the "High Sierra RBBS" system at 209/296-3534.*

*David W. Carroll is a freelance writer and computer consultant living in the Sierra Nevada foothills near Sacramento, California. He is the author of "Telecommunications with the IBM PCjr" co-published by Microtext/Prentice Hall in March 1985 and "Programming with Turbo Pascal" co-published by Microtext and McGraw Hill.*

```

program listwild;

{This program accesses files using command line wild-cards.}
{It works with MS-DOS (or PC-DOS) versions 1 and 2. }

{Copyright 1985 by David W. Carroll}
{All commercial rights reserved.}

type
  regpack = record
    case integer of
      1: (ax,bx,cx,dx,bp,si,di,ds,es,flags: integer);
      2: (al,ah,bl,bh,cl,ch,dl,dh      : byte)
    end;

  fcbarray = array[0..36] of char;
  strtype = string [14];
  comstr = string[127];

const
  getdta = $1a;
  getlstdir = $11;
  getnextdir = $12;
  parsename = $29;

var
  buffer : comstr;
  comline : comstr absolute cseg:$80;
  inch : char;
  filestr,
  filename: strtype;
  dfcb,
  dta,
  dta2 : fcbarray;
  user_input : boolean;

function listproc(fname:strtype) : byte;

const
  lines_per_page = 66;
  chars_per_line = 79;
  bottom_margin = 8;
var
  infile : text;
  timel,
  datel : string[8];
  infname : string[20];
  max_lines : integer;
  goodfile : boolean;

procedure open_file;
const
  bell = 07;
begin
  infname := fname;
  assign(infile,infname);
  {$I-} reset(infile) {$I+};
  goodfile := (IOresult = 0);

  if not goodfile then
  begin
    write (chr(bell));
    writeln ('FILE ',infname, ' NOT FOUND');
    delay(2000)
  end;
end;

procedure list;
var
  p,
  line : integer;
  txtline,
  printline : string[255];

procedure print_heading(page:integer);
const
  space = ' ';
begin
  if page <> 1 then writeln(lst,chr(12));
  writeln(lst);
  writeln(lst);
end;

begin {list}
  p := 0;
  while not eof(infile) do
  begin
    p := p + 1;
    print_heading(p);
    line := 4;
    while (not eof(infile)) and (line < max_lines) do
    begin
      readln(infile,txtline);
      writeln(lst,txtline);
      line := line + 1;
    end;
  end;
end;

```

```

  writeln(lst,chr(12)); {form feed}
end; {list}

begin {listproc}
  max_lines := lines_per_page - bottom_margin;
  open file;
  if goodfile then
  begin
    list;
    close(infile);
    listproc := 0;
    writeln;
    writeln(' - listing done -');
  end
  else
  listproc := 1;
end; {listproc}

procedure setDTA(num:byte); {set Disk Transfer Address}
var
  regs: regpack;

begin
  with regs do begin
    ah := getdta;
    case num of
      1: begin
          ds := seg(dta);
          dx := ofs(dta);
        end;
      2: begin
          ds := seg(dta2);
          dx := ofs(dta2);
        end;
    end;
    MSDOS(regs)
  end
end; {setDTA}

procedure calldir(calltype : byte; var errflag : byte);
var
  regs: regpack;

begin
  with regs do begin
    ah := calltype;
    cx := 0;
    ds := seg(dfcb);
    dx := ofs(dfcb);
    MSDOS(regs);
    errflag:= al
  end
end; {calldir}

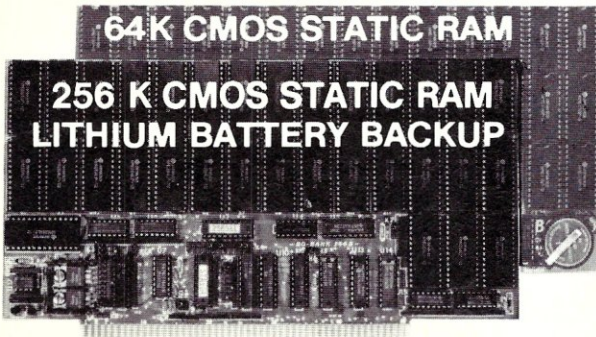
procedure parse(var errflag:byte);
var
  regs : regpack;
begin
  with regs do begin
    ah := parsename;
    ds := seg(buffer[1]);
    si := ofs(buffer[1]);
    es := seg(dfcb);
    di := ofs(dfcb);
    al := $0F;
    MSDOS(regs);
    errflag := al;
  end;
end; {parse}

procedure find;
const
  space = ' ';
  period = '.';
var
  i,
  err: byte;

begin
  for i := 0 to 36 do dfcb[i] := chr(0);
  if not user_input then
    writeln('Search mask: ',buffer:15);
  writeln;
  parse(err);
  setDTA(1); {set lst DTA for get func.}
  calldir(getlstdir, err);{get first entry matching mask }
  while err = 0 do
  begin
    filename:= '';
    for i:= 1 to 11 do
    begin
      if dta[i] <> space then
        filename := filename + dta[i];
      if i = 8 then filename := filename + period;
    end;
  end;

```

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```
writeln(filename);
setDTA(2);           {set 2nd DTA for file processing}
err := listproc(filename);{process file}
if err = 0 then
begin
  setDTA(1);
  callDir(getnextdir, err);           { get next entry }
end;
end;
writeln;
end; {find}

begin {listwild}
buffer := conline;
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writeln('Wild card program lister');
writeln('This program formats and lists all specified');
writeln('files on default drive to system printer.');
```

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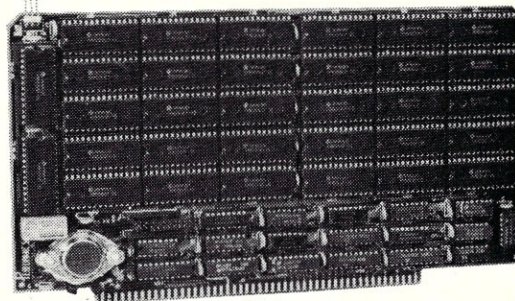
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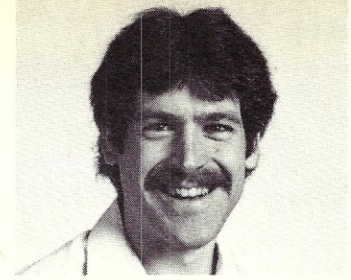


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# The C Forum

by Don Libes



## Context - independent macros

Macros provide a means of textual substitutions in the source code at compile time. Most people get along fine with an intuitive idea of how they work, but occasionally stumble over anomalies.

These anomalies come from the C preprocessor's (cpp) limited understanding (less than ours) of C. For example, while cpp knows not to perform substitutions inside of quoted strings, it doesn't prevent changes in operator bindings, as the following example shows:

```
/* weight of a battery components */
#define ACID_WEIGHT 5
#define COVER_WEIGHT 1
#define BATTERY_WEIGHT ACID_WEIGHT + COVER_WEIGHT /* WRONG! */

/* compute total weight of 10 batteries */
total_weight = 10 * BATTERY_WEIGHT;
```

In this example, the assignment turns into a computation of  $10 * 5 + 1$ . This is evaluated as  $(10 * 5) + 1$ , not  $10 * (5 + 1)$  as the programmer wanted. The problem is that an operator (+) inside the macro was of lower precedence than one (\*) outside the macro. Rather than learning all the rules of operator precedence, it is easier to simply remember to always enclose your entire macro with parentheses.

It is rare that this ability of cpp to change bindings is what is desired, although it is used occasionally (and typically produces obfuscated code). See Vol 1, #4 of M/SJ for some classic examples!

Unfortunately, cpp can complicate things even further because it has the same effect on statements that it has on expressions. This is a much more troublesome problem, because the indentation that we use is completely ignored by the C compiler. While we understand the control of the program at a glance because of the indenting of the code, it can be misleading when the program has a completely different structure in reality.

For example, suppose we define the macro #assert. #assert is typically used to state a predicate that is always true. It generates actual code that checks that its argument is true. What is the point of that?

Think of it as being able to execute your comments; to check that the code really does what the comments say it does. If the assertion is ever false, a serious error has occurred - your program no longer matches your specification. For example, if you are writing a program and at a certain statement, you are confident that a pointer will always be valid (non-zero), you can place the statement:

```
assert(pointer != NULL, "pointer is null!");
```

This will generate code to verify the expression when the program is run. If the expression evaluates to 0 (false), a message will print stating that "assertion failed: pointer is

null!". It is possible to set the macro up so that when you are ready to create a final program, the assertions are effectively ignored. (I will show this later.) Another possible use for this would be array bounds checking. During program development you might want this, but when you are convinced your program works, you can compile it without this feature.

A simple macro to do the assertion is:

```
#define assert(expr,msg) \
    if (!(expr)) printf("assertion failed: %s\n",msg)
```

Look at this macro very carefully. You should notice two things. The first is that we have put parentheses around expr. You should be able to come up with an example where #assert would not perform correctly if we left the parentheses out. Also, take note that there is no terminating semicolon at the end of the if statement. This allows us to use the macro as if it were a function call, that is, to terminate it with a semicolon at the point of usage.

Now suppose that we have the following piece of code:

```
if (a > b) assert(a+1 > b, "eh?");
else c = 5;
```

What happens after the macro is evaluated, is:

```
if (a > b)
    if (a+1 > b) printf("assertion failed: %s\n","eh?");
    else c = 5;
```

The else has bound with the wrong if! Not only will this function behave incorrectly, but the C compiler will not complain about it. It will compile just fine. These kinds of errors can be very hard to find, because the block and control bindings of the program don't match the indentation level. Humans believe very strongly in white space, while the C compiler ignores it entirely.

The problem has occurred because our macro looks like a function call but doesn't behave like one. Because the macro is only a textual substitution, it is free to rebind itself with any part of the program that the control structure syntactically warrants. If #assert had been a function, this would never have happened (and sometimes this is your only recourse).

In this case, an if statement bound with an else to become an if-else statement. One way to stop this rebinding is to make the if statement into its complete cousin. For example:

```
#define assert(expr,msg) \
    if (!(expr)) printf("assertion failed: %s\n",msg); \
    else
```

Notice, the else just hanging off the end? This prevents another else from binding with the if. Remember that we are assuming that the user will terminate the macro use with a semicolon so that the else will be followed immediately by a semicolon (or more precisely, with a null statement).

Unfortunately, if you forget the semicolon, you will have more trouble since the following statement will be sucked up as the statement to be executed in the else clause (again without errors or warnings of any kind)!

Well, then, why don't we just put the whole thing in a

pair of braces? This seems like a good idea, because it makes the macro into a complete C statement. You can also declare local variables and have other control structures such as loops in the macro.

Unfortunately, there is still a problem with this. (Think about it before reading on.) The problem appears in the following piece of code:

```
if (expr) assert(expr2, "...");
else ....
```

which turns into:

```
if (expr) {
    if (expr) printf (....);
};
else .... /* syntax error! */
```

What happened is that the assert is replaced by a block, but the block is followed by a semicolon. This semicolon came from the user adding it to the end of the macro. Unfortunately, it now terminates the if prematurely.

Is there anything that will do the job? The answer is yes, but its not exactly pretty. (You won't hit yourself on the head and say "Why didn't I think of that"! ) The following macro does the job nicely:

```
#define assert(e,m) do { \
    if (!(e)) printf(m);\
} while (0)
```

This is very similar to the previous case where we enclosed the macro in a block. The difference is that this one requires a semicolon to make it into a syntactically correct and complete statement. The block is sealed from misinterpretation through rebindings, and it will be executed once and only once. Although it may seem like an unusual way to do it, rest assured that every (reasonable) compiler will optimize the statement so that the extra test is not performed.

I particularly like this macro because if the user leaves off the semicolon, by mistake, the C compiler will complain.

On the other hand, the compiler won't complain with a macro like:

```
#define assert(e,m) if (1) { \
    if (!(e)) printf(...); \
}
```

For people who absolutely have to have the shortest macro, (no matter much readability they sacrifice,) here it is:

```
#define assert(e,m) if (e) ; else printf(...)
```

It is particularly ugly, because 1) the test is reversed which can be a little confusing, and 2) there is a null "then" clause due to the semicolon immediately following the expression, which is easy to miss.

I'm not encouraging you to use these last two macros (or impress you with my knowledge). Rather I'm pointing out that you may see things like this when reading C source, and you should be able to understand it when you see it.

Note that in each macro above you can replace the printf by a block of statements.

It is sometimes useful to have an if statement embedded in an expression (as opposed to a statement). This can be done with the following macro:

```
#define EXPR_ASSERT(expr,msg) (expr || printf(...))
```

although this is not that useful, since you can't have local variables and looping control structures. Its occasionally called for, though.

What really makes #assert useful is that once you have debugged your program, you can turn off the assertion checking in the final version without doing any editing of your source.

Simply store #assert and any other debugging macros in a file called debug.h as follows:

```
/* debug.h */
#ifdef DEBUG
#define assert (expr,msg) if (1) { \
    if (!(expr)) printf(msg);\
}
#elseif
#define assert(expr,msg) ;
#endif DEBUG
```

Now if you define DEBUG when compiling, the assertions will generate real code, otherwise they are turned into null statements. (Convince yourself that the null statement doesn't mess anything else up!)

*I encourage readers to write to me about topics or problems that you want to know about. I want this column to be reader driven. Write to me care of M/SJ, Box 1192, Mountainside, NJ 07092.*

*Don Libes is a computer scientist working in the Washington, DC area. He works on artificial intelligence in robot control systems. He is also the son of Lennie and Sol Libes.*

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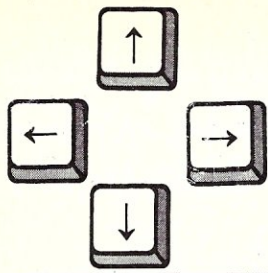
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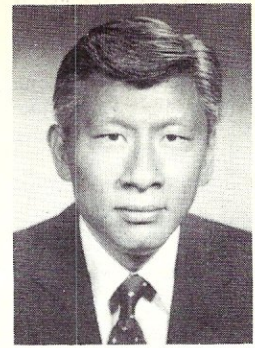
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# PC/Blue Report

by Hank Kee



In the past Sol Libes and I, at different times, discussed, in this publication, and in the old Microsystems, assembling an IBM PC clone. The task has come along way. Availability of components has increased and costs have dropped. Almost anyone who can use a screwdriver can put together a system. Not only have hardware costs dropped dramatically but so have software costs dropped, if one makes full use of public domain software, such as exists in the PC/Blue Library.

The main difference between commercial software and software in the public domain is mainly the depth of functionality. For example, Lotus 1-2-3 is currently the most popular commercial spreadsheet program. I would venture to guess that more than half the 1-2-3 users don't take advantage of its complex functions. This is also true for other programs like word processing and database management systems. There are however exceptions to the rule. I feel that public domain communication programs are far more creative and functional than their commercial counterpart systems.

We can divide public domain software into three basic categories - spreadsheets, database management systems, and word processors. Another category can be best described as esoteric. We have in the public domain library systems like XLISP, graphic display and bulletin board systems which really don't command a very large market. The third category consists of utilities. These programs tend to be small in program size. They include screen blanking, color graphics selector and many others. There is a multitude of them on the various bulletin boards across the country.

For this issue I will comment on building your own software library from what is available in the PC/Blue public domain library. Our base library should contain a word processor, spreadsheet, database manager, and communication programs.

For a word processor, there is *PC-Write* (Vol. 130) and *WPK* (Vol. 95). *PC-Write* reminds me of

## Build Your Own Program Library Using Public Domain Software

*Volkswriter* and *Wordstar*. It is a very functional program. It is memory mapped for high speed like *Volkswriter*. Everything is constructed in memory. Alas, it is similar to *Wordstar* in that the functional controls are accessed via control characters. Once the function keys are mastered, however, it is an excellent word processor. For the young ones in the home, *WPK* (*Word Processing for Kids*) is very easy to use and learn. Its very intelligent use of graphics makes it a joy to use.

*PC-Calc* (Vol. 115) and *FreeCalc* (Vol. 50) function in a manner very similar to the classic *VisiCalc*. Simple and functional and yet not encumbered by the extended features like regression routines, present values, or macro generation. For the home, we don't need something as complex as Lotus 1-2-3. On the contrary, *PC-Calc* is as simple to use as 1, 2, and 3.

*PC-File* (Vol. 46) started off in the public domain or user supported sector. It has since graduated from the ranks and gone commercial. In its place, there are a number of candidates one can choose from. *PC-DBMS* (Vol. 131) and *3BY5* are pretty nifty programs. A clear cut leader from a bunch of good database managers will only come with their continued distribution and acceptance in the public domain library network. Database management systems will vary in functionality. They may perform the same tasks but the presentation can make two similar functions packages look like night and day. Pick the one that best meets your requirements.

*QModem* (Vol. 141) has fast

*Editor's Note: Hank Kee is the librarian for the PC/Blue public domain software library. He is the person who collects, assembles, and checks all the software issued by PC/Blue and then compiles and edits them into the released volumes.*

become a very popular communications package. The author is constantly updating it. Sometimes a little too often. But we should never complain about a good thing. *QModem* is an excellent program that has incorporated graphics, windows, directories, and split screen operation. There are now many ancillary programs available for *QModem* such as background dialers. A challenger to *QModem* is *Termulator* (Vol. 143). *Termulator* does not have the cosmetics of *QModem*, but it has the Kermit and *XModem* protocols. It can also emulate a large number of terminals. Least of all, let's not forget *PC-Talk III* (Vol. 143). I think it has been surpassed by *QModem*, but for a very long time it set the benchmark standards for a public domain or user supported communications program.

A favorite of mine in the PC-Blue library is *PC Picture Graphics* (Vol. 44). IBM has since included this in their class C software product catalog. The updated version is very modestly priced. But the original version works almost as well at a very modest copying cost.

I will comment on esoteric systems and utilities to be added to a base library consisting of public domain or user supported software in following issues.

During the past two months, a number of new volumes have been added to the PC/Blue public-domain software library. They are the following.

Vols. 138 & 139

Remote Bulletin Board System v12.5A

Capital PC Users Group - vol 1 & 2

Vol. 140

PIBTERM version 2.0 terminal emulator and host communications facility

JUDY version 1.01 background desktop utility

Vol. 141

QModem version 1.07 modem communications  
PC-CALC - electronic spreadsheet  
DIALER - background dialer  
RM1200B - software power on reset

Vol. 142 Miscellaneous Utilities -  
archive utility/overwrite boot sector  
examine all RAM (1MB)/file encryption  
list utilities/file managers  
Bueg's library utilities  
squeeze/unsqueeze  
disk cataloging/display environment  
sort large files/TREE directory

Vol. 143

PC/Talk III v2.6 - Modem Communications  
Termulator v1.0 -  
Kermit/XModem Compatible  
Minitel v3.2 - Modem Communications  
Butler v1.01 - Automatic Modem Communications

Vol. 144 Miscellaneous Utilities -  
area code utility/create .BAT files  
Bly's utilities/simple sci calculator  
auto CAPS LOCK/file encryption  
DES module/memory map display  
disk and file utilities

Vol. 145 Hints, Tips, & Notes -

1-2-3 <--> dBase III  
dBase III fixes  
Macro Assembler tutorial  
Copy B <--> C  
extending DoubleDOS 1.0  
640KB on XT systemboard  
Multimate fixes  
Turbo Pascal tutorial  
Wordstar patches

Vol. 146 XLISP version 1.5

Vol. 147 Fun & Games -

alfred / bumblebee / eliza / face /  
flies / funphone / furelise / happy /  
hopper / insults / joycal /  
kaleidoscope / keyclick / kirk / luv /  
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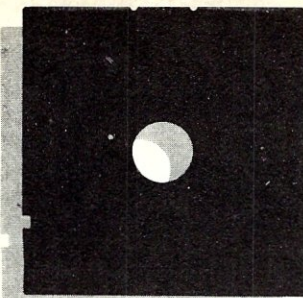
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# In the SIG/M Public Domain



by Stephen M. Leon

## THE PROTOCOL WAR

I rented a video tape a few weeks ago...a film called 'Protocol' with Goldie Hawn. It was so bad we just never bothered to see more than a few minutes of it. What we did, however, was turn on the computer, phone Compuserve and tune in to the "Protocol War".

It was the hottest thing around, in recent weeks, on the CP/M SIG (GO PCS-47). Always an interesting place, in recent times CP/M SIG has been bubbling with sarcastic wit, attack, retreat and sundry forms of mayhem. The subject...revising Ward Christensen's XMODEM protocol to handle 1024 byte blocks.

The present XMODEM error checking is based upon transmission of a 128 byte data block. After the receiver gets the block and checks it, it advises the sender all is well - continue, or - send the block again. With 2400 baud modems (and even 1200 baud) the experts say transmission speed can be significantly improved by increasing the block size to 1024 bytes and changing the method of retransmitting errors.

Ward had put a message on the SIG that he was doing an article for BYTE on the protocol and proposed adoption of the YMODEM protocol to bring XMODEM to 1K blocks. It seemed a logical way of handling the matter. YMODEM has been extensively tested and in wide use in the 16-bit world. Paul Homchick then went ahead and did the code. Ron Fowler put the code into MEX and we released SIG/M Volume 241 with the new XMODEM (XMODM110) and the new MEX (MEX114).

One would expect the problem has been solved. However, this was just the beginning. It seems there is a movement, led by Irv Hoff, to have two standards for 1024 byte blocks. Out in California they never discovered that if you take your shoes off one can count to 16. As a result, the *revision an hour* crew, led by Irv, has been putting out *new* program versions with non-sanctioned protocols. Therefore, watch out for version numbers greater

than XMODM110. In the meantime, Irv has promised to send SIG/M his new IMP - (Irv's Modem Program). More on the protocol wars next issue.

## FOREIGN SIG/M CONTRIBUTORS

CP/M is very popular in Australia and every month or so SIG/M gets a contribution from Bill Bolton of Software Tools of Australia (PO Box 357, Kenmore, QLD, 4069) with their latest public domain software releases. Australia must be modem heaven. The vast distances must make for a telephone way of life and modem and BBS systems are high on the frequency list of releases. Their library is also heavy on programs for limited distribution computers.

Derek Fordred of the United Kingdom CP/M Users Group (72 Mill Road, Hawley, Dartford, Kent, England DA2 7RZ) is another frequent contributor. Unfortunately, the UK library features quite a few non-standard BASIC and PASCAL programs, which means that only a few of their releases make it into the SIG/M library for distribution in the U.S.

Readers interested in Australian and U.K. public domain software libraies can contact Bill and Derek directly.

## NEW SIG/M RELEASES

Our new releases include an updated KERMIT for CP/M-80. KERMIT is widely distributed as *the* mainframe-to-micro modem program. Many IBM PC commercial packages include a version of it for communications. It has a number of limitations, but as its distribution keeps expanding it is becoming a *must have* package.

The Disk-Jockey Controller is in reasonably wide use and Robert Davies of Wellington, New Zealand has written a CP/M+ BIOS for it (SIG/M Vol 236). Also in that volume is a fine article by Bob on CP/M+ together with an updated LISP in PASCAL/Z.

Interest in transmission of computer data by radio is growing. The SIG/M library contains a number of programs of interest to packet radio

*Steve Leon is the SIG/M Disk Editor. In other words, he is the person who assembles, compiles and edits all the of the SIG/M public domain software disks. Thus, he speaks with the greatest authority as to what is going on in the SIG/M public domain software area.*

buffs. The latest releases include two volumes in this area. Ed Elizondo has implemented all three levels of the CCITT X.25 Packet Standard for the Big Board (Vol 238). It contains full documentation and should be readily adaptable to other machines. Full documentation is also available for BASICODE radio transmission (Vol 235). Unfortunately, the documentation is mostly in Dutch. We are working on a translation. In the meantime, true radio fans should find it of interest. Additional packet radio material is also available on SIG/M Volume 143.

We really can't do justice to the ten volumes covered by SIG/M 232 through 241 in the space remaining, so we will just list them and perhaps cover them in more detail in the next issue. One last word, however, with respect to the fine contribution we received from Rick Surwild. He has written an excellent full screen Z80 debugger with full (90 pages) documentation (Vol 239). This is a major work, although as you can see from the list, there are a number of major innovations on these ten volumes.

SIG/M Volumes are available on 8" SSSD Disks for \$6.00 each (\$9.00 foreign) directly from SIG/M, Box 97, Iselin, NJ 08030. Printed catalogs are \$3.00 each (\$4.00 foreign). Disks in a variety of formats may be obtained through the worldwide SIG/M distribution network (which was published in the last issue of M/SJ). The distributor list is included with the printed catalog. A disk version of the catalog (Volume 00) is available for \$6.00. Many bulletin boards have the software for downloading and most new releases are available on the Compuserve CP/M SIG.

Vol 232 - Kermit 3.9 for CP-M-80, Z80 translator  
released July 19, 1985

BECBIOS .MQC Modified Ferguson Big Board 1 BIOS  
KERMIT .VER KERMIT communications version list  
KRMSRC .LBR KERMIT version 3.9 for CP/M-80  
M7BBS+ .ACM Modem 7 for Ferguson Big Board 1  
XLATE216.LBR Updated XLATE 8080>Z80 source translator

Vol 233 - Miscellaneous CP-M-80 Utilities  
released July 19, 1985

BOY-MOR .LBR Z80 Boyer-More string search function  
CLEANUPC.LBR Cleans up C source, makes cross listing  
DISKNAME.LBR Gives 45 char volume name on CP/M disk  
MODEM7B .LBR MODEM7A modified for LST device output  
PMATCH .LBR Checks print command pairing for Word\*  
SDDIRENT.LBR Updated SD77, more information displayed  
UDM1200 .DQC Using Modem Tech UDM1200 at 1200/75 bps  
UDMAUTOD.BAS BASIC auto dialer for Modem Tech UDM1200  
VDUPRNT .LBR Screen dump Microbee to Tandy DMP 200  
XPRINT .CQ Extended print utility in C

Vol 234 - CP/M+ & Other Utilities, Curve Fitting  
released July 19, 1985

AUTO .LBR Auto execute program on cold boot  
CPM3UTIL.LBR Disk & other utilities for CP/M+  
CUBE .LBR Solves 5 x 5 cube  
CURVFIT .LBR Curve fitting in MBASIC  
DISKSTAT.LBR Display disk info and file allocation  
DUMP .LBR Improved file dump utility  
SBCOPY .LBR Fast copy utility for SuperBrain  
SPZ .LBR Full screen disk utility SuperBrain version  
SYM .LBR Make SID symbol table from MACRO-80 listing

Vol 235 - BASICODE Radio Communications (in Dutch)  
Netherlands Enhancements to FIG FORTH  
released July 19, 1985

ABSTRACT.235 Abstract of disk contents (in Dutch)  
BASICODE.DOC Documentation on BASICODE (in Dutch)  
BASICODE.ENG Brief intro to BASICODE (in English)  
BC2 .BQS "Standard" BASICODE-2 for MBASIC  
BC2 .OSB "Osborne" BASICODE-1 for Osborne 1  
BC2 .OSI "Ohio Scientific" BASICODE-2  
BCREAD .AQM Read BASICODE-2 from parallel port  
BCTEST .AQM Test program - BASICODE-2 port transfer  
BCWRIT .AQM Write out BASICODE-2 program, std  
BCWRITE .AQM Write out BASICODE pgm, (BASICODE-1?)  
BOKA&EI .BQS BASICODE-2 Tic Tac Toe, in Dutch  
CONVERT .BQS CBASIC source - BASICODE-2/MBASIC xlate  
CONVERT .COM Converts BASICODE-2> Microsoft BASIC  
DELERS .BQS BASICODE game of some sort, in Dutch  
DIGIKLOK.BQS BASICODE-2 on screen digital clock  
FEESTEN .BQS BASICODE-2 show public holidays-any year  
FORTH-NL.LBR FIG FORTH 1.1 with enhancements for CP/M  
FUNCTION.DAT Used with CONVERT.COM  
KALFEEST.BQS BASICODE-2 calendar-any month & year  
KEYWORDS.DAT Used with CONVERT.COM  
MASSA .BQS BASICODE-2 demo program, in Dutch  
SORT .BQS BASICODE-2 sort program, in Dutch  
STELSELS.BAS BASICODE-2 solves 3 order quadratics?  
TANKIE .BQS BASICODE-2 game, simple ASCII graphics  
TESTBC2 .BQS BASICODE-2 test/exerciser program  
TIMER555.BQS BASICODE-2 designs 555 timer circuits  
UITLEG1 .BQS Introduction to BASICODE? (in Dutch)  
UITLEG2 .BQS See UITLEG1.BAS

Vol 236 - CP/M+ BIOS for Disk-Jockey Controller  
Updated Lisp in Pascal/Z  
released July 19, 1985

CPM3BIOS.DQC CP/M+ BIOS for Morrow Disk Jockey-Doc  
SCB .ASM BIOS routines  
MOVE .MAC " "  
CHARIO .MQC " "  
DISKDEFN.ASM " "  
DISKHNDL.MQC " "

SEMIHNDL.MAC " "  
BOOT .MAC " "  
GENCPM .DAT Sample data for GENCPM  
DDLDR .ASM Loader BIOS routines  
LDRBIOS .MAC " "  
LOADSYS .MAC BIOS routine loader  
REBOOT .MAC To cold start  
SEESCB .RAT Print the SCB  
ACCSCB .MAC " "  
SEESCB .COM " "  
BARB2 .MAC Memory check  
IF .COM Conditional execution  
IF .MAC " "  
OVLNMR .MAC Overlay manager  
PRINT .COM Spooling printer  
PRINT .MQC " "  
CPMPLUS .TQM Article on CP/M+  
LISP .COM Lisp in Pascal/Z  
LISP .DOC from Vol 27 Pascal/Z  
LISP .PAS Users Group  
INITLISP. /  
INITLISP.STB /

Vol 237 - Pilot in Pascal/Z  
Solving Deductive Reasoning Puzzles  
released July 19, 1985

PILOT-P .LBR Pilot in Pascal/Z  
PUZZLE .LBR Helps solve deductive reasoning puzzles

Vol 238 - CCITT X.25 Packet Standard (all 3 levels)  
released August 16, 1985

BUFFERS .AQM Full implementation of CCITT X.25  
FILES .AQM packet standard (all 3 levels) under  
LEVEL1 .AQM CP/M-80. Implements a dumb terminal  
LEVEL2 .AQM with bi-directional file transfer  
LEVEL3 .AQM capability. Configured for Digital  
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X25 .CQM polynomial check). Extensive diag-  
X25 .MSG nostic facilities built in. Full  
X25SYS .DQC User manual.  
X25UM .DQC /  
XUTIL .AQM /

Vol 239 - Z8E Z80 Debug Monitor  
released August 16, 1985

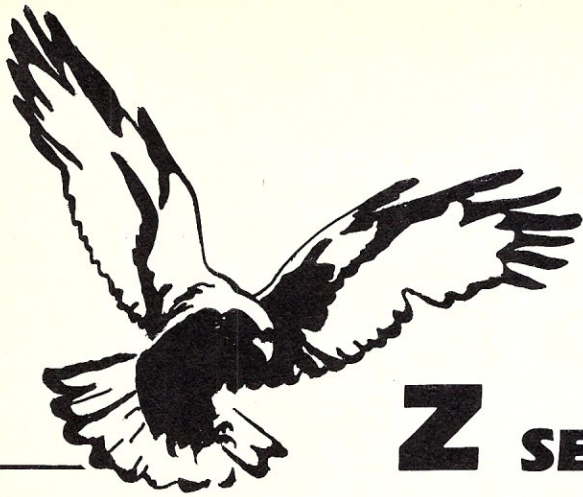
Z8E .CQM Symbolic Z80 debugger. Full screen  
Z8E .DQC animated display of program under  
Z8E .MQC test, built in assembler, 16 break-  
Z8E .SYM points, 20 + commands. Full doc file

Vol 240 - Extracts from UK CPMUG - Volumes 21 & 23  
BASIC (Z80) Bulletin Board  
released August 16, 1985

ASM65 .DOC converts ASM.COM to 6502  
ASM65 .HEX cross assembler  
BACKUP .COM Winchester backup program (Z80)  
BACKUP .DOC /  
BACKUP .MAC /  
ECCE .DOC Edinburgh Compatible Context Editor  
ECCE48K .COM line oriented editor with macro  
ECCE56K .COM capability and conditional commands  
ECCE60K .COM /  
ACK .DOC /  
ZBBS .LBR BASIC BBS (Z80) system

Vol 241 - Updated XMODEM, MEX with Revised XMODEM  
Protocol; Turbo Pascal Bulletin Board  
released August 16, 1985

MEX114 .LBR Update to XMODEM & MEX using new  
XM0DM110.LBR 1024 protocol for faster transfer  
TURBOBBS.LBR Turbo Pascal BBS system



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# The Data Base Forum

by Nelson T. Dinerstein

*This column will be a regular feature in M/SJ. It will discuss problems associated with the application of database managers such as dBase-II/III, Framework, and Rbase 5000. Suggestions, comments and questions are welcomed.*

## THE NATURE OF THE PROBLEM

When dBase-II programs slow down, the cause is almost always the indices. As the file size grows, programs that used to run quickly may now run very slowly. It is not the size of the data file that makes the difference, but the size and number of index files. The techniques described herein will help to overcome this problem and can be incorporated in written as well as to future programs. These speed techniques often reduce execution time on indexed files containing as few as 100 records. The larger the files, the greater the resulting reduction in run time.

Since it is the updating of the index files that makes dBASE II programs slow, we need to avoid the use of indices as much as possible. But, since indices are valuable, we must continue to use them. The trick is to use them in the most efficient manner.

**RULE 1 : If an operation is slow, use it as seldom as possible.**

There are two major operations that use indices and change files, i.e. adding a new record to a file and modifying an existing record. Let's examine each of these operations.

## ADDING A RECORD TO A FILE

Since the number of indices plays an important role in the amount of time needed to APPEND a record to a file, keep the number of indices as small as possible.

**RULE 2: Do not create an index on the chance that you might eventually need it. Create an index only when you are sure you will need it. This will reduce the total number of indices on each file.**

**RULE 3: If an index will be used infrequently, add records to the file without using the index. Then, when the index is required, create the index just before it is used.**

## dBase-II Speed Techniques -Part I

The time required to add new records to a file can also be controlled through the use of a combination of interactive and batch techniques. *Interactive* is used here to mean that all of the indices are in use when the record is added to the file. Thus, when a record is added, all of the index files are updated immediately. *Batch* is used here to mean that no index is in use when the record is added to the file. This means that records can be added to the data file very rapidly. When all of the desired records have been added, the files can be re-indexed. Consider examples 1 and 2.

### EXAMPLE 1: INTERACTIVE ADDITION OF RECORDS

```
* IN THIS EXAMPLE, INDEXES ARE UPDATED IMMEDIATELY
USE X INDEX A,B,C
DO WHILE T
  STORE " " TO ANSWER
  ERASE
  @ 5,1 SAY "ENTER ANOTHER RECORD (Y/N)" GET ANSWER
  READ
  IF ANSWER <> "Y"
    RETURN
  ENDF
  * Enter record here, in normal manner
ENDDO
```

### EXAMPLE 2: BATCH ADDITION OF RECORDS

```
* IN THIS EXAMPLE, INDEXES ARE UPDATED AFTER
* ADDITIONS HAVE BEEN COMPLETED
USE X INDEX
DO WHILE T
  STORE " " TO ANSWER
  ERASE
  @ 5,1 SAY "ENTER ANOTHER RECORD (Y/N)" GET ANSWER
  READ
  IF ANSWER <> "Y"
    RETURN
  ENDF
  * Enter record here, in normal manner
ENDDO
INDEX ON <field name> TO A
INDEX ON <field name> TO B
INDEX ON <field name> TO C
```

In some cases, you may wish to verify the record you are about to enter is not already in the file. To do this, first use the appropriate index and the FIND

statement to verify that the record is not already in the file, then remove (deactivate) the index and add the record.

### EXAMPLE 3: BATCH ADDITION OF RECORDS

```
* IN THIS EXAMPLE, INDEXES ARE UPDATED AFTER
* ADDITIONS HAVE BEEN COMPLETED, BUT CHECK IS MADE
* TO VERIFY THAT RECORD TO BE ENTERED IS NOT
* ALREADY IN FILE.
USE X
DO WHILE T
  STORE " " TO ANSWER
  ERASE
  @ 5,1 SAY "ENTER ANOTHER RECORD (Y/N)" GET ANSWER
  READ
  IF ANSWER <> "Y"
    RETURN
  ENDF
  STORE " " TO MEMKEY
  @ 7,1 SAY "ENTER THE RECORD KEY" GET MEMKEY
  READ
  SET INDEX TO A
  FIND &MEMKEY
  IF # <> 0
    @ 9,1 SAY "RECORD ALREADY EXISTS WITH KEY="+MEMKEY
    @ 11,1 SAY "TYPE ANY KEY TO CONTINUE"
    WAIT
    LOOP
  ENDF
  SET INDEX TO
  * Enter remainder of record here,
  * in normal manner.
ENDDO
INDEX ON <field name> TO A
INDEX ON <field name> TO B
INDEX ON <field name> TO C
```

In Example 3, SET INDEX TO A activates the index A causing it to become the primary index. The FIND which follows will then work correctly, assuming that MEMKEY contains an appropriate value for the index A. After the FIND statement has been executed, # will have the value, 0, if there is no record in file X with the value contained in MEMKEY. Otherwise, the value of # will be greater than 0. To add a new record to the file, first remove (deactivate) the index with the SET INDEX TO statement and then add the new record.

I recommend that you have both types of functions (interactive and batch) in any system that you build. This will allow users to decide for themselves which to use. If, for example, a data file and its associated index files have grown so large that it takes 2 minutes to enter a single record, and 10 minutes to reindex all of the files, the interactive function should be used for entering five or fewer records and the batch function for entering five or more records. In this case, five records is the break-even point. As the file sizes grow or shrink, the break-even point will probably change.

**RULE 4:** Allow the users to choose interactive or batch entry of new records based upon the number of records to be entered.

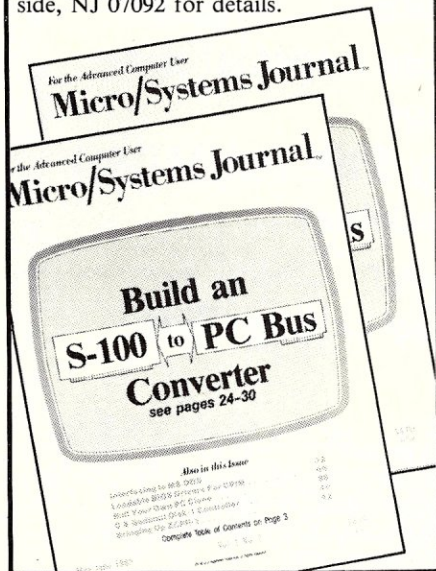
In the next issue of MISJ I will conclude my discussion of dBase speed-up techniques. In the meantime, if you have questions or topics that you would like to see discussed in this column drop me a line.

Nelson Dinerstein is an Associate Professor of Computer Science at Utah State University and an active consultant in database applications on micros. He has a Ph.D. in mathematics from the University of Utah. And, he is the author of 8 books on dBase-II/III, Framework, and Rbase 5000 applications.

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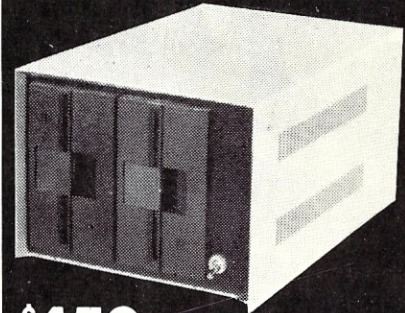
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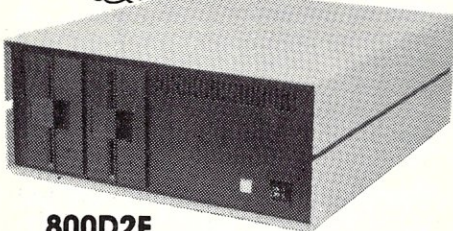
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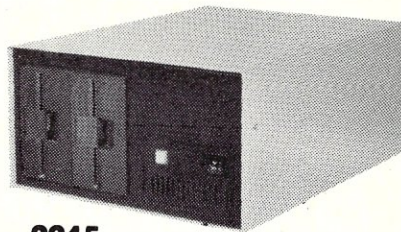
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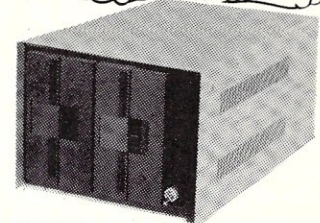
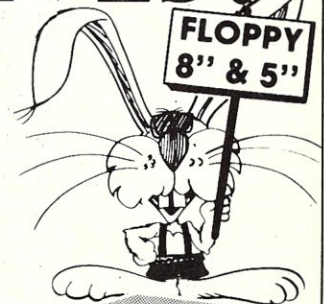
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## Your 8086/8088

# Computer

by Stephen Davis

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NEC recently announced a new family of processors- the V-Series. It is probable that all members of this family will eventually interest the computing world, especially the 32-bit supermicro V60. But as yet, only two members of the family currently exist in silicon, the V20 and V30. They should be of keen interest to owners of 8086- and 8088-based personal computers.

The V20 and V30 carry the more formal part numbers uPD70108 and uPD70116, respectively (apparently, all NEC microprocessors carry the designation, uPD). These chips are pin-compatible replacements for the Intel 8088 and 8086. Far from being mere second sources of the same processor, these CMOS chips offer substantial improvements, both in terms of speed and instruction set. In addition, these processors can run 8080 code if desired! In this two part series, we will examine these improvements, citing benchmarks when appropriate. We will also look into how these improvements can be incorporated into existing 8086 or 8088 systems, including, but not limited to, the IBM PC and compatibles.

We will examine closely the 8-bit bussed V20 and compare it to the 8088. Likewise this comparison can be extended to the 16 bit bussed V30 and 8086. Differences between the two pairs of chips, when they exist, will be pointed out. In this discussion keep in mind that both the 8086 and 8088 processors are available from several second sources besides Intel; however, for our purposes differences between the various 8086/88 versions are minimal.

### THE V20 vs THE 8088

The V20 has the same exact pin out

as the Intel 8088. NEC claims that there are no external electrical differences between the two chips. However, the chips differ internally in some significant ways.

The 8088 is known as an 8/16-bit processor, having a 16-bit word size, but an 8-bit external bus. The 8088 was designed to allow for interfacing to 8-bit peripherals originally designed for the 8080 and Z80 microprocessors. (The 8086 is 16-bit both internally and externally.) The 8088 has 20 bits of address allowing for direct addressing of 1 megabyte of memory. Internally the 8088 is a microcoded machine, having a microcode word size of 21 bits. In a microcoded processor machine instructions are decoded and carried out by an internal program, known collectively as the microcode. It generally requires multiple microcode instructions to perform even the simplest machine instruction. Since each microcode instruction takes one clock cycle to perform, individual instructions may take many clock cycles to execute. As an extreme example, the MULTIPLY instruction takes more than 100 clock cycles to perform in the Intel chips.

To route data internally to the chip the 8088 has one 16-bit wide bus. Often extra clock cycles must be used in the 8088 to avoid collision of data on this internal bus. For example, in a compare (CMP) instruction, two 16-bit values must be passed to the ALU (arithmetic/logical unit) for comparison. These two values must be passed in 2 subsequent operations since only one value may be on the bus at one time, even if both are available simultaneously.

The V20 maintains two internal data busses. The second data bus is

used to advantage in logical comparison and arithmetic instructions to fetch the second argument while the first argument is being fetched on the primary data bus. This results in a savings of one clock cycle, a 33% improvement. In addition, subtraction and comparison instruction times are reduced.

The 8088 allows several addressing modes to be used with its instructions. This makes the chip easier to program, but resolving some of its addressing modes into an effective address can be complicated as some modes require up to four additions to come up with a physical address. The 8088 uses microcoded subroutines to resolve these addresses. Although invisible to the user, these microsubroutines add from 5 to 12 clock cycles (depending on the addressing mode used) to the number of cycles needed to execute a single assembler instruction.

The V20 does not use microcoded subroutines to calculate effective addresses. Rather the chip contains a special circuit called the Effective Address Generator (EAG) which can calculate any effective address in a constant 2 clock cycles. (Note: The addition of an EAG circuit is one of the important improvements in the later members of the 8086 family.)

In order to improve chip performance, the 8088 has a 4-byte prefetch queue (6 byte in the 8086). The Bus Interface Unit (BIU) section of the chip uses clock cycles during which the bus would otherwise be idle to prefetch the next instruction to be executed into a faster memory within the chip (this technique is known as pipelining and is practiced on most modern microprocessors). The BIU in the 8088 allows the Instruction Pointer

(IP) to "get ahead" of the Execution Unit, the part of the microprocessor which actually carries out the individual instructions. Thus, although we programmers think of the IP as pointing to the currently executing instruction, in fact the IP points to the next instruction to be prefetched, which may be several bytes ahead.

This works fine for instructions which don't use the instruction pointer, but jumps and loops are coded relative to the IP. For example, a jump instruction at address 1F0 codes a 'JMP 200' as 'jump forward 10 bytes'. Thus, whenever the execution unit encounters such an instruction, it must first back the IP up to the currently executing instruction (the jump, etc.) before it can calculate the target address.

The effect of this is easily seen in the conditional jump and loop instructions. The conditional jump instruction takes a modest 4 cycles if the jump is not taken. Here the instruction pointer is not backed up since no jump is performed. The same instruction takes a relatively long 16 cycles to perform if the jump is taken and the program counter must be recalculated.

(Notice that every instruction which changes the instruction pointer causes the contents of the prefetch queue to be flushed. This forces the next instruction to be fetched from external memory, slowing down its execution by several clock cycles. This effect does account for a part of the time difference in the conditional jump timings.)

In far CALLs and INTerrupts the target address is not coded relative to the IP, but instead absolutely. A far CALL to 100:100 would encode the address 100:100 literally, independent of its own address. In these cases, however, the IP must still be backed up so that it may be pushed onto the stack as the return address. Therefore, the effect in these cases is the same.

The V20 has a Prefetch Pointer separate from the instruction pointer for maintenance of the prefetch queue. The IP actually does point immediately after the instruction being executed just like we had always thought, while the prefetch pointer scouts out ahead for the next instructions. Thus, when a IP relative instruction is executed there is no need to back the IP up and that time is saved. For example, the V20 requires 50 clock cycles to perform an INT instruction, compared to the 8088's 63.

A further internal improvement of the V20 is the addition of two internal registers, allowing more efficient algorithms in the microcode for many instructions. The V20's string

instructions are roughly twice as fast, while its multiply and divide are up to three times as fast. Of all of the time improvements in this chip, the improvements in the multiply and divide have the potential for being the most significant, depending on the application. Since these are the longest instructions in the 8088's instruction set, in terms of time to execute, a 50% improvement may amount to many clock cycles. (It is not always obvious that your program is performing multiplies -- many high level language resolve matrix subscripts with MUL instructions.)

In addition to these timing improvements in the 8088 instructions, the V20 adds three sets of extra instructions to the 8088 instruction set. The first of these extensions are the 80186 extensions, which are also the only extensions available to the 80286 when left in real mode (the 80186 and 80286 are the next members of the Intel iAPX 86 family).

These include a PUSH/POP all (pushes/pops all registers in one instruction), an expanded class of rotate and shift instructions, a string OUT and IN (used with the repeat prefix REP) for faster CPU controlled I/O and a set of stack frame instructions useful primarily for higher level languages (see Table 1).

The PUSH/POP all instructions are quite handy for interrupt routines which must save off any registers they intend to use upon entry into the interrupt code and restore them upon exit. In the 8088 rotate and shift instructions may only specify the CL register or a 1 as the number of bit positions to rotate; no other constant is allowed. The extended V20 shifts allow any constant (or the

CL register). The string IN and OUTs allow driving I/O devices at the bandwidth of the bus under CPU control (as opposed to DMA). This is a respectable 2MB per second on an 8 MHz V30.

The 8088 has no instructions to manipulate any field smaller than a byte. The V20 corrects this limitation in the second set of extensions, which NEC calls the unique instructions. These include nibble (4-bit) and bit instructions (test, set, clear and complement) as well as a pair of new repeat prefixes (repeat while and until carry) and a second floating point prefix (see Table 2). This second prefix allows NEC to offer an extended set of floating point instructions with their own numerical coprocessor, due out the beginning of next year.

The final members of the instruction set are truly unique, not being present on any other common microprocessor. They are the "enter emulation" and "exit emulation" instructions. When, in what NEC calls emulation mode, a different set of microcode is executed by the V20/30. This new set of microcode allows the NEC chips to execute 8080 code!

In emulation mode the V20 continues to look externally like an 8088, but it no longer understands 8088 instructions. Internally it now becomes an 8080 8-bit microprocessor. With the proper interface code, any computer using this chip can run either 8086 code (MS-DOS, CPM86, etc.) or 8080 code (primarily CPM80). We will leave the detailed discussion of how this is done (along with examples of a BDOS to do this) to the second part of our two part series.

These internal improvements to the

**TABLE 1**  
**EXTENDED INSTRUCTIONS**  
(USING INTEL 80186/286 MNEMONICS)

INSTRUCTION	FUNCTION
PUSH <i>immed16</i>	push an immediate value onto the stack
PUSHA	push all eight general registers
POPA	pop " " " "
IMUL <i>reg16,mem8,immed8,mem16,immed16</i>	multiply memory with immediate value and place result into <i>reg16</i>
SHL <i>reg8 or 16,immed</i>	similar to normal shift left except that any value is allowed (not limited to CL or 1)
SHR	
SAL	
SAR	
ROL	
ROR	
RCL	
RCR	
INSB,INSW	string input used with REP prefix (byte or word)
OUTSB,OUTSW	string output used with REP prefix ( " " )
ENTER <i>immed16,immed8</i>	sets up a stack frame for Pascal or ADA
LEAVE	tears down a stack frame
BOUND <i>reg16,mem block</i>	check an index against a memory block for range

V20 have forced the internal microcode size to swell from the 8088's 21 bits to some 29 bits and the transistor count, a measure of the complexity of a chip, to almost double.

### ADDING THE V20/30 TO YOUR 8088/86 COMPUTER

Were it not for the external similarity of the V20 with the 8088 (and the V30 with the 8086), the discussion so far might be merely interesting but of no immediate use. However, since the NEC chips are pin compatible with the corresponding Intel part, anyone who owns a computer containing either of the Intel chips can have access to these improvements by merely replacing a microprocessor chip.

The V20 and V30 should work with Intel's 8087 Numerical Processor (NP). In this mode of course the new floating point instructions are not available, but the standard Intel set works the same. I did not have sufficient access to the Intel numerical processor to test this completely.

Note also that the NEC parts will cause problems in the TI Professional Computer and the Victor 9000. The TI uses some rather critical timing loops in its self test BIOS code. Due to the higher speed of the V30, the TI erroneously times out its hardware and will not complete boot up. The Victor will not format a diskette properly, again due to the processor's higher speed. The IBM PC and XT, Compaq Portable and Deskpro, Hyperion, Eagle PC, and Columbia are among those computers known to work properly with the NEC chip. Computers not on either list will probably work without problems.

When selecting the proper NEC chip for your computer you should first note whether your computer uses the 8088 or the 8086. Your documentation should make this clear in the technical specifications. You should next note the clock speed of your system. It will probably be either 4.77 MHz or around 8 MHz (the 8088-2 is the 8 MHz model). The NEC processors come in 5, 8, and 10 MHz versions. If your machine runs at 4.77 MHz, then the 5 MHz model is the one for you; if your system clock is between 5 and 8 MHz or if you have a switchable clock who's higher speed is in this range, then the 8 MHz model is the correct processor. If your processor runs faster than 8 MHz, you are safest ordering the 10MHz part.

NEC only guarantees a chip's rated speed if your computer's clock maintains a 50% duty cycle, the optimum for CMOS processors. If your computer runs with a 33% duty cycle clock, the optimum for NMOS chips, the V20/30 will probably work at its

**TABLE 2  
NEC'S UNIQUE INSTRUCTIONS**

INSTRUCTION	FUNCTION
INS reg8,reg8 reg8,immed4	transfers number of bits in second operand from least significant bits of AL into DS:[DI] with bit address in lower 4 bits of first operand; both DI and first operand are updated to point to next bit field
EXT " , "	inverse operation to that above
ADD4S	adds BCD number pointed at by SI to the BCD number pointed at by DI; length of two BCD numbers is in CL (max no. of digits is 254); sets flags
SUB4S	subtracts similar to add above
CMP4S	set flags as subtract above without saving results
ROL4 reg8	rotates left by 4 bits 8 bit register or memory location specified with lower 4 bits of AL register
ROR4 "	complimentary operation
TEST1 CL or immed3,reg8 CL or immed4,reg16 CL or immed3,mem8 CL or immed4,mem16	set Z flag if bit specified by first argument in byte or word pointed at by second argument is clear.
NOT1 " , "	complement bit specified as above
CLR1 " , "	clear bit specified as above
SET1 " , "	set bit specified as above
REPC	repeat while carry following string instruction
REPNC	repeat until carry " " " "
FPO2	prompts NEC numerical processor for unique NEC floating point op.s
BRKEM immed8	execute 8080 code pointed at by interrupt vector immed8 (not included in EXIND.INC - will be covered in part 2)

specified rating, but you might want to order the next faster chip just to be safe.

With this information in hand, you are now ready to order your V20 or V30. As of this writing, few computer retail outlets have these parts in stock. I did find two retailers handling the parts: Lolir Electronics, 13933 N. Central Expressway, Suite 212, Dallas, Tx 75243 (214-234-8032) and GFI Electronics, 1800 Avalon St., Olathe, KS 66062 (913-829-0157). The price for the 5 MHz V20 was \$24.95. Wherever you purchase yours, cost should be in the \$25 to \$35 range, depending on speed and whether ordering the V20 or V30.

To install the new chip, you will of course need to locate and remove your existing processor. Locating the chip is fairly straightforward: look for a 40 pin dual in-line package (DIP) with the designation 8088 or 8086 on it. In the case of IBM PC's and their clones, the 8088 is at the far rear of the board, immediately in front of the keyboard connector. Before removing the old chip, note in which direction the half circle groove on top of the chip points. Removing the chip is best done with a

chip puller tool, but can be done by sliding a screwdriver up under the chip and carefully prying the chip up, being especially careful not to bend the chip legs.

To insert the new chip, set it down on top of the socket with each pin sitting in the slot into which it will be going. If one or more pins do not match the hole(s), bend them until all do. Be sure the chip is oriented with its half-circle groove facing the same as the old chip. Now carefully, but firmly, press the chip into the socket ( be careful to support the other side of the board, if possible, to keep from bending it any more than is necessary).

### USING THE NEC V20/30

Once you have installed your V20 or V30 in your system, you should notice some increase in speed. This increase will depend on what type of work you are doing and upon the configuration of your hardware. Programs which perform a lot of floppy disk I/O will not improve significantly. Programs which are not I/O bound and perform lots of calculations (multiplies and divides) will improve dramatically.

**TABLE 3**

BENCHMARK	REPS	8088 (4.77MHz)			8086 (7.14 MHz)		
		INTEL	NEC	%DIFF	INTEL	NEC	%DIFF
Sieve of Eratosthenes	10	3.9	3.7	5%	1.9	1.7	12%
Bench A +	50,000	2.0	1.8	11%	1.0	0.8	25%
Bench B	5,000	7.2	6.8	6%	3.4	3.0	13%
Bench E	20,000	10.6	7.9	34%	6.3	4.6	37%
Bench F	20,000	10.9	10.3	6%	5.1	4.5	13%
			(6.3)*	(73%)*		(3.0)*	(70%)*
Bench H	10,000	7.1	6.8	4%	3.5	3.1	13%
Bench I	100	11.1	9.8	13%	6.0	4.6	30%
Bench K	10,000	29.9	26.0	15%	15.8	12.8	23%
			(18.0)*	(66%)*		(8.1)*	(95%)*
Filter ++	20,000	22.6	13.5	67%	13.0	6.7	94%

8088 times measured on an unmodified IBM PC; 8086 times on a Compaq DeskPro in "fast" mode

\* = time when algorithm recoded to take advantage of NEC unique instructions  
 + = benchmarks A thru K were selected in EDN Sept. '81 from a 1979 Carnegie Mellon study for comparing 8086, 68000 and 32016 microprocessors; these benchmarks were selected as being most applicable to microprocessors.  
 Individual benchmarks measured:  
 Bench A - interrupt response time  
 Bench B - interrupt response time  
 Bench E - string instruction performance  
 Bench F - bit manipulation  
 Bench H - linked list manipulation  
 Bench I - quick sort  
 Bench K - bit manipulation  
 ++= filter benchmark selected from IEEE Micro 2/81 as being particularly advantageous for their microprocessors

To test the increase in speed I ran several benchmarks on an IBM PC (5MHz), and on a Compaq Deskpro (8MHz 8086), first with their standard Intel processors and then again with the NEC chips. The results of these timings appear in table 3. It should be noted that I had no problem in replacing the processors on either computer and neither system showed any signs of rejecting the foreign chip.

When interpreting the "percentage improvement" column of Table 3, keep in mind that this is the improvement of the NEC chip over the Intel chip. Thus a figure of 100% means that the NEC part performed the benchmark in one half the time, ie. twice as fast.

The first benchmark, the Sieve of Eratosthenes, is something of a standard, appearing in almost every discussion of compiler or processor speed. The sieve is small and easily reproduced on different processors, but does not test very many aspects of a chip. Nevertheless, the assembler source code for the sieve appears as program listing 1.

A further set of benchmarks was reproduced from an article appearing in EDN magazine, which compared the performances of several popular microprocessors. This bank of benchmarks tests various aspects of processor performance. In every case, the code for each benchmark was taken

directly from the article. In some cases, however, the benchmark could have been coded more efficiently using the NEC chip's instruction extensions. In these cases, the benchmarks were recoded using the more efficient instructions and rerun. These times appear after the times using only the "standard" 8086 instructions.

A final digital filter benchmark was selected from the IEEE's Micro magazine. This benchmark contains a high percentage of multiply and divide instructions to highlight the improvements in the V20 and V30. As expected the relative increase in performance was largest for this benchmark.

The improvement on the 8088 equipped PC was not large, in some cases hardly amounting to more than 5%. The improvement in the 8 MHz 8086 was much more substantial, averaging more in the 25 to 35%. This is primarily because in programs with long strings of simple to execute instructions, such as those in the sieve, the 8088 runs at roughly 90% bus utilization. It is very difficult for the V20 to get data in and out through this 8-bit bottleneck very much faster than the 8088 chip and thus the meager throughput improvement. The relatively greater improvement in the V30 is due to the wider bus being much less of a performance limiting factor.

However, for those who tend to run

programs which perform large amounts of math, such as spreadsheets without 8087 support, the improvements of even the V20 are substantial. This is equally true for those who code their own programs and are willing to make use of the V20/30 extensions.

To easily quantify your throughput increase, a benchmark program called CPU was adapted from a public domain program of the same name (see Program 2). Run this program before installing the NEC chip to get a reference for your system. The program compares the speed of your system against an IBM PC. You will get a time to execute (10 seconds on the PC) and an effective clock speed - that is, your PC runs as fast as an IBM PC with this speed clock. Rerunning the benchmark with the NEC part should result in shorter times and a faster effective clock speed. Notice that your clock speed has not changed, only the effective clock speed -- the difference is due to the NEC using fewer cycles to perform the same instructions.

Picking the instruction mix to use in the timing loop of CPU is a difficult thing. The increase in throughput using NEC CPUs can vary anywhere from near 0%, if only simple instructions are used, to more than 100% if multiplies and divides are present. I have tried to pick a mix which accurately reflects the types of instructions I code. You may want to change the instruction mix to fit the types of programs you run.

To do this, with the Intel part still in place, change the instruction mix in the timing loop to whatever you prefer. Adjust the number of iterations of the timing loop until you get the same value for clock speed that you got when you ran my mix (4.77 for the IBM PC). When you now install the NEC chip rerun the program to get an accurate measure of how much improvement you should expect. Including lots of string instructions or multiplies in your instruction mix will favor the NEC; lots of simple instruction will minimize the improvement of the NEC.

### USING THE NEC INSTRUCTIONS

Programs which you buy or download from bulletin boards will continue to use only 8086/88 instructions and so, unless you write your own assembler programs, you cannot expect to see any improvement from the extended instruction set. However, if you do write some of your own programs, you may want to use some the improved instructions.

If you own a later copy of Microsoft's MASM assembler, simply specifying the .186 or the .286C pseudo-op at the top of your program will allow you access to the extended

instructions (but not the unique instructions). The Microsoft assembler manual, as well as Intel publications, describe the proper format for these instructions, so I will not describe them in detail here. A list of these instructions appears in Table 1. Programs using the extended instructions will also execute properly on 80186 and 80286 equipped computers.

The unique instructions defined by NEC fall into several related groups. The first group is comprised of the variable length bit field operations, INS (insert) and EXT (extract). The insert instruction transfers the least significant bits from the AX register to the address pointed at by DS:DI. The starting bit position in the memory location is specified by the first argument, which must be a register, and the number of bits transferred by the second argument, which may be either a register or an immediate value. The bit fields may cross from one byte or word to the next. The first argument and the DI register are updated after each transfer. The extract instruction performs the same function in the opposite direction. This instruction pair allows for efficient packing and unpacking from a structure of fields which are not an even 8 or 16-bits.

Also provided are the single bit instructions, TEST1 (test), NOT1 (complement), CLR1 (clear bit), and SET1 (set bit). The test bit instruction sets the Z flag if the specified bit is a 0 and clears the Z flag if not. All four of the above instructions specify a bit position in a byte or word field. The bit position is in the first argument and is either an immediate value or else the CL register. The word or byte in the second argument can be any valid reference: register, variable, or indexed location.

Three operations are included in the packed BCD group: ADD4S, SUB4S and CMP4S. Each of these operate on the BCD number pointed at by the DI register with the BCD number pointed at by the SI register. The number of BCD digits is specified by the CL register. These operations set the overflow, carry and zero flags, but if the number of digits is odd, the zero flag is not set correctly. An extra set of BCD rotate instructions, ROL4 and ROR4, rotates the 8-bit register or memory location specified by the single argument through the least significant 4 bits of the AX register. This instruction group allows efficient BCD algorithms to be implemented.

Two new prefixes to string instructions are added with the unique instructions: REPC (repeat as long as

## NEC VERSUS INTEL

The similarities between NEC's uPD70108/116 and Intel's 8086/88 microprocessors did not go unnoticed by either company. Before introducing the 108 and 116, NEC asked the U.S. District Court in December of 1984 to rule that the chips' microcode did not infringe upon Intel's copyrighted 8086/88 microcode (past rulings had made it clear that the underlying hardware was neither copyrightable nor patentable). Intel responded by suing NEC in February of 85 for copyright violation. Intel's suit must have been anticipated by NEC's engineers for some time, since NEC had already gone to some pains to build a defense for their chip.

First, NEC introduced these chips as members of the newly announced V-Series of microprocessors and refer to them as the V20 and V30. Other members of the V-Series do not directly resemble any existing microprocessors. Secondly, in its instruction set descriptions, NEC is careful to call its 80186 compatible instructions the "extended instructions", while designating the bit instructions (not present in any of Intel's chips) as the "unique instructions". This NEC does without ever mentioning the 80186.

Perhaps even more damning, is NEC's access to internal documentation on the 8086. As a contracted second source for the Intel processors, NEC would have had detailed drawings and perhaps even microcode listings at its disposal when designing the V20 and V30.

carry set) and REPNC (repeat until carry set). An extra floating point instruction is included for eventual use with the NEC numerical processor to be introduced later.

The NEC's unique instructions are summarized in Table 2. If you would like to use these unique instructions and are using the popular Microsoft MacroAssembler, including the macro definition file EXTND.INC (Program 3) at the beginning of your program will define the unique instructions for you. (This is the same macroassembler sold and endorsed by the MS-DOS personal computers' manufacturers, including IBM.) Assembling a program which uses unique instructions can be done on either an Intel or NEC microprocessor, but of course, the resulting program will only run properly on the NEC chip.

The reader will probably be struck by the complexity of these macro

NEC does have some real defenses built right into the chip. NEC added a set of instructions to their processors not present on any Intel processor, including an emulation mode not present on any other common microprocessor. NEC improved the hardware by introducing a dual rail internal bus, hardware calculation of effective address (which the Intel 80186 has but not the 8086) and an extra prefetch pointer to reduce the penalty of JUMPs and CALLs. These improvements result in increased CPU throughput by reducing the number of clock cycles required to perform most instructions. Further, the internal word size of the V20 and V30 processors was increased to 29 bits vs. the 8086 and 8088's 21 bits.

NEC may or may not win its case in district court, but no matter what the decision, the case will undoubtedly end up in the Supreme Court. By the time a decision is eventually handed down, it might well be a moot as the 8086/88 processor is already in the autumn years of its existence. In late April, Intel raised the stakes by asking for a summary judgement on the issue of whether microcode is copyrightable (a recent decision in the case of Apple vs Franklin established that software is copyrightable, but this decision probably does not apply to microcode). With that move the case took on an importance far more important than the original question, one which will have long reaching effects on the entire semiconductor industry.

definitions; this is primarily due to the severely limited macro capabilities of the Microsoft assembler. An example subroutine has been provided in program 4 showing usage of the unique instruction set.

Notice that the assembler limitations resulted in two concessions. As with all memory references, NEC allows segment overrides to be added to memory references in unique instructions. The macros provided do not allow adding a segment override directly to a memory reference. Generally a segment override can be avoided, but you can specify a segment with the override macros provided. Unlike normal segment overrides, these macros precede the instruction. Thus, instead of coding 'TEST1 CL, CS:memory\_loc', you would need to code 'CS TEST1 CL, memory\_loc'. If you prefer, you can use these segment

override macros for all instructions, not only the unique opcodes.

Secondly, I was forced to code the bit instructions with the arguments in reverse order from that specified by NEC. Thus, where NEC specifies TEST1 AX,CL, I was forced to use TEST1 CL,AX.

Since incorrectly coding a unique instruction might lead to completely misleading error messages in the macro expansion, the macros check all arguments to the instructions for proper type. If a type is wrong, the offending argument is displayed on the listing along with a comment explaining the problem and an *Improper syntax* error message.

A special macro has also been included for Intel compatibility. This instruction macro, called J\_NOT\_NEC, checks the processor upon which it is being run to determine whether it is an Intel or an NEC part. If it is the NEC part, the jump is not taken; if it is an Intel processor, the jump is performed. This allows the programmer to code sections both with and without the NEC extensions. Such programs use the faster, more convenient NEC instructions when possible, but continue to work, albeit more slowly, when executed on Intel processors.

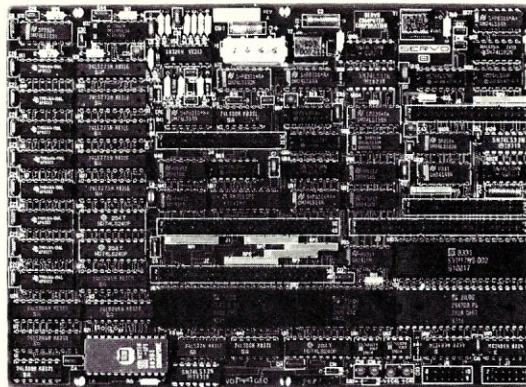
The emulation instructions are not defined in EXTND.INC as they cannot be executed like normal instructions without going into 8080 mode. This entire subject will be dealt with in Part 2 of this series.

A second macro definition file has also been provided for Intel's assembler as Program Listing 4. This assembler is superior to Microsoft's but, due to its exorbitant price plus Intel's marketing policy, is almost unknown. These macro definitions are much more straight forward due to that assembler's extensive macro capabilities. These macros perform more or less identically to those above except for the absence of the peculiarities noted in EXTND.INC.

When disassembling a program with MS-DOS's DEBUG, the debugger will not disassemble the extended and unique instructions correctly. Attempting to disassemble them with the U command will result in some garbaged instructions at, and immediately after, the NEC instruction. This does not mean that the instruction is encoded incorrectly, so this is a big nuisance when debugging. (The debugger provided with MS-DOS 3.0 and later does handle the extended instructions properly.)

Several users groups are beginning to spring up around the country to offer support for the V20 and V30. This

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effort is being encouraged and supported by NEC. Already a version of DEBUG which understands and supports the NEC unique (and extended instructions) is available in the public domain. If you would like a copy of this debugger, send your name and address plus \$10 to cover postage, disks, mailers, etc. to: Stephen R. Davis, Route 5 Box 107K, Greenville, Tx 75401. This disk also includes source and executable code for all benchmarks mentioned in the article, source files for all listings appearing in both Parts 1 and 2, sample 8080 programs which run on

the V20/30, etc. I will also include the numbers and addresses of any support groups.

### CONCLUSION

The NEC V20/30 microprocessor provides a means of turbo charging your conventional 8086/8088 personal computer both in terms of speed and in terms of instruction set. Although the improvement may not come close to the improvements claimed for some of the add-on turbo cards, neither is the rather modest \$25 cost close to their price.

## PROGRAM 1 LISTING

```

; Sieve of Erasthosthenes
;
; Stephen R. Davis
;
NTIMES EQU 8190 ;STANDARD SIZE
NLOOPS EQU 10 ;TEN ITERATIONS STANDARD

CSEG SEGMENT PUBLIC PARA
ASSUME CS:CSEG,DS:CSEG,ES:CSEG

ORG 100H

START:
CLI ;DON'T CONFUSE WITH INTERRUPTS
MOV LOOP_CNT,NLOOPS ;INIT LOOP COUNTER

OUTER_LOOP:
XOR AX,AX ;FIRST ZERO OUT FLAG ARRAY
MOV DI,OFFSET ARRAY
MOV CX,NTIMES/2
CLD
REP STOSW

XOR DX,DX ;NOW COUNT THE PRIMES
XOR BX,BX ;KEEP THE COUNT IN DX
MOV CX,NTIMES ;START AT SUBSCRIPT 0
MOV DI,CX ;GET THE LOOP COUNT

INNER_LOOP:
CMP BYTE PTR ARRAY[BX],0
JNZ SKIP_AROUND
MOV AX,BX
ADD AX,BX
ADD AX,3
MOV PRIME,AX
MOV SI,BX ;NOW MARK OUT MULTIPLES
ADD SI,AX

MARK_OUT:
MOV BYTE PTR ARRAY[SI],0FFH ;MARK THIS MULTIPLE OUT
ADD SI,AX
CMP SI,DI ;IS THAT IT?
JNA MARK_OUT
INC DX ;INCREMENT PRIME NUMBER COUNT

SKIP_AROUND:
INC BX
LOOP INNER_LOOP
MOV COUNT,DX ;NOW COUNT IS IN DX REGISTER
DEC LOOP_CNT ;DO IT 10 TIMES
JNZ OUTER_LOOP
INT 20H ;OK -- STOP NOW

;DEFINE OUR VARIABLES DOWN HERE
LOOP_CNT DW 0
PRIME DW 0
COUNT DW 0
ARRAY DB NTIMES DUP (0)
CSEG ENDS
END START

```

## PROGRAM 2 LISTING

```

TITLE CPU

;CPU WAS TAKEN FROM PUBLIC DOMAIN AND MODIFIED TO PROVIDE
;A REPRESENTATIVE INSTRUCTION MIX FOR QUANTIFYING SPEED
;OF ONE'S 8086/8088/80186/80286 COMPUTER IN TERMS OF STANDARD
;IBM PC. RESULT IS IN EFFECTIVE CLOCK RATE (I.E. YOUR COMPUTER
;RUNS AS FAST AS AN IBM PC WITH FOLLOWING CLOCK RATE)

LF EQU 0AH
CR EQU 0DH
HUNDRED EQU 64H
THOUSAND EQU 3E8H
TEN EQU 0AH

CODE SEGMENT
ASSUME CS:CODE,DS:CODE,SS:CODE,ES:NOTHING
ORG 100H

;FIRST OUTPUT A 'WAIT A MINUTE' MESSAGE & THEN GET TIME

START:
MOV AH,9
MOV DX,OFFSET INIT_MSG
INT 21H
MOV AH,2CH
INT 21H
MOV TIME1,DX
STI ;BE SURE CLOCK IS RUNNING

```

```

;HERE IS THE BIG TIMING LOOP
XOR AX,AX
MOV DX,TEN
OUTERLOOP:
MOV CX,03B84H ;THIS NUMBER MUST BE AD-
;JUSTED FOR DIFFERENT MIXES

TIMERLOOP:
;MY MIX OF REPRESENTATIVE, USEFUL INSTRUCTIONS --
;USER MAY PROVIDE HIS OWN AND REASSEMBLE, BEING CAREFUL
;TO ADJUST CONSTANT ABOVE FOR TOTAL NUMBER
;OF CLOCK CYLES IN LOOP
MOV AX,BX ;REGISTER TO REGISTER MOVE
MOV AX,BX ;(FAR AND AWAY MOST COMMON)
MOV AX,BX
MOV AX,BX
MOV AX,BX
MOV AX,10[BX] ;COMPLEX ADDRESSING
MOV AX,10[BX] ;(PRETTY COMMON)
MOV AX,10[BX]
MOV AX,10[BX]
ADD AX,AX ;REG - REG ARITHMETIC
ADD AX,10 ;REG - IMMED ARITHMETIC
PUSH CX ;PUSH (POP FOLLOWS) ARE COMMON
MOV CL,5
SHL AX,CL
POP CX
CALL DUMMY_ROUTINE ;THESE CALLS/JUMPS SHOULD ALSO
; FAVOR NEC
JMP CONTINUE
DUMMY_ROUTINE PROC NEAR
RET
DUMMY_ROUTINE ENDP
CONTINUE:
LOOP TIMERLOOP
DEC DX
JNZ OUTERLOOP
;NOW GET TIME AGAIN (AFTER LOOP)
MOV AH,2CH
INT 21H
;OK -- CONVERT THIS INTO CLOCK SPEED RELATIVE TO 8088
;AND OUTPUT IN ASCII FORM
MOV AX,HUNDRED
IMUL DH
MOV DH,0
ADD AX,DX
MOV BX,AX
MOV DX,TIME1
MOV AX,HUNDRED
IMUL DH
MOV DH,0
ADD AX,DX
SUB BX,AX
JNB SKIP
ADD BX,1770H

SKIP:
MOV AX,BX
MOV TIME2,BX
MOV BP,OFFSET VALUE1
MOV BX,THOUSAND
CWD
IDIV BX
CALL CONVERT2NUM ;CONVERT FIRST VALUE & STORE
MOV BX,HUNDRED ;HUNDREDS DIGIT
MOV AX,DX
CWD
IDIV BX
CALL CONVERT2NUM
INC BP
MOV BX,TEN ;TENS DIGIT
MOV AX,DX
CWD
IDIV BX
CALL CONVERT2NUM ;ONES DIGIT
MOV AX,DX
CALL CONVERT2NUM
MOV AH,9
MOV DX,OFFSET RES_MSG
INT 21H
MOV AX,12A2H/TEN ;CALCULATE EFFECTIVE CLOCK RATE
CWD
MOV BX,TIME2
DIV BX
MOV BP,OFFSET VALUE2
CALL CONVERT2NUM ;TENS DIGIT
MOV AX,DX
MOV CX,TEN
MUL CX
DIV BX
CALL CONVERT2NUM ;ONES DIGIT
INC BP
MOV AX,DX
MUL CX

```

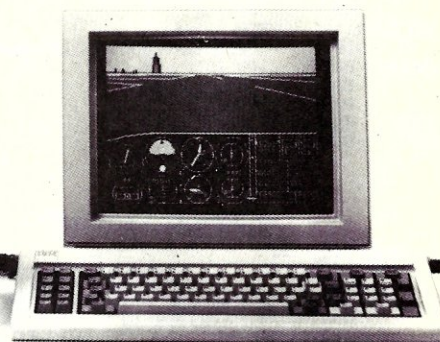
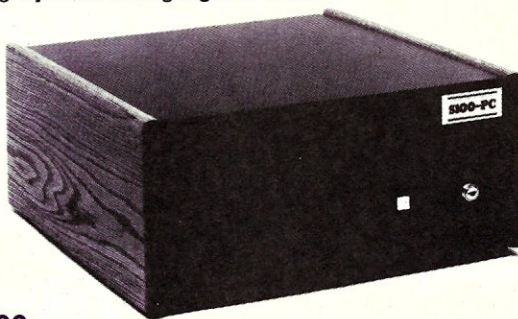


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```

DIV     BX
CALL   CONVERT2NUM           ;TENTHS DIGIT
MOV    AX,DX
MUL    CX
DIV    BX
CALL   CONVERT2NUM           ;HUNDRETHS DIGIT
MOV    AH,9
MOV    DX,OFFSET RES_MSG2
INT    21H
MOV    AH,4CH                 ;TERMINATE
INT    21H
CONVERT2NUM:
OR     AL,30H ;'0'
MOV    [BP+0],AL
INC    BP
RET
TIME1  DW 0000
TIME2  DW 0000
INIT_MSG DB 'CPU SPEED CHECKER ',2CH,' please w'
        DB 'ait... ',CR,LF,CR,LF
        DB '$'
RES_MSG DB 'Execution time should be 10.00 secs on a
        DB '4.77 Mhz 8088 ',CR,LF
        DB 'with no WAIT's on RAM access ',CR,LF
        DB 'Actual execution time here was '
VALUE1 DB '00.00'
        DB ' seconds ',CR,LF
        DB '$'
RES_MSG2 EQU $
        DB 'Effective 8088 clock speed = '
VALUE2 DB '00.00'
        DB ' Mhz ',CR,LF
        DB '$'
CODE   ENDS
END    START

```

```

;OK WE CAN NOW BEGIN DEFINING NEC UNIQUE INSTRUCTIONS
;THE BCD INSTRUCTIONS-
;   THESE HAVE NO ARGUMENTS, SO JUST PUT OPCODE
ADD4S  MACRO
        DB 0FH,20H
        ENDM
SUB4S  MACRO
        DB 0FH,22H
        ENDM
CMP4S  MACRO
        DB 0FH,26H
        ENDM
;THE BIT FIELD INSTRUCTIONS-
;   THESE ALLOW EITHER 2 1-BYTE REGISTERS OR ELSE
;   A BYTE REGISTER & AN IMMEDIATE BYTE VALUE.
;   HERE WE CAN DO ALMOST COMPLETE ERROR
;   CHECKING BECAUSE OF SIMPLE ARGUMENT TYPES.
;   DEFINE A TEMPLATE TO DO THAT.

```

```

BIT_FIELD MACRO CC,ARG1,ARG2
    .OK = 1
    SET TYPE ARG1           ;;CHECK ARGUMENT 1 FOR VALIDITY (REG8)
    IF TYPE OF ARG - 101H
        ARG1 ; ARGUMENT MUST BE BYTE REGISTER
        .OK = 0
    ENDIF
    OPCODE = OC
    IF .OK
        SET TYPE ARG2 ;;NOW CHECK ARGUMENT 2 (REG8 OR IMM8)
        IFE TYPE OF ARG
            OPCODE = OPCODE + 8 ;;IMMEDIATE ARG
        ELSE
            IF TYPE OF ARG-101H ;;CHECK FOR REG8
                ARG2 ARGUMENT MUST BE BYTE REG OR IMMED
                .OK = 0
            ENDIF
        ENDIF
    ENDIF
    IF .OK ;;IF ARGUMENTS OK, BUILD INSTR.
        DB 0FH
        DB OPCODE
        IFE TYPE OF ARG
            DB 0C0H+@&ARG1 ;;IMMED8 TYPE SECOND ARG
            DB ARG2
        ELSE
            DB 0C0H+(@&ARG2 SHL 3)+@&ARG1 ;;REG8 TYPE 2ND ARG
        ENDIF
    ENDIF
    ENDM
;INS-
INS MACRO ARG1,ARG2
    BIT_FIELD 31H,ARG1,ARG2
    ENDM
;EXT-
EXT MACRO ARG1,ARG2
    BIT_FIELD 33H,ARG1,ARG2
    ENDM
;NOW BIT INSTRUCTIONS
;BIT INSTRUCTIONS HAVE A COMPLICATED STRUCTURE, ALLOWING
;EITHER CL OR ELSE AN IMMED VALUE FOLLOWED BY ANY REG. OR
;MEMORY ;REFERENCE (IT WAS NECESSARY TO REVERSE ARGUMENTS
;FROM NEC'S ;DEFINITION BECAUSE OF COMPLEXITY OF ADDRESS-
;ING MODES ALLOWED. THIS TEMPLATE BUILDS USES 'INC' IN-
;STRUCTION TO BUILD MORE COMPLICATED ADDRESSING MODES FOR
;IT (THE OPCODE OF INC INSTRUCTION IS OVERRITTEN WITH
;PROPER CODE AFTER ASSEMBLER GENERATES IT)
BIT MACRO CC,ARG1,ARG2,ARG3,ARG4
    LOCAL OPC,CONT
    OPCODE = OC
    .OK = 1
    IFDIF <ARG1>,<CL> ;;1ST ARG MUST BE CL OR IMMED
        SET TYPE ARG1
        IF TYPE OF ARG
            ARG1 ;ARGUMENT MUST BE CL OR IMMEDIATE VALUE
            .OK = 0
        ELSE
            OPCODE=OPCODE+8;;IF NOT CL, SET CL BIT IN OPCODE
        ENDIF
    ENDIF
    IF .OK
        SET TYPE ARG2
        IFE TYPE OF ARG ;;2ND ARG ANYTHING BUT IMMED
            ARG2 ;ARGUMENT MAY NOT BE IMMED. VALUE
            .OK = 0
        ENDIF
        IFE (TYPE OF ARG-2H) MOD 100H ;;IF MEM16 OR REG16
            ;;SET W BIT IN OPCODE
            OPCODE = OPCODE + 1
        ENDIF
    ENDIF
    ENDM

```

### PROGRAM 3 LISTING

```

;
; EXTIND.INC --
; .SALL ;;DONT BORE POEPL WITH EXPANSION
; IFL ;;WE NEED ONLY INVOLVE PASS 1
; WRITTEN FOR MICROSOFT ASSEMBLER TO DEFINE
; UNIQUE INSTRUCTIONS IN NEC'S PD70108/PD70116
; MICROPROCESSOR. INCLUDE THIS FILE IN YOUR
; PROGRAM WITHIN ANY SEGMENT DEFINITION BEFORE
; USING NEC INSTRUCTIONS; E.G.
;CSEG SEGMENT PUBLIC PARA
; ASSUME CS:CSEG,DS:CSEG,SS:CSEG
;
; INCLUDE EXTIND.INC
;
; ORG 100H
;START:
; <ETC.>
; WE NEED TO DEFINE SOME LABELS TO HELP DIFEREN-
; TIATE BETWEEN 8-BIT REGISTER ARG.S & 16-BIT
; REGISTER ARG.S TO OUR MACROS & TO GIVE
; REGISTERS VALUES TO BUILD INSTRUCTIONS
;
; .VAL = 0
; IRPC Z,ACDB ;; DEFINE FIRST 4 16-BIT REGGIES
@&Z&X = .VAL
        .VAL = .VAL + 1
        ENDM
;
; .VAL = 0
; IRPC Z,ACDB ;; DEFINE ALL OF 8-BIT REGISTERS
@&Z&L = .VAL
@&Z&H = .VAL + 4
        .VAL = .VAL + 1
        ENDM
;
;SET_TYPE -
; GIVEN AN ARGUMENT, SETS VARIABLE 'TYPE OF ARG' TO
; 0 IF IT IS AN IMMEDIATE VALUE
; 1 A BYTE VARIABLE REFERENCE
; 2 WORD VARIABLE
; ... ETC
; 101 BYTE REGISTER
; 102 WORD REGISTER
; 201 BYTE PTR TYPE REFERENCE
; 202 WORD PTR TYPE REFERENCE
;
;SET_TYPE MACRO ARG
; IFIDN <ARG>,<BYTE>
; TYPE_OF_ARG = 201H
; ELSE
; IFIDN <ARG>,<WORD>
; TYPE_OF_ARG = 202H
; ELSE
; TYPE OF ARG = TYPE ARG
; IFE TYPE OF ARG
; IFDEF "&ARG
; TYPE OF ARG = TYPE .&ARG
; IF TYPE OF ARG
; TYPE_OF_ARG = TYPE_OF_ARG + 100H
; ENDIF
; ENDIF
; ENDIF
; ENDIF
; ENDIF
; ENDIF
; ENDM

```

```

IF .OK
DB      0FH
IFE (TYPE OF ARG-102H);;FOR REG16 WE MUST BUILD INSTR
DB OPCODE
DB 0C0H+@&ARG2
ELSE
INC ARG2 ARG3 ARG4 ;;LET 'INC' BUILD ARGUMENT
ORG OPC
DB OPCODE      ;;NOW OVERWRITE OPCODE W/ OURS
ORG CONT
ENDIF
IFDIF <ARG1>,<CL>
DB ARG1
ENDIF
ENDIF
ENDM
;TEST1 -
TEST1 MACRO ARG1,ARG2,ARG3,ARG4
BIT    10H,ARG1,ARG2,ARG3,ARG4
ENDM
;NOT1 -
NOT1 MACRO ARG1,ARG2,ARG3,ARG4
BIT    16H,ARG1,ARG2,ARG3,ARG4
ENDM
;CLR1 -
CLR1 MACRO ARG1,ARG2,ARG3,ARG4
BIT    12H,ARG1,ARG2,ARG3,ARG4
ENDM
;SET1 -
SET1 MACRO ARG1,ARG2,ARG3,ARG4
BIT    14H,ARG1,ARG2,ARG3,ARG4
ENDM
;NEW STRING PREFIXES
; NO ARGUMENTS ALLOWED HERE
REPC MACRO
DB      65H
ENDM
REPNC MACRO
DB      64H
ENDM
;BCD ROTATES
;ONLY ONE ARGUMENT BEING ANY VALID 1-BYTE REFERENCE.
;AGAIN WE USE 'INC' INSTRUCTION TO BUILD PROPER
;ADDRESSING BYTES & OVERWRITE OPCODE WITH OUR OWN
BCD_ROT MACRO OPCODE,ARG1,ARG2,ARG3
LOCAL OPC,CONT
SET TYPE ARG1
IF (TYPE OF ARG - 01H) MOD 100H
ARG1 ARG2 ARG3; ARGUMENT MUST BE
; A BYTE REFERENCE
ELSE
DB      0FH
INC ARG1 ARG2 ARG3
ORG OPC
DB OPCODE
ORG CONT
ENDIF
ENDM
;ROL4-
ROL4 MACRO ARG1,ARG2,ARG3,ARG4
BCD_ROT 28H,ARG1,ARG2,ARG3
ENDM
;ROR4-
ROR4 MACRO ARG1,ARG2,ARG3,ARG4
BCD_ROT 2AH,ARG1,ARG2,ARG3
ENDM
;
;SEGMENT OVERRIDE
;PROVIDE METHOD FOR INCLUDING SEGMENT OVERRIDES
CS_ MACRO ARG1,ARG2,ARG3,ARG4,ARG5
DB      2EH
ARG1 ARG2,ARG3,ARG4,ARG5
ENDM
ES_ MACRO ARG1,ARG2,ARG3,ARG4,ARG5
DB      26H
ARG1 ARG2,ARG3,ARG4,ARG5
ENDM

```

```

SS_ MACRO ARG1,ARG2,ARG3,ARG4,ARG5
DB      36H
ARG1 ARG2,ARG3,ARG4,ARG5
ENDM
;J NOT NEC <LABEL>
; NOT STRICTLY A NEC UNIQUE INSTRUCTION, THIS MACRO
; TESTS CPU TO DETERMINE IF IT IS AN INTEL 8086/88
; OR NEC V20/V30; IF 86/88 JUMPS TO LABEL ARGUMENT,
; ELSE CONTINUES. ALL REGS ARE RETAINED EXCEPT CX.
J_NOT_NEC MACRO ARG
LOCAL V_SERIES
PUSH CS ;;PUSH CS IN CASE IT'S INTEL
XOR CX,CX
SET1 0,CX ;;INTEL WILL POP CS,
;;NEC WILL SET BIT IN CX
OR CX,CX ;;IS CX STILL 0?
JNZ V_SERIES
JMP ARG ;;YES - AHA, ITS AN INTEL CHIP
V_SERIES:
POP CX ;;NO--ITS NEC, BUT READJUST STACK
ENDM
ENDIF ;;END OF MACRO INCLUDE FILE

```

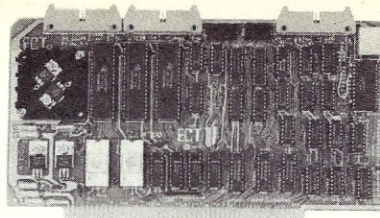
### PROGRAM 4 LISTING

```

$NoList
; Repeat Prefixes
CodeMacro DB REPC Prefx
065H
EndM
CodeMacro DB REPNC Prefx
064H
EndM
; Bit Field Instructions
CodeMacro DW INS dst : Rb, src : Rb
0310FH
ModRM src, dst
EndM
CodeMacro DW INS dst : Rb, count : D(0,15)
0390FH
ModRM 0, dst
DB count
EndM
CodeMacro DW EXT dst : Rb, src : Rb
0330FH
ModRM src, dst
EndM
CodeMacro DW EXT dst : Rb, count : D(0,15)
03B0FH
ModRM 0, dst
DB count
EndM
; Bit Manipulation Instructions
CodeMacro Segfix TEST1 dst : Eb, off : Rb(CL)
DW dst
ModRM 100FH
0, dst
EndM
CodeMacro Segfix TEST1 dst : Ew, off : Rb(CL)
DW dst
ModRM 110FH
0, dst
EndM
CodeMacro Segfix TEST1 dst : Eb, off : D(0,7)
DW dst
ModRM 180FH
0, dst
DB off
EndM
CodeMacro Segfix TEST1 dst : Ew, off : D(0,15)
DW dst
ModRM 190FH
0, dst
DB off
EndM
CodeMacro Segfix SET1 dst : Eb, off : Rb(CL)
DW dst
ModRM 140FH
0, dst
EndM
CodeMacro Segfix SET1 dst : Ew, off : Rb(CL)
DW dst
ModRM 150FH
0, dst
EndM
CodeMacro Segfix SET1 dst : Eb, off : D(0,7)
DW dst
ModRM 1C0FH
0, dst
DB off
EndM

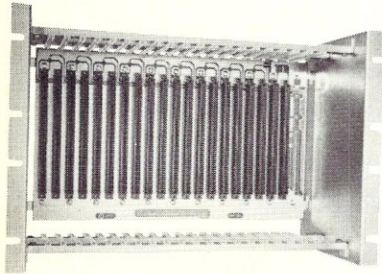
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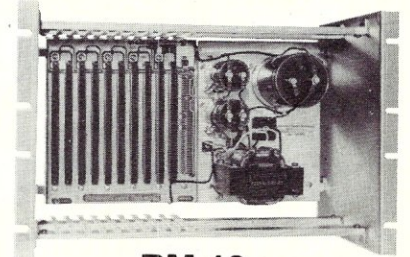


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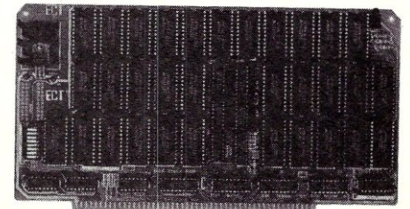
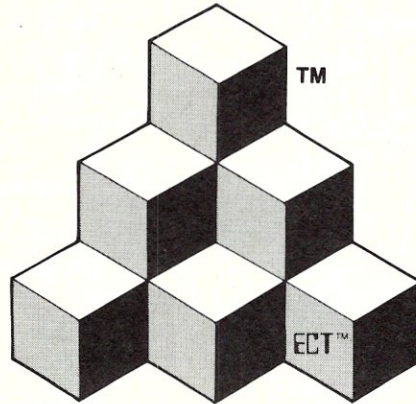


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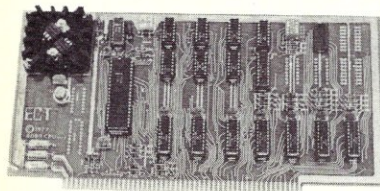


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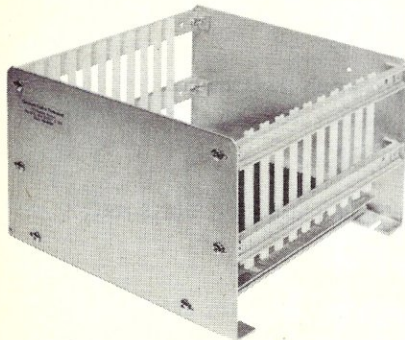
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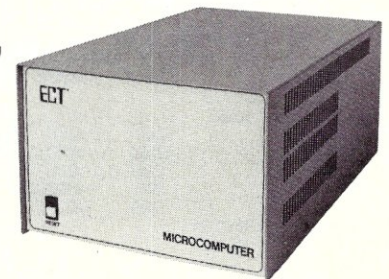
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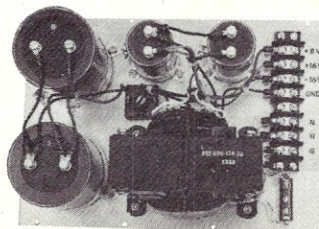


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```

CodeMacro   SETl   dst : Ew, off : D(0,15)
  Segfix   dst
  DW      1D0FH
  ModRM   0, dst
  DB      off
EndM

CodeMacro   NOTl   dst : Eb, off : Rb(CL)
  Segfix   dst
  DW      160FH
  ModRM   0, dst
EndM

CodeMacro   NOTl   dst : Ew, off : Rb(CL)
  Segfix   dst
  DW      170FH
  ModRM   0, dst
EndM

CodeMacro   NOTl   dst : Eb, off : D(0,7)
  Segfix   dst
  DW      1E0FH
  ModRM   0, dst
  DB      off
EndM

CodeMacro   NOTl   dst : Ew, off : D(0,15)
  Segfix   dst
  DW      1F0FH
  ModRM   0, dst
  DB      off
EndM

CodeMacro   CLRl   dst : Eb, off : Rb(CL)
  Segfix   dst
  DW      120FH
  ModRM   0, dst
EndM

CodeMacro   CLRl   dst : Ew, off : Rb(CL)
  Segfix   dst
  DW      130FH
  ModRM   0, dst
EndM

CodeMacro   CLRl   dst : Eb, off : D(0,7)
  Segfix   dst
  DW      1A0FH
  ModRM   0, dst
  DB      off
EndM

CodeMacro   CLRl   dst : Ew, off : D(0,15)
  Segfix   dst
  DW      1B0FH
  ModRM   0, dst
  DB      off
EndM

; Emulation Mode Instructions
CodeMacro   BRKEM vector : Db
  DW      OFF0FH
EndM

DB      vector

; BCD String Arithmetic
CodeMacro   ADD4S
  DW      200FH
EndM

CodeMacro   ADD4S   dst:M, src:M
  NoSegfix ES, dst
  Segfix   src
  DW      200FH
EndM

CodeMacro   SUB4S
  DW      220FH
EndM

CodeMacro   SUB4S   dst:M, src:M
  NoSegfix ES, dst
  Segfix   src
  DW      220FH
EndM

CodeMacro   CMP4S
  DW      260FH
EndM

CodeMacro   CMP4S   dst:M, src:M
  NoSegfix ES, dst
  Segfix   src
  DW      260FH
EndM

; BCD Rotates
CodeMacro   ROL4   dst:Eb
  Segfix   dst
  DW      280FH
  ModRM   0, dst
EndM

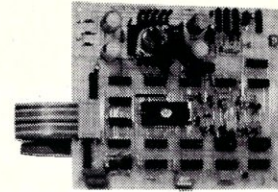
CodeMacro   ROR4   dst:Eb
  Segfix   dst
  DW      2A0FH
  ModRM   0, dst
EndM

$List

```

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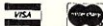
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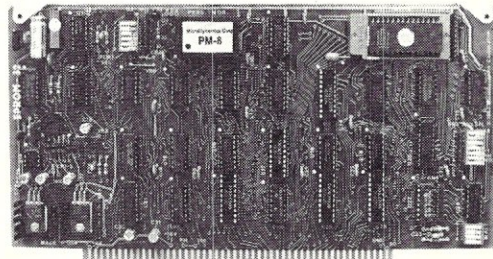


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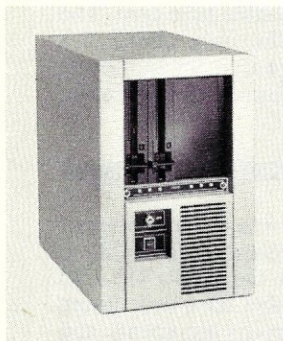
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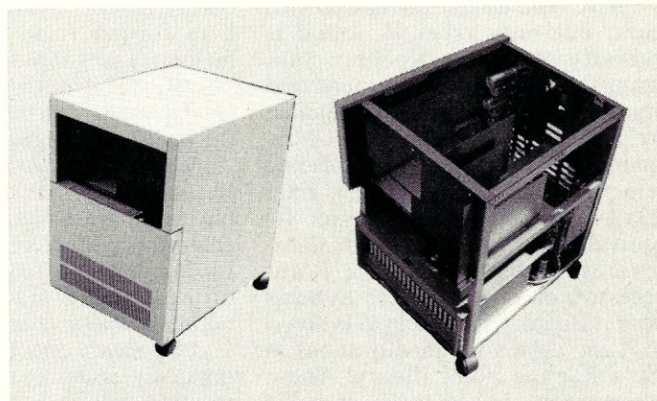
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# Faster Floating Point Math

by N. T. Carnevale

The Software Toolworks' C80 compiler has received high marks in several reviews for being a nearly complete implementation of C that compiles in a reasonable time to produce compact, fast integer code. It even has an optional float/long library that extends its arithmetic capabilities beyond the basic byte and integer data types.

However, the speed of floating point operations in most languages for 8-bit micros leaves something to be desired, and C80 is no exception. In a list of benchmark timings based on Bill Savage's program (Dr. Dobb's Journal #94 (Aug. 1984), pp. 110-114), C80 clocked in at 238 seconds on a 6MHz 8085, but BASIC 80 took only 175 seconds on a 5MHz 8085!

I have been using C80 for over two years, but only recently found it necessary to use its floating point arithmetic. Appalled that an interpreted language could outperform a compiled one, I decided to speed up C80's floating point operations by replacing them with routines to run the Intel 8231A floating point processor IC (equivalent to the Advanced Micro Devices Am9511 Floating Point Processor) on my CompuPro Systems Support Board. This article tells how I did it and details my modifications to C80's floating point library. These routines were written for Microsoft's M80, but they can be altered easily for use with Digital Research's RMAC or the assembler provided with C80. Throughout this article I will also try to give helpful suggestions for others who might want to add hardware floating point support to other compilers and languages.

## FLOATING POINT FORMATS

Unfortunately, there is no FPP for 8-bit systems that monitors the bus for data and commands destined for itself, responding automatically without specific intervention by the CPU.

## Speed Up A C Compiler's Math Operations Using A Math Coprocessor IC

Instead, the CPU must feed it the data and instructions and retrieve the results by ported or memory-mapped I/O. Any speed advantage that an FPP may have over software arithmetic can be wiped out by delays required to convert the data format from that used by a high-level language to its own internal format, feed it the data and commands, get the results, and then convert back to the high-level language's format.

C80 and the 8231A both represent floating point variables with four bytes, but there are some differences (see comments just before label C2AMD: in Listing 3). Both have a 24-bit two's complement mantissa that is normalized to a value between 0.5 and 1. C80 saves one bit of storage by implicitly assuming the high bit of the mantissa will be 1, so the 24th bit can be used to represent mantissa sign. The 8231A retains the high bit of the mantissa, and puts the mantissa sign bit in the exponent byte. This reduces the number of bits available for the exponent to seven, so the range of numbers that the 8231A can represent is  $2^{-64}$  to  $2^{+63}$ . The more efficient storage scheme used by C80 and many other languages lets them represent numbers from  $2^{-128}$  to  $2^{+127}$  with no loss of precision in the mantissa.

Despite this difference of range, the fundamental similarity of the formats meant that reasonably efficient routines

could be written to convert between them (see C2AMD: and AMD2C: in Listing 3). I first wrote these routines as functions, tested them for proper operation with a program that printed out the bit patterns for various floating point values before and after conversion. Listing 1 gives this program for the convenience of others who wish to adapt it to investigate the internal representation of floats in other versions of C, some of which do not provide such information in their documentation. Single precision floating point variables in Microsoft's FORTRAN 80, and single floats in Alcor's C, also occupy 32-bits. There is a hardware floating point library to use the 8231A with FORTRAN 80, and it might be possible to develop one for single floats in Alcor C. The 8232 (Am9512), which does both four and eight byte floating point arithmetic, might be a better choice for Alcor C, which also has a double float type. The 8232 would be the only choice for ECO-C, which uses an internal eight byte double float format in all floating point calculations.

## PASSING ARGUMENTS & RETURNING RESULTS

The next step was to write a set of routines to pass arguments from C80 to the FPP and return the result. The C80 manual gives a rather terse description of how floating point arguments and results are passed, and suggests that interested users examine the code that is produced to figure it out for themselves.

Which I did. The intrinsic float operations (add, subtract, multiply and divide) and the *extrinsic* functions (e.g. `sin()`, `sqrt()`, or user-defined functions) all return their result in registers BCDE, but there are important differences in how they receive arguments. The intrinsic operations are called with the first argument on the stack and the second in registers



BCDE. The library routines for these elementary operations remove the first argument from the stack and return the result in BCDE.

The extrinsic functions retrieve all arguments from the stack without disturbing the stack pointer. The stack pointer is still unchanged upon return, so the calling routine must remove the arguments from the stack to prevent stack overflow. Code to preserve and fix the stack is generated automatically when the C80 compiler processes C source code. It is up to the programmer to keep track of the stack pointer and restore it as needed when writing functions in assembly language.

Although the LGFLTLIB.ASM and FLOATLIB.ASM sources provided by the Software Toolworks are uncommented, they were invaluable for tracing what happened to arguments and function results. Few other compiled languages provide the source code for their libraries, but many produce assembly code that can give useful clues to internal data formats, the names or locations of entry points for important library routines, and what source code constructions produce the most efficient object code. Such access to assembly code also offers the possibility of hand-optimization of critical sections to improve speed and reduce storage requirements.

At this point, I was able to estimate the time required just to convert formats and pass data back and forth to the FPP. This process took more than 167 microseconds (usec), slow enough that it didn't seem worth the effort to replace the floating-point addition and subtraction routines. However, multiplication, division, and the other functions promised to be much faster with the FPP.

My next step was to write routines to use the FPP to duplicate but not replace C80's floating point operations. I wrote these for assembly with M80, following the general format produced by C80. Then I tested them with a program that stepped through a series of arguments, fed them to C80's original floating point library and to my special FPP routines, and compared the results to be sure they gave the same answers as their software counterparts.

## DISSECTING THE LIBRARY

Satisfied that no errors had crept in, I now had to decide how to replace the multiplication and division routines, and where to put the functions that were previously part of MATHLIB.C. This is when I became very grateful for two facts about C80: the relocatable floating point library was in Microsoft's REL format and could be

examined by LIB; source code for the floating point routines was provided, even though it was really intended for use with the Software Toolworks assembler.

Processing FLIBRARY.REL with LIB (/L option) identified its modules and their entry points. This revealed that the module that contained the floating point multiplication and division routines was called FLTLIB.

FLOATLIB.ASM includes the source for several modules. The source for FLTLIB ends with a RET just before the label f.stak:. I isolated what looked like the FLTLIB code from FLOATLIB, added a list of ENTRYs and EXTRNs as indicated by LIB's listing of FLIBRARY.REL, and inserted DSEG and CSEG to preserve the 15 byte data area revealed by LIB. I named this NUFLTLIB.MAC and assembled it with M80 using the /C option to produce NUFLTLIB.REL and NUFLTLIB.CRF.

The cross-referenced NUFLTLIB.PRN file generated from the CRF file by CREF80 showed that the floating-point multiplication section could be excised in toto - the only entry point that was referenced by other routines was at the label fmul:. However, the division routine had an entry point (div10:.) that might be called by something outside FLTLIB, so I decided not to tamper with the short section between div10: and fdiv:.

The task of modifying the floating point library would have been more difficult if the source code were not available. Some versions of C (e.g. Alcor) have a runtime package that contains all of the math routines and is linked as a complete unit into every compiled program. Alcor says they would provide information such as locations and lengths of the software math functions to help interested users implement hardware math routines.

## FLTLB - THE HARDWARE FLOATING POINT ROUTINES

I gave the hardware math module a different name than the original FLTLIB. This was accomplished with the TITLE pseudo-op (see Listing 2). The DSEG and CSEG pseudo-ops preserve data areas exactly as they were in the original, just in case they are referenced by some other part of the C80 library. The list of EXTRNs and ENTRYs was derived from LIB's output, as described above.

C80 uses a dispatch table to jump to the floating point addition, subtraction, multiplication and division routines. I replaced this with a simple JMP for multiplication and division, and commented out the two unused entries in the dispatch table located at ftab:

(Listing 3). Since the dispatcher now only has to decide between addition and subtraction, further simplification is possible, but this would produce only a small improvement of speed and storage.

The actual floating point routines replace two major blocks of code. The first block contained the software multiplication routines starting with label fmult3: and ending just before label pophrt:. I decided to put everything but the hardware floating point division routine in this area. The division routine replaces the original section that started with fdiv: and ended just before mul10:.. Listing 4 gives all the new code, plus the small portion between pophrt: and the old fdiv: that remains unchanged. I have not included the absolute value or polynomial functions (fabs() and F\_poly()) in this listing, although they are part of the MATHLIB. If you prefer to include these in your version of FLTLB, use C80 to generate the appropriate assembler code from the C source and patch the assembly code into your FLTLB before assembly.

I don't use the long data type much, but tests showed that it would be beneficial to replace the software long multiplication and division routines with hardware operations. C80 and the 8231A use the same four-byte format for longs, so this should be easy.

The new code includes routines to convert data formats, transfer data to and from the FPP, initiate the various operations, test when results are ready, and detect and handle errors. Two types of errors may occur. A software error results if C80 attempts to pass an argument that is too big or too small for the 8231A ( $< 2^{-64}$  or  $> 2^{63}$ ). A hardware error is generated by the FPP itself in case of arithmetic overflow, underflow, divide by zero, taking the log or square root of a negative number, or passing too large an argument to the exponential or inverse sine or cosine functions. If any one of these errors happens, the present code prints a message and exits to the operating system.

There are times when some hardware errors, such as underflow, could be handled more sensibly by returning a zero or some other value instead of aborting the program. Therefore I included a function fpmask() that can be used to set the error detection mask under program control. The default condition is to test for, and crash in case of, any hardware error. If any of the FPP error tests is disabled, it is up to the programmer to test for and handle such errors in a meaningful way. This might be done by writing a routine that would check the

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## **Cross reference table generated—**

## **Plain English Error Messages—**

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8086/88	199.50	750.00	99.50	99.50	199.50
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8044/51	199.50	500.00	199.50	199.50	199.50
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8096	199.50	500.00	199.50	199.50	199.50
68020	399.50	750.00	399.50	399.50	399.50
68000,08,10	299.50	750.00	299.50	299.50	299.50
6800,02,08	199.50	500.00	199.50	199.50	199.50
6801,03	199.50	500.00	199.50	199.50	199.50
6804	199.50	500.00	199.50	199.50	199.50
6805	199.50	500.00	199.50	199.50	199.50
6809	199.50	500.00	199.50	199.50	199.50
32000	399.50	750.00	399.50	399.50	399.50
COPS400	199.50	500.00	199.50	199.50	199.50
NSC800	199.50	500.00	199.50	199.50	199.50
6301	199.50	500.00	199.50	199.50	199.50
6501/11	199.50	500.00	199.50	199.50	199.50
6502	199.50	500.00	199.50	199.50	199.50
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status register immediately after any suspect operation, branching to an error-handling routine if an error occurs.

## RESULTS

These routines illustrate two major bottlenecks in the use of any hardware math device that is not a coprocessor. Both are related to data transfer between the CPU and the FPP. The first is format conversion, which takes a major toll: about 46usec per argument passed to the 8231, and 20usec to convert the result back to C80's format. The second bottleneck is the fact that the C80 compiler maintains intermediate results in the CPU's address space rather than leaving them in the FPP's stack. Aside from the time needed to pass and retrieve these results, this imposes extra overhead for needless format conversions. Short of rewriting the C80 compiler, the only way around this would be to modify FLTLB and manually revise critical portions of the 8080 code produced by C80 so that frequently used intermediate results stay in the FPP's stack until all floating point operations are complete.

Despite these shortcomings, the new floating point library is a definite improvement over the original. Savage's benchmark took only 16 seconds on a 4mHz Z80 with a 2mHz 8231A, producing a final result of 2327 (rounded off to the nearest integer - error 2E+2). This is faster than any other 8-bit machine running at 4mHz, and about 15 times faster than C80's software floating point library. The result is slightly more precise than the software arithmetic, and just as (im)precise as any other Am9511 or Intel 8231A FPP in the list—roughly comparable to single precision FORTRAN. This is not my first choice for processing ill-conditioned matrix equations, but it is more than adequate for less demanding applications, such as averaging and display transformations of data following A/D conversion.

*Ted Carnevale, an assistant professor of neurology at SUNY Stony Brook NY, is involved in research on information processing in neurons. His primary use of computers is in the implementation of the following algorithm:*

```
while not (broke or fired) {
do_experiments(time_and_money--);
write_papers(time_and_money--);
submit_research_proposals_to_get\
more_money(time_and_money--);
}
```

## LISTING 1

```
/* fpc.c—tests conversion to/from amd9511 fpp format */
#include fprintf.h
#include c80def.h

#define MESSAGE "\nFloating-point format conversion program"
#define DASHES "\n\n-----\n\n"

#define MAX 6 /* how many different values to feed
              to the format conversion routines */

/* replace the next two functions with
your own format conversion routines as needed */
extern long c2amd(); /* link .rel file containing these */
extern float amd2c(); /* to fpc.rel */

main()
{
    int i;
    static int sx=10;
    float x;
    static float dx=1.0;

    printf(MESSAGE);
    printf(DASHES);

    /* a geometric series of positive values */
    for (i = 0, x = 100.0; i<=MAX; x /= sx, i++) showbits(x);
    printf(DASHES);

    /* a geometric series of negative values */
    for (i = 0, x = -100.0; i<=MAX; x /= sx, i++) showbits(x);
    printf(DASHES);

    /* a linear series of positive and negative values */
    for (i = -MAX, x=(float)(-MAX); i<=MAX; x += dx, i++) showbits(x);
}

/* show bit patterns used by C80 and AMD FPP floating point formats
to represent the float n */
showbits(n)
float n;
{
    int i;
    union {
        float f;
        long l;
    } x,z; /* unions are easier to use here than pointers */
    long y;

    x.f=n;

    /* show C80's preconversion bit pattern */
    printf("\n\nx = %e,\t\tBCDE = ",x.f);
    prntlong(x.l);

    /* eliminate next few lines if you just want to check the format
used by your version of C */
    /* show AMD formatted data */
    y=c2amd(x.f);
    printf("\n\n\t\t\t\t\tAMD = ");
    prntlong(y);

    /* convert back to C80's format */
    z.f=amd2c(y);
    printf("\n\nz = %e,\t\tBCDE = ",z.f);
    prntlong(z.l);

} /* end of C80 -> AMD -> C80 format conversion test */

/* print bit pattern of a long, starting with the high-order bit
of the most significant byte, working down from left to right */
prntlong(k)
long k;
{
    int i;
    union {
        long l;
        char b[4];
    } datum;

    datum.l=k;
    for (i=3; i>=0; i--) {
        prntbyt(datum.b[i]);
        printf("\n");
    }
}

/* print the bit pattern for a byte from left to right,
high order bit first (does the dirty work for prntlong) */
prntbyte(i)
int i;
{
    int j;
    char bit;

    for (j=0x80; j>0; j>>1) {
        if (i & j) bit='1';
        else bit='0';
        printf("%c",bit);
    }
}
```



```

;Floating point formats
;C80 stores floats as:
; mantissa sign in C7
; mantissa = 24 bit two's complement in CDE,
;           with bit 23 assumed = 1.
; exponent is added to 128 (80H) and stored in B.
;           If the number is 0, B=0.
;FPP stores floats as:
; mantissa sign in B7
; mantissa = 24 bit two's complement in CDE,
;           with bit 23 = 1. However,
;           the value 0 is represented by BD=0.
; exponent sign in B6
; exponent in B5-B0 (only 6 bits).
;Call with value to convert in BD.
C2AMD:
MOV A,B           ; 4
ORA A             ; 4
JZ FPPZERO       ;10-B=0 implies x=0
;take care of register B
SUI 80H          ; 7--corrects exponent
;does exponent lie in FPP's range?
CPI 64           ; 7
JP EXPHI        ;10--exceeds 2^63
CPI -64          ; 7
JM EXPLO        ;10--smaller than 2^-64
;exponent ok, proceed
ANI 7FH         ; 7--mask out hi bit of B
MOV B,A         ; 4-- and save til later
MOV A,C         ; 4
ANI 80H         ; 7--isolate mantissa sign bit
ORA B           ; 4--fix mantissa sign bit for FPP
MOV B,A         ; 4--done with B
;take care of C
MVI A,80H       ; 7
ORA C           ; 4--set hi bit of C
MOV C,A         ; 4
JMP LOADFPP     ;10--put data in FPP
;114 t cycles @ 4MHz = 28.5usec
PPZERO:
XRA A           ;x=0
MOV C,A
MOV D,A
MOV E,A
;a short cut, time not calculated
;fall through to next routine
;
;Data transfer routine
;LOADFPP puts BD into fpp
LOADFPP:
MOV A,E         ; 4
OUT DREG        ;11
MOV A,D         ; 4
OUT DREG        ;11
MOV A,C         ; 4
OUT DREG        ;11
MOV A,B         ; 4
OUT DREG        ;11
RET             ;10
;70 t cycles = 17.5usec
;TOTAL TIME for C2AMD & LOADFPP = 46usec
;*****
;C2AMD found float to be out of range for FPP--warn & abort
EXPHI:
LXI D,HIMSG
JMP ERREXIT
EXPLO:
LXI D,LOMSG
ERREXIT:
CALL PRMSG
JMP BOOT       ;bail out!

```

```

;
;
HIMSG: DB CR,LF,'float --> FPP exponent overflow (> 2^63)$'
LOMSG: DB CR,LF,'float --> FPP exponent underflow (< 2^-64)$'
;*****
;
;
;FLOD1 gets 1 float from the stack, puts it into fpp,
;and DOES NOT restore stack. Called by "intrinsic"
;float arithmetic operations, e.g. fpmul and fpdiv.
FLOD1:
POP H           ;10--return addr for this block
SHLD RETADR    ;16
POP H           ;10--return addr for calling function
POP D           ;10
POP B           ;10--BD = argument
CALL C2AMD     ;17--convert format & load FPP
;
PUSH H         ;11--restore return address of calling function
LHLD RETADR    ;16--return to calling function
PCHL          ; 4-- without disturbing stack
;104 t cycles = 26usec, + 46 for C2AMD = 72usec
;*****
;
;FLOAD1 gets 1 float from the stack, puts it into fpp,
;and restores stack for c80. Called by "user-defined"
;functions, not by fpmul or fpdiv.
FLOAD1:
POP H           ;10--return addr for this block
SHLD RETADR    ;16
POP H           ;10--return addr for calling function
POP D           ;10
POP B           ;10--BD = argument
CALL C2AMD     ;17--convert format & load FPP
;fix stack for c80
PUSH H         ;11
PUSH H         ;11
PUSH H         ;11--restore return address of calling function
LHLD RETADR    ;16--return to calling function
PCHL          ; 4-- without disturbing stack
;126 t cycles = 31.5usec, + 46 for C2AMD = 77.5usec
;
;*****
;
;FLOAD2 gets 2 floats from the stack, puts them into fpp,
; and restores the stack for c80
FLOAD2:
POP H           ;10--return addr for this block
SHLD RETADR    ;16
POP H           ;10--return addr for calling function
POP D           ;10
POP B           ;10--BD = second argument
CALL C2AMD     ;17--convert format & load FPP
POP D           ;10
POP B           ;10--BD = first argument
CALL C2AMD     ;17
;fix stack for c80
PUSH H         ;11 x 5 = 55
PUSH H
PUSH H
PUSH H
PUSH H
PUSH H
;restore return address of calling function
LHLD RETADR    ;16--return to calling function
PCHL          ; 4-- without disturbing stack
;185 t cycles = 46.25usec, + 2 * 46 (for C2AMD) = 138.25usec
RETADR: DS 2    ;used by all FPP load routines
;*****
;
;
;fpmask() allows the user to specify which error bits
;are tested for error detection. The argument to fpmask

```

```

;becomes the ERRMASK that is ANDed with the status word
;to detect a hardware (FPP) error.
PUBLIC fpmask
fpmask: POP H          ;return address
        POP B          ;argument
        PUSH B         ;fix stack
        PUSH H
        MOV A,C        ;get the user-specified error mask
        ANI ERFBITS    ; and mask out all but the genuine error bits
        STA ERRTST+1
        RET
;*****
;
;FPP error handling routine
;print message according to what sort of error occurred
FPERR:  LXI D,EMSG0
        CALL PRMSG     ;print general message
        MOV C,A        ;save error code
        MVI B,MSGPTR-ETYPES ;# of codes to check
        LXI H,ETYPES  ;M=first code in the list
        LXI D,MSGPTR  ;(DE) = address that contains
                        ; location of message for first error code
ERCHEK: ANA M
        JMP ERMATCH
        MOV A,C        ;restore error code
        INX H         ;advance to next code and message
        INX D
        INX D
        DCR B
        JNZ ERCHEK   ;more codes to test
        ;should never fall through, but if it does, will print 'huh?'
;
ERMATCH: XCHG          ;(HL) holds address of error message
        MOV E,M
        INX H
        MOV D,M
        JMP ERREXIT
;
EMSG0:  DB CR,LF,LF,'FPP error: $'
EMSG1:  DB 'overflow$'
EMSG2:  DB 'underflow$'
EMSG3:  DB 'sqrt or log of negative number$'
EMSG4:  DB 'divide by 0$'
EMSG5:  DB 'argument of asin, acos, or exp too large$'
EMSGX:  DB 'huh?$' ;should never occur!
;
ETYPES: DB OVRFLO,UNRFLO,TOOBIG,NEGARG,DIVZER
MSGPTR: DW EMSG1,EMSG2,EMSG5,EMSG3,EMSG4,EMSGX
;*****
;
;Next come the hardware floating point routines themselves.
;The multiplication routine contains most of what the
;other routines use, so it is listed first.
PUBLIC fpmul
fpmul: ;Note: for fp multiply and divide,
        ;c80 passes the first arg in the stack, the second in BD.
        ;For the intrinsic multiply and divide operations,
        ;the calling program does NOT have to remove args
        ;from the stack upon return! This is quite different from
        ;the situation with user-defined functions.
        ;take 2nd arg from BD, convert to amd format, and pass to fpp
        CALL C2AMD    ;17
        ;take 1st arg from stack, convert format, and pass to fpp
        CALL FLD1    ;17
        ;send command, test for error, return with result in BD
        MVI A,FMUL   ;7
        ;fall through to DOIT-ERRTEST-GETIT-AMD2C

```

```

;
;DOIT-GETIT starts an FPP operation, tests for error,
;gets the result & converts to c80 format
;send command in A to FPP
DOIT:  OUT CREG      ;11—send command
WAIT:  IN CREG       ;10
        ORA A        ;4
        JM WAIT     ;10—until done
        ;11 + n*24 t cycles = 2.75 + 6n usec (X)
;A contains error code
ERRTEST: ANI ERFBITS ; 7—default = test all error bits
        JNZ FPERR  ;10—if error found, else fall through to GETIT
;
;get top of fpp's stack into BD
GETIT:  IN DRBG      ;10
        MOV B,A      ;4
        IN DRBG     ;10
        MOV C,A      ;4
        IN DRBG     ;10
        MOV D,A      ;4
        IN DRBG     ;10
        MOV E,A      ;4
;
;Fall through to AMD2C, which converts FPP format in BD
;to c80 float
;AMD2C is based on suggestions by J.Shook, Electronics Lab,
;Dept.of Chemistry, SUNY Stony Brook
AMD2C: MOV A,C        ;4
        ORA A        ;4
        JP C80ZERO  ;10—bit 7=0 implies value is 0
        ;take care of mantissa sign
        XRA B        ;4—complements bit 7 of B, among other things
        ANI 80H     ;7—mask out all the garbage
        XRA C        ;4—hi bit of C was 1 in AMD format, so this
        MOV C,A     ;4—sets the hi bit of C to mantissa sign
        ;take care of exponent sign
        MVI A,40H   ;7
        ANA B        ;4— is exponent negative?
        MOV A,B     ;4
        JZ POSEXP  ;10—no, set hi bit to 1 (add 128)
        ANI 7FH    ;7— yes, mask out hi bit
        MOV B,A     ;4
        RET        ;10
POSEXP: ORI 80H     ;set hi bit for positive exponent
        MOV B,A
        RET
;format conversion delay identical whether exponent is + or -
C80ZERO: XRA A
        MOV B,A
        RET
;short cut—no time calculated
;
;(DOIT-ERRTEST-GETIT-AMD2C takes 156 t cycles
;= 39usec, + X (for operation))
;
;41 t cycles = 10.25usec, + 46 (C2AMD) + 72 (FLD1) + 39
;+ X (DOIT) = 167.25 + X usec
;
;float sqrt(x) float x;
PUBLIC sqrt
sqrt:  CALL FLOAD1
        MVI A,FSQRT
        JMP DOIT
;float sin(x) float x;
PUBLIC sin

```

```

sin:      CALL FLOAD1
          MVI A,FSIN
          JMP DOIT

;float cos(x) float x;
          PUBLIC cos
cos:      CALL FLOAD1
          MVI A,FCOS
          JMP DOIT

;float tan(x) float x;
          PUBLIC tan
tan:      CALL FLOAD1
          MVI A,FTAN
          JMP DOIT

;float asin(x) float x; /* arc sin in radians */
          PUBLIC asin
asin:     CALL FLOAD1
          MVI A,FASIN
          JMP DOIT

;float acos(x) float x;
          PUBLIC acos
acos:     CALL FLOAD1
          MVI A,FACOS
          JMP DOIT

;float atan(x) float x;
          PUBLIC atan
atan:     CALL FLOAD1
          MVI A,FATAN
          JMP DOIT

;float log(x) float x; /* log10 */
          PUBLIC log
log:      CALL FLOAD1
          MVI A,FLOG
          JMP DOIT

;float ln(x) float x; /* log e */
          PUBLIC ln
ln:       CALL FLOAD1
          MVI A,FLN
          JMP DOIT

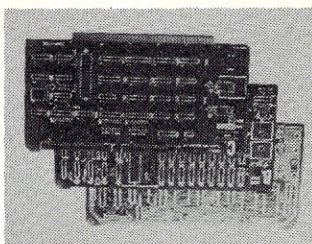
;float exp(x) float x;
          PUBLIC exp
exp:      CALL FLOAD1
          MVI A,PEXP
          JMP DOIT

;float pwr(x,y) float x,y; /* x to the yth power */
          PUBLIC pwr
pwr:      CALL FLOAD2
          MVI A,XCHF
          OUT CREG          ;11—send command
          IN CREG           ;10
          ORA A             ;4
          JM PWAIT         ;10—until done
          MVI A,FPWR
          JMP DOIT

;<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<
;briefly back to the original source for fltlib—
;
pophrt: POP    H
          RET

```

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```

;since divl0.: is called by an external routine, I left it alone.
divl0.: CALL    pushf
          LXI    B,8420H
          LXI    D,0000H
          CALL   movfr.
fdivt:   POP    B
          POP    D

;
;<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<<
;the fdiv: routine is replaced by fpdiv:, and muldiv: is not needed
;
fpdiv:   PUBLIC fpdiv
          ;take 2nd arg from BD, convert to amd format, and pass to fpp
          CALL C2AMD ;17
          ;take 1st arg from stack, convert format, and pass to fpp
          CALL FLD1  ;17
          ;swap fpp's A and B registers
          MVI A,XCHF ;7
          OUT CREG  ;11—send command
          IN CREG   ;10
          ORA A     ;4
          JM DWAIT  ;10—until done
          ;send command, test for error, return with result in BD
          MVI A,FDIV ;7
          JMP DOIT  ;10
          ;takes 169.75usec + X plus delay for register swap

;END OF MODIFICATIONS TO FLTILIB.MAC<<<<<<<<<<<<<<<<<<<<<<<<
;back to the original code again at mul10.:
mul10.: CALL   movfr.

```



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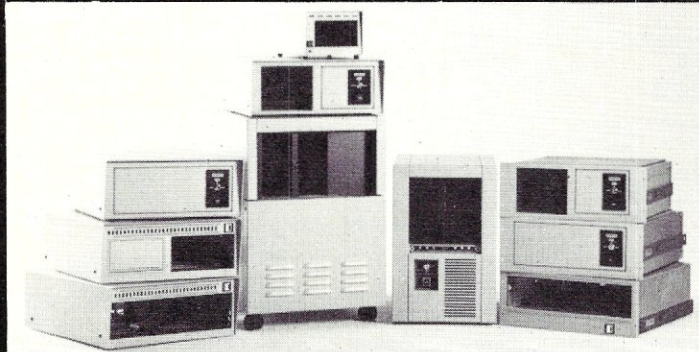
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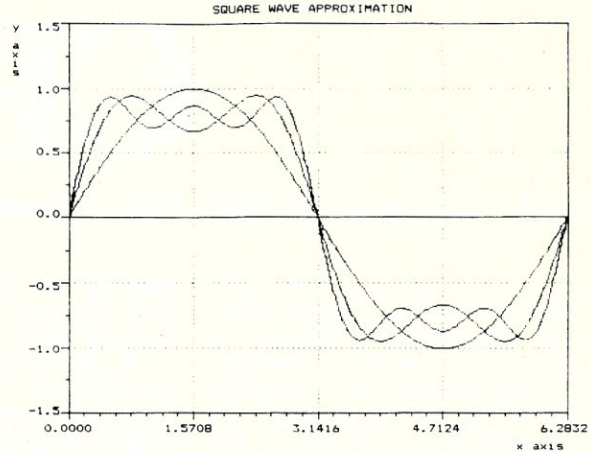
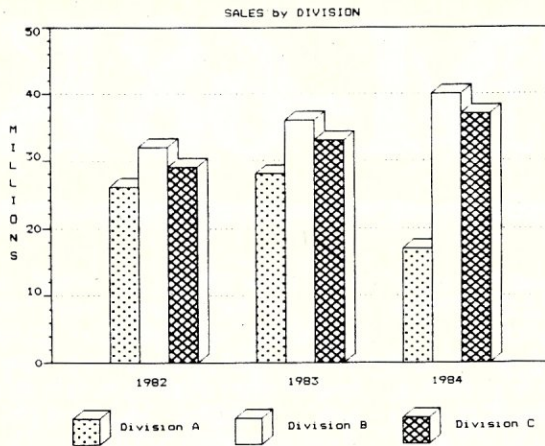
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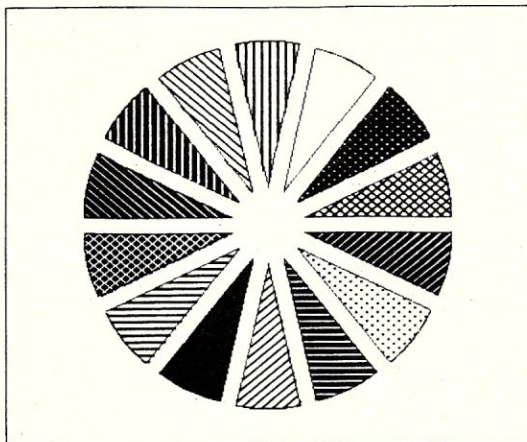
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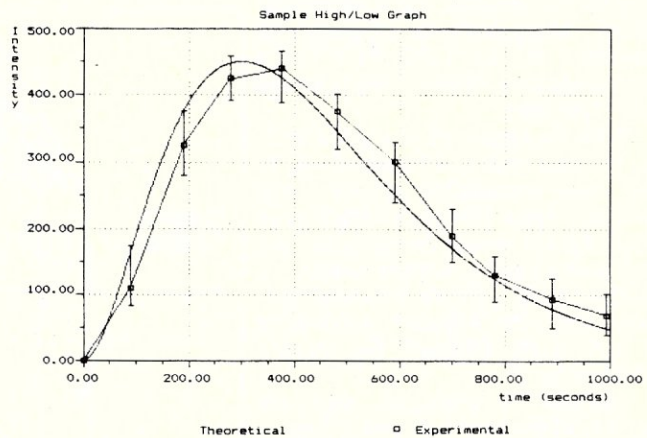
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# Bringing Up CP/M-68K

by J.L. Calaway & Ben Hill, Jr.

A few months ago, we were developing an idea for a new product. As the investigation proceeded, it became apparent that the real-time processing requirements would exceed the capabilities of an 8-bit processor by a wide margin. It was time to look into the world of 16 bits.

We currently manufacture equipment based on the S-100 bus and it was decided not to change buses in mid-stream. We knew we needed speed and most of the 16-bit processors seemed to have plenty. Programming ease and flexibility loomed large in our decision, as well as hardware multiply and divide capability along with plenty of room for expansion. These basic requirements can be met by several 16-bit processors, but the Motorola 68000 was given the edge for its extended, linear addressing facility, along with its programming similarity to the DEC PDP-11, a minicomputer with which we have had past experience.

With the choice of processor settled, the next order of business was to find some compatible hardware and software. Since CompuPro markets an S-100 68000 processor card and we have used a number of their boards, we felt this would solve the hardware problem nicely. For software, we decided to go with Digital Research's CP/M-68K.

Anxious to press on after the delivery of the hardware and software, we now devoted our attention toward finding a Z80/68000 cross-assembler to work with our existing Z80 computer. Avocet Systems and Quelo have such software. We opted for the Quelo version, but the Avocet cross-assembler should work as well.

## GETTING THE SYSTEM TOGETHER

A swift appraisal of the Digital Research documentation disclosed that the BIOS listing required the use of a Tarbell double-density disk-controller! Oh, no time like the present to replace our old, single-density model. A panic call was placed to our dealer (pusher?), Patio Computer, in Los Angeles. For-

tunately for us, they rounded up a controller in record time. Yea Patio! Now we could begin work in earnest.

A thorough reading of all the documentation was the next item of business. The new CP/M-68K manuals are several light years ahead of the old, turgid, CP/M-80 manuals. Its a good thing, too, because it turned out that we would get no additional help from Digital Research. We tried to contact them several times during the painful (and expensive) start-up process. Each time, the customer service desk promised to have someone call back on the problem, but nobody ever did.

We used the sample assembly language, BIOS listing in the the CP/M-68K manual as a guide. Unfortunately, while the mnemonics and the

logic in the listings are correct, in our copy of the manual, some of the assembled op-codes were incorrect. Things like this are not especially helpful when implementing something new, complex and unfamiliar. However, things could be worse - and they quickly got that way. The operating manual provided for the 68000 CPU was typical CompuPro documentation - exasperatingly brief. At one point, in response to our call for technical assistance, we were informed by CompuPro that they would not give us any assistance. We would only be able to get the information second-hand, from the distributor! The distributor didn't know the answer, of course. In contrast, we are happy to report, the people at Quelo not only

		RECORD MARK	RECORD TYPE	RECORD LENGTH	LOAD ADDRESS	DATA	CHECKSUM
(a)	Motorola S-FORMAT	S	01	10	000406	428640FA4200430040FA40FA40FA43E7	67
(b)	INTEL HEX FORMAT	3A	10	002A	00	428640FA4200430040FA40FA40FA43E7	67

Figure 1

Motorola S-record format (a), is similar to, but not interchangeable with, INTEL hex format (b). It has a variable size load-address which may be 2, 4 or 6 bytes depending on data type. The type is a hex number (0 - 9), depending on whether record is for file housekeeping, actual program data or an end-of-file record. INTEL format has a fixed,

2-byte load-address, and currently, all record types are 00. Data portions of both records are 8-bit words represented by two ASCII HEX characters. The checksum is negative sum of all the bytes after the record mark. Thus, ignoring carries, the sum of all the bytes plus the checksum equals zero.

answered several questions about their cross-assembler's operation by phone, but have twice updated the assembler, sending along a new disk at no cost, each time. Yea Quelo!

Further reading of the CP/M documentation disclosed the fact that CP/M-68K is configured to run with the Motorola EXORmacs development system for the 68000. Since we didn't have one of these systems, another approach had to be used. CP/M for the 68000 is similar in concept to the old 8080 CP/M. You have the CCP (Command Control Processor) that handles commands from the system terminal, the BDOS (Basic Disk Operating System) that processes all the disk activity, and the BIOS (Basic Input/Output System) that handles all the interfacing with the printer, terminal, disks and other peripherals.

### MODIFYING THE SOFTWARE

The CP/M68K system file (SR400.SYS) contains the CCP and the BDOS. This file is a Motorola S-record format file and contains no BIOS. Since the BIOS is hardware dependent, it must be written to fit the system in use. A listing of a sample BIOS is provided by Digital Research in an assembly language file called ERGBIOS.S. This listing can be used as a starting point for creating your own. The Motorola S-file (figure 1a), is an all ASCII file. Everything in the file is in hex code. It serves the same purpose as the familiar INTEL hex format (figure 1b), and allowed us to read the file data.

It was obvious at this point that we would have to do a bit of work on the software to accomplish the following:

- Modify the CP/M BIOS to work with the hardware and cross-assembler.
- Work out a method of downloading the HEX S-files from the 8" standard CP/M release disk into the 68000's system.
- Provide a method of displaying and changing the 68000's memory.
- Provide a method of jumping to and executing code stored in the 68000 memory to check out the BIOS modifications and start the system running.

Modifying the BIOS was not too difficult. We had a cross-assembler and a good bit of experience with CP/M BIOS requirements from earlier systems, so it was a matter of copying the CP/M supplied sample into our Z-80 system in order to modify some of the lines of code to work with our 68000 hardware. We did find that some of the listed code in the sample BIOS wouldn't assemble with the Quelo cross-assembler, but this was simply a syntax problem and a minor wording change here and there

readily converted the code so it would assemble properly.

A few Input/Output addresses required changing in order to resolve the difference between the way the CP/M-68K BIOS and the CompuPro board sees I/O addresses. The Godbout CPU uses the top 64K of memory for I/O addresses. There are no IN or OUT instructions in the 68000. Instead, it sees everything as being memory-mapped. For example, address of FF0001H is converted to port 1 by the CPU board. The top 64K address of 'FF' identifies it as a peripheral access address/instruction. The sample BIOS, on the other hand, expected to see an address of FFFF01H for the same port, so it was necessary to change the listed BIOS address to FF0001H. All the disk-access ports were changed as well as the console data and status ports.

Another BIOS change necessary was an adjustment in the step-rate value loaded into the disk controller board. The disk I/O board uses the bus clock for timing. If this clock is too fast, the disk stepping motor won't be able to keep up. The step-rate is a software-loaded variable that may be changed to get proper stepping-motor action. The Tarbell disk-controller manual lists the byte that has to be changed in the BIOS to adjust the rate.

The final change was to insert the address of the Command Control Processor (\_\_\_ccp), into the BIOS. This is the address location the system will jump to on a warm-boot command. The BIOS label is 'WBOOT:', and the required \_\_\_ccp address is supplied with the CP/M-68K release notes. After the BIOS changes were thought to be correct, it was assembled to give us a hex S-file ready to be down-loaded into the 68000 system.

### DEVELOPING A 68000 SYSTEM MONITOR

We needed a simple monitor that we could burn into a prom that would allow us to download, display, change and execute programs and data. We looked about for just such a program, but couldn't find it, so we decided to do our own. The results are shown in listing 1. This simple tool is an invaluable aid when struggling with programming at the machine level in an unfamiliar system. The listing is heavily commented and should prove interesting to those of you who haven't had a chance to see much 68000 assembly language software. In our development system, we had the convenience of two terminals. One for the Z-80 and the other dedicated to the 68000. If you haven't the luxury of two terminals, the alternate, shown in figure 2, works as well.

There are three commands in the monitor, S (Substitute), L (Load), G (Go). While there is virtually no error checking in the program, it does the job. Once the monitor has been burned in a PROM and inserted into the 68000 system it is ready for use.

To change the data at memory location 1000H (hex), for example, type: S1000 <RETURN>

The display will show:

00001000 XX where XX is hex data at that location.

Enter the desired data change in hex, followed by a <RETURN>. The new data will be entered at the displayed memory location. For no change, just hit <RETURN>. To return to the monitor command mode, type a PERIOD (.). The monitor prompt, (also a PERIOD), will re-appear.

To start a program at location 1000H type:

G1000 <RETURN>

The program will jump to that location and execute. In essence, the 'G' command acts as a jump-to-subroutine. If the code at the jump location ends with a return instruction, control returns to the monitor and the prompt reappears. The 'G' command is great for checking things like altered BIOS routines. To download an S-format hex file, enter the 'L' command. This starts the 68000 monitor program running. The Z-80 BIOS is altered slightly so that PIP can call PUNCH (or any unused IOBYTE label) to output characters to the RS-232 port connected to the 68000 (figure 2). The monitor program loops while waiting for data to appear on this line. When it does, the monitor strips off the non-data portion of the incoming S-file, converts it to binary machine-code and loads it into consecutive memory locations. The command sequence is:

L <RETURN> on 68000 system.

PIP PUN:=ERGBIOS.HEX <RETURN> on Z-80 system.

This command sequence downloads the file ERGBIOS.HEX byte-by-byte into the 68000. At the conclusion of the loading process, control returns to the monitor as indicated by the monitor prompt.

### BIOS TEST PROGRAM

With our monitor working we tested our altered BIOS. To make that little job as simple as possible, we wrote a short program called BTEST (see listing 2) to give us some test data for the BIOS. This program allows the loading of data in registers D0, D1 or D2, jumping to a segment of code in the BIOS and returning with the data stored in a memory location labelled 'RESULT' (00201CH). The process allows section-by-section testing and lets you know if the program is work-



LISTING 1

```

*****
*
* A MONITOR FOR THE MOTOROLA 68000 MICROPROCESSOR TO ENABLE
* LOADING PROGRAMS, CHANGING DATA VALUES, AND BEGIN EXECUTION
* AT ANY MEMORY LOCATION. 68000 ASSEMBLY LANGUAGE LISTING
*
* Copyright (C) 1985, Jack L. Calaway. All rights reserved.
*
*****
*
* EQUATES
*
DATA EQU.L $0FF0010 * CONSOLE UART DATA
STATUS EQU.L $0FF0011 * CONSOLE UART STATUS
SDATA EQU.L $0FF0020 * DOWN LOAD UART DATA
SSTAT EQU.L $0FF0021 * DOWN LOAD UART STATUS
STACK EQU.L $0000300 * STACK BELOW CP/M-68K

ORG $0FD0000

*
* START UP CODE FOR GODBOUOT CPU
* ON HARDWARE RESET, PROMS ON CPU BOARD ARE GLOBAL
*
DC.L $8 * FIRST INSTRUCTION ADDRESS
DC.L STACK * INITIAL STACK VALUE
JSR.L INIT * SWITCH PROMS TO REAL ADDRESS

*
* DO INITIALIZING TASKS
*
INIT:
MOVEA.L #STACK,A7 * SET STACK POINTER

BSR CRLF * OUTPUT A CR/LF PAIR
MOVEQ #04D,DO * THEN LOAD AND OUTPUT
BSR OUTCH * THE MONITOR SIGN-ON
MOVEQ #036,DO * MESSAGE: M68K
BSR OUTCH
MOVEQ #038,DO
BSR OUTCH
MOVEQ #04B,DO
BSR OUTCH

*
* BEGIN PROCESSING COMMANDS. THE PROGRAM
* RETURNS TO THIS POINT BETWEEN COMMANDS
*
START:
MOVEA.L #STACK,A7 * RESET STACK POINTER
BSR CRLF * NEXT LINE
MOVEQ #02E,DO * OUTPUT THE MONITOR
BSR OUTCH * PROMPT CHARACTER:
BSR INCH * GET A COMMAND
CMPI.B #0D,DO * IGNORE CARRIAGE RETURN
BEQ.S START * ECHO THE CHARACTER
BSR OUTCH * 'S' = SUBSTITUTE
CMPI.B #053,DO * NOT 'S', TRY NEXT COMMAND
BNE.S START1 * ON 'S' GO TO SUBSTITUTE
BSR SUBST * ROUTINE.
BSR CRLF * BACK TO START
BRA.S START

START1:
CMPI.B #047,DO * IF COMMAND IS A 'G',
BNE.S START2 * JUMP TO GOTO AND BEGIN
BSR GOTO * EXECUTION
BSR CRLF
BRA.S START

START2:
CMPI.B #04C,DO * ON 'L' COMMAND, JUMP
BNE.S START * TO THE LOAD ROUTINE
BSR LOAD
BSR CRLF
BRA.S START * NONE OF THE ABOVE

*****
*
* THIS ROUTINE WILL JUMP TO INPUT ADDRESS AND BEGIN EXECUTION
*
*****
GOTO:
BSR INADR * GET THE ADDRESS
JMP (AO) * JUMP TO IT

```

```

*****
*
* LOAD
* THIS ROUTINE WILL DOWN LOAD AN S-FILE INTO THE 68000 MEMORY
*
*****
LOAD:
BSR CRLF * WE ARE HERE

*
* FIND THE S-RECORD HEADER
*
LOAD1:
CLR.B D4 * D4=LENGTH FLAG
BSR GCHR * GET CHARACTER
CMPI.B #053,DO * IS IT AN 'S'?
BNE.S LOAD1 * IF NOT, TRY AGAIN
BSR GCHR
CMPI.B #030,DO * CHARACTER EQUALS ZERO
BEQ.S LOAD1 * TRY AGAIN IF SO
CMPI.B #039,DO * CHECK FOR FILE END, (9)
BEQ.S LOADX * DONE IF SO
CMPI.B #032,DO * 4, OR 6 BYTES OF ADDRESS
BEQ.S LOAD3
ADDQ.B #001,D4 * PUT 1 IN LENGTH FLAG

*
* GET BYTE COUNT
*
LOAD3:
BSR GHEX * GET RECORD LENGTH
MOVE.B DO,D2 * SAVE IN COUNTER
SUBI.B #03,D2 * ADJUST COUNT, AND TEST
TST.B D4 * AND TEST FOR LONG OR SHORT ADDRESS
BNE.S LOAD4 * SHORT
SUBQ.B #001,D2 * LONG, SUBTRACT ONE MORE

*
* GET LOAD ADDRESS OF RECORD
*
LOAD4:
BSR GADR

*
* NOW GET FILE DATA
*
LOAD2:
BSR GHEX * GET BYTE OF DATA
MOVE.B DO,(AO)+ * STORE IN MEMORY
SUBQ.B #001,D2 * DECREMENT COUNT
BNE.S LOAD2 * CONTINUE
BRA.S LOAD1 * SKIP CHECKSUM

LOADX:
RTS * RETURN FOR NEW COMMAND

*
* GET TWO ASCII CHARACTERS FROM SERIAL PORT
* AND CONVERT TO ONE BINARY BYTE
* RETURNS THE DATA IN THE DO REGISTER
* D1 IS CLOBBERED
*
GHEX:
CLR.B D1 * CLEAR TEMPORARY
JSR CAHEX * GET HIGH NIBBLE
ASL.B #4,D1 * SHIFT TEMPORARY LEFT
OR.B DO,D1 * 'OR' WITH D1
JSR CAHEX * GET LOW NIBBLE
ASL.B #4,D1 * POSITION HIGH NIBBLE
OR D1,DO * COMBINE LOW AND HIGH
ANDI.L #0000FF,DO
RTS

*
* CONVERT ASCII TO HEX
*
CAHEX:
BSR GCHR * GET CHARACTER
SUBI.B #030,DO * REMOVE ASCII
CMPI.B #00A,DO * A-F?
BLT.S CAHEX1 * NO
SUBI.B #007,DO * YES, SUBTRACT 7

CAHEX1:
RTS

*
* GET LOAD ADDRESS FROM SERIAL PORT
* RETURNS WITH THE ADDRESS IN REGISTER AO
* WORKS JUST LIKE GHEX, BUT DOES 2 OR 3 BYTES
* RATHER THAN JUST ONE
*

```

```

GADR: CLR.L D3          * TEMPORARY=0
      BSR GHEX
      ASL.L #08,D3     * MAKE ROOM FOR NIBBLE
      OR.L DO,D3
      BSR GHEX
      ASL.L #08,D3
      OR.L DO,D3
      TST.B D4         * LONG OR SHORT ADDRESS?
      BNE.S GADRX     * SHORT
      BSR GHEX
      ASL.L #08,D3     * LAST BYTE
      OR.L DO,D3

```

```

GADRX: MOVE.L D3,A0
      RTS

```

```

*
* GET SERIAL CHAR
*

```

```

GCHR: ANDI.B #02,SSTAT * ANY WAITING?
      BEQ.S GCHR       * NO
      MOVE.B SDATA,DO * GET IT
      ANDI.B #07F,DO  * STRIP HIGH BIT
      RTS

```

```

*****
*
*          SUBSTITUTE
* THIS ROUTINE WILL SUBSTITUTE DATA AT ANY MEMORY LOCATION *
*
*****

```

```

SUBST: BSR INADR       * GET ADDRESS
      BSR CRLF        * CLEAN UP

```

```

SUBST1: BSR CRLF        * FOR NEW LINE
        BSR PADR      * PRINT ADDRESS
        MOVEQ #020,DO * SPACE
        BSR OUTCH
        MOVE.B (AO),DO
        BSR PHEX      * PRINT CURRENT DATA
        MOVEQ #020,DO
        BSR OUTCH     * SPACE
        BSR INCH      * GET KEYBOARD CHAR
        CMPI.B #0D,DO * NEXT ADDRESS?
        BEQ.S SUBST4  * YES
        BSR OUTCH     * ECHO
        CMPI.B #02E,DO * PERIOD EQUAL DONE?
        BEQ.S SUBSTX  * YES, EXIT

```

```

*
* INPUT NEW BYTE OF DATA
*

```

```

      CLR.B D1          * CLEAR REGISTER

```

```

*
* CONVERT 1 OR 2 ASCII CHARACTER
* TO BINARY BYTE
*

```

```

SUBST2: SUBI.B #030,DO * STRIP ASCII
        CMPI.B #0A,DO
        BLT.S SUBST3
        SUBI.B #07,DO

```

```

SUBST3: ANDI.L #0000000F,DO
        ASL.L #04,D1
        OR.L DO,D1
        BSR INCH      * NEXT
        CMPI.B #0D,DO * DONE?
        BEQ.S SUBST5  * YES
        BSR OUTCH     * NO
        BRA.S SUBST2

```

```

SUBST5: MOVE.B D1,(AO) * STORE NEW DATA

```

```

SUBST4: ADDQ.L #001,AO * NEXT MEMORY ADDRESS
        BRA.S SUBST1

```

```

SUBSTX: RTS          * FINI

```

```

*
* INPUT ADDRESS FROM CONSOLE
* EXIT WITH AO=ADDRESS
*

```

```

INADR: CLR.L D1          * TEMPORARY = 0

```

```

INADR1: BSR.S INCH      * GET ASCII CHARACTER
        CMPI.B #0D,DO * CR=END?
        BEQ.S INADRX   * YES
        BSR OUTCH     * SHOW
        SUBI.B #030,DO * STRIP ASCII
        CMPI.B #0A,DO * 0-9
        BLT.S INADR2
        SUBI.B #07,DO * FOR A-F

```

```

INADR2: ANDI.L #0000000F,DO * CLEAR
        ASL.L #04,D1 * POSITION HIGH NIBBLE
        OR.L DO,D1 * MAKE ONE BYTE FROM TWO NIBBLES
        BRA.S INADR1

```

```

INADRX: MOVE.L D1,A0 * ADDRESS TO ADDRESS REGISTER
      RTS

```

```

*
* PRINT ADDRESS
* (AO)=DATA
*

```

```

PADR: MOVEQ #04,D2 * PRINT FOUR BYTES
      MOVE.L A0,D1 * COPY ADDRESS

```

```

PADR1: ROL.L #08,D1 * SHIFT BYTES
        MOVE.B D1,DO
        ANDI.B #0FF,DO
        BSR.S PHEX * PRINT BYTE
        SUBQ.B #001,D2 * COUNTER -1
        BNE.S PADR1 * MORE TO PRINT
        RTS

```

```

*
* PRINT HEX
* DO=DATA

```

```

PHEX: MOVE.B DO,-(SP) * SAVE LOW NIBBLE
      ROR.B #04,DO * PRINT HIGH NIBBLE FIRST
      BSR.S PHEX1
      MOVE.B (SP)+,DO * GET LOW NIBBLE BACK

```

```

PHEX1: ANDI.B #0F,DO * CLEAR LOW NIBBLE
        CMP.B #0A,DO * A-F?
        BLT.S PHEX2 * NO
        ADD.B #07,DO * YES - CORRECT

```

```

PHEX2: ADD.B #030,DO * MAKE ASCII
        BSR.S OUTCH
        RTS

```

```

*
* CRLF TO CONSOLE
*

```

```

CRLF: MOVEQ #0D,DO * CR
      BSR.S OUTCH
      MOVEQ #0A,DO * LF

```

```

*
* PRINT CHAR IN REG DO TO CONSOLE
*

```

```

OUTCH: ANDI.B #01,STATUS * BUSY?
        BEQ.S OUTCH * YES
        MOVE.B DO,DATA * SEND
        RTS

```

```

*
* INPUT CHAR FROM CONSOLE
*

```

```

INCH: ANDI.B #02,STATUS * WAITING
      BEQ.S INCH * NO
      MOVE.B DATA,DO * GET IT
      ANDI.B #07F,DO * CLEAR HIGH BIT
      RTS

```

```

*****
*
*          T H A T ' S   A L L   F O L K S
*
*****

```

END



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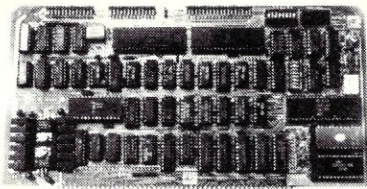
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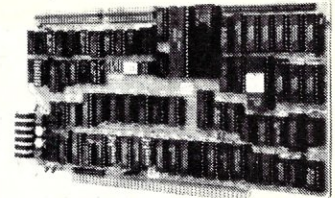


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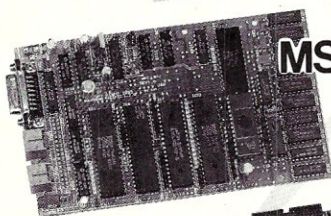
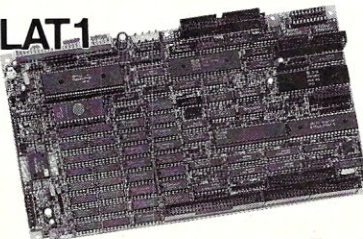
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Text Control System Multiple versions of text files—source code, letters, spread sheets, contracts, any text. Keeps record of changes allowing any version to be recovered. Twenty revisions normally only require three times the disk storage space. [CP/M-80, 83; MP/M 816; CCP/M-816; PCDOS/MSDOS, Macintosh, Lisa]		The Original—Still Fastest! Ultrafast C compiler for CP/M-80 with symbolic debugger, full library and run time source code. Large public domain library of programs available.	
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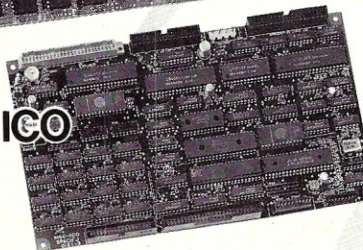
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## MSC-MTC

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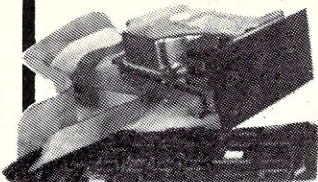
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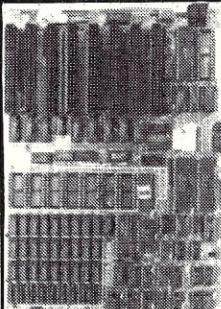
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# The Peak

# 68K8-CP

by Dave Hardy & Ken Jackson

Peak Electronics' 68K8-CP Coprocessor card offers the S-100 user a fast and painless way to upgrade to the world of high-speed, high-powered multi-processing. Using the MC68008 (8-bit bus version of the 68000) processor at 8 or 10MHz, the IEEE-696 compatible 68K8-CP can be installed in just about ANY S-100 system in less than five minutes, and will coexist with that system's current processor.

Software provided with the 68K8-CP allows the user to switch between the system's original processor and the 68000 with just a simple command, and full source for the board's firmware is available for those users who prefer to "roll their own" operating systems.

## THE HARDWARE

The 68K8-CP is a standard single-height S-100 board, well made, solder-masked, silk-screened, and fully socketed. A spare DIP socket is available for those who wish to perform any circuit modifications. All options are either switch or jumper selectable, so no soldering is necessary for user configuration.

Naturally, the 68K8-CP is fully IEEE-696 compatible (after all, Peak's president, Don Pannell, is one of the authors of the IEEE-696 standard), including the ability to do full bus arbitration and act as an IEEE-696 temporary bus master.

Communication between the master processor and the 68K8-CP is performed via two S-100 ports that provide the ability for the two processors to exchange commands and status information. This is really the key to the operation of the 68K8-CP. Each processor can talk to the other via this simple I/O interface for commands and status, but the 68K8-CP actually takes over the S-100 bus (via its TMA ability) to perform data transfers, or use other S-100 bus resources. Because the

## An easy-to-install 68000 S-100 Co-processor card

IEEE-696 standard allows for up to 16 processors to exist on a single S-100 bus in this manner, it is actually possible for up to 16 68K8-CP's to live in a single S-100 frame.

Our 68K8-CP came "out of the box" with 8K of ROM and 128K of RAM on board, and with an 8MHz clock, although other configurations are available, as mentioned above. The documentation provided gives information on configuring the board for several different types of EPROMS and RAMS, and even gives information for reconfiguring the addressing PLA. Interestingly, in spite of the 8 or 10MHz clock speed, no wait

### Features:

- Works as a temporary bus master with full bus arbitration and TMA ability

- MC68008 8 or 10MHz CPU

- Fully IEEE-696 compatible

- 128K on-board RAM, expandable to 512K

- 8K on-board EPROM, expandable to 128K

- Two on-board serial ports (requires daughter boards)

- On-board parallel printer port and sense switch

- Polled or interrupt-driven port communication with master processor (used only to S-100 I/O ports)

- Eleven on-board interrupts

- On-board timer

- Easy to configure for most S-100 systems

states are needed for any of the on-board RAM or EPROM.

The serial I/O, timer, and on-board interrupt handler are all contained in the same versatile IC, an MC 68681 DUART, which requires only the addition of RS-232 or current-loop driver (daughter) boards, if serial I/O from the 68K8-CP is desired.

The parallel printer port is actually just a simple latched output port with strobe and acknowledge lines. The input port at the same address serves as the sense switch input that is used at power-up to read configuration information into the 68K8-CP.

## THE SOFTWARE

The 68K8-CP is currently available with software to allow the user to boot directly from CP/M 2.2 into CP/M 68K, although a proficient 68000 programmer could program the board to do most anything else, since it is basically an S-100 peripheral device. In fact, the manual gives several ideas for alternate uses of the 68K8-CP, including a numeric processor, and a high-speed data buffer. Although they were not ready at the time of this writing, 68K8-CP firmware is also available for use as a printer buffer and a RAM disk.

We were impressed with the implementation of CP/M-68K, especially due to the fact that the CP/M-68K system could be loaded and executed from CP/M 2.2 with just a single command. Eight single-density 8" standard CP/M format disks are provided with the 68K8-CP, along with a demo disk that contains some simple "C" programs and a benchmark program. (Because the 68K8-CP uses the host system's disk drivers after it boots up, it can read any disk that the host system can read, so transferring data files from CP/M-80 to CP/M 68K requires no additional work at all.)

Disk #1 is the CP/M 68K boot disk,

which contains all of the files necessary to run CP/M 68K, along with the files "CPM68K.COM", and "RETURN.68K," which are used to boot CP/M 68K from CP/M-80 and to return to CP/M-80 from CP/M 68K. All of the usual CP/M utilities are present with CP/M 68K, like STAT, DDT, ASM, etc., along with a few new ones. Not surprisingly, the BIOS is written in "C."

## DOCUMENTATION

The 68K8-CP comes in a ring-binder containing four separate parts: the Introduction, the Hardware manual, the Software manual, and the Firmware manual.

The introduction section comes with two very important pieces of information. First, it lists the factory-shipped configuration and serial number of the 68K8-CP. Second, and most importantly, it contains a one-page mini-manual called "How to bring up your new 68K8-CP card in 5 minutes." We tried it, and it works, except that it actually takes only about 3 minutes if you have already removed the cover from your S-100 machine.

The Hardware manual is a complete little book about the 68K8-CP, including an overview of the entire board, precise explanations about how the board works and how to configure it, appendices, an index, and complete schematics. Also included are instructions on how to set up the 68K8-CP for use in older non-IEEE-696 S-100 machines.

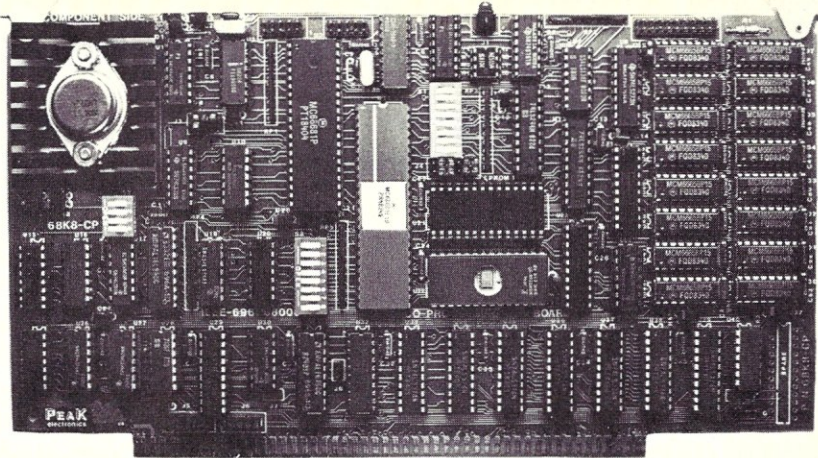
The Software manual is only about 10 pages long (any source listings provided are on the floppy disks), and briefly covers how to use the CPM68K.COM program and how to set up a system configuration file.

The Firmware manual was not yet available at the time of this review.

## INSTALLATION

In most cases, installation of the 68K8-CP should take only a few minutes. We installed the board in more than a dozen different S-100 machines with virtually no trouble at all. As shipped from the factory, the board is set up to use S-100 I/O ports 0C0H and 0C1H for data and status exchange, but it is easily reconfigurable to any other port addresses by just changing a few switch settings and editing the system configuration file to indicate the new port addresses.

Our technical staff took great delight in plugging the 68K8-CP into every S-100 machine it could find, including everything from dinosaur IMSAI's to multi-processor TurboDos-based frames, and never had



ANY problems at all. The 68K8-CP contains nine user configurable jumpers and three user configurable switches, although it can usually be installed using factory settings. The user configurable jumpers are:

J1 - Wait States for RAM, EPROM or I/O

J2 - Type of parallel I/O IC used (74LS374 or 74LS273)

J3 - Off-board RAM paging size

J4 - EPROM type (2764, 27128, 27256, 27512)

J5 & J6 - S-100 Vectored Interrupt number (V10-V17, NMI\*, INT\*)

J7 - Ground/CPU DSB for use with older front-panel machines

J8 - pSTVAL\* transfer disable (for old non-IEEE-696 machines)

J9 - sM1 disable (for old non-IEEE-696 machines)

The user configurable switches are:

S1 - 8-bit sense switch (used to determine serial I/O speed at boot-up)

S2 - 4-Bit TMA priority number (needed for bus arbitration)

S3 - S-100 I/O address

## TESTS

Our usual benchmark tests were of little use with the 68K8-CP, since they are meant primarily for testing other processors in stand-alone configurations. However, we did duplicate the manufacturer's tests (using the Sieve of Eratosthenes "C" language benchmark provided), and the results were:

68K8-CP @ 8MHz: 32 seconds

Z80 @ 4MHz: 141 seconds

These results are largely meaningless, except they do demonstrate the 68000's increased efficiency. The 68K8-CP could yield some very attractive time savings in a system that could off-load number-crunching from a Z80 master processor.

## CONCLUSION

The 68K8-CP is a fast and easy way

to expand an existing S-100 system into a multiprocessing machine, or at least a painless way to bring up a powerful 68000-based system. Although the 68K8-CP is currently only available with CP/M 68K, other operating systems (like UNIX) are almost certainly going to be available in the future.

The price of the 68K8-CP with an 8MHz CPU and 128K of RAM is \$995. The 10MHz version with 512K of RAM costs \$1545, and various other configurations are available. CP/M 68K is available for \$350, and source code for the 68K8-CP programs is available for an additional \$50 with the purchase of a board.

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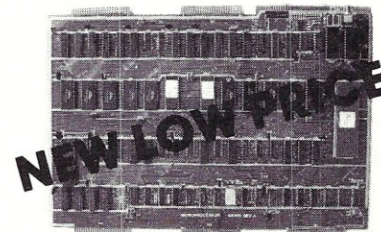
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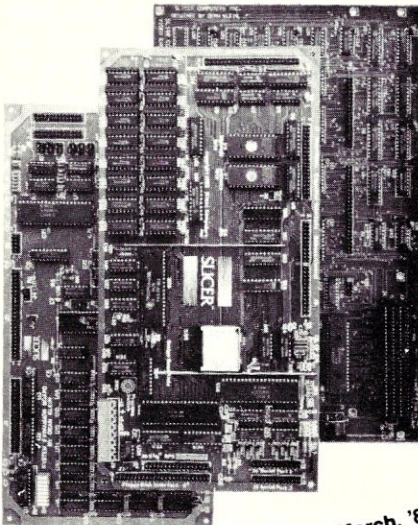
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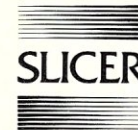
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# Program Interfacing To MS-DOS

by William G. Wong

UNIX-style file functions were first included in DOS V2 along with the hierarchical directory structure. Although these tools provide a more powerful and flexible environment the functions are actually easier to use than the CP/M-style file functions. For this reason, new applications tend to use the UNIX-style file functions exclusively.

I will first discuss what a subdirectory is for those unfamiliar with their use, then deal with file names and handles since they differ significantly from the CP/M-style file function parameters. The file functions themselves are covered after this.

Another unique feature of the UNIX-style file functions is the ability to redirect the data transfer of a particular file to another file including built-in files such as the console. This process will be covered in the section on file redirection.

Finally, a simple file copy program example will be presented to show how simple it is to use the UNIX-style file functions at the assembly language level.

## SUBDIRECTORIES & DEVICES

One of the more advanced features found in UNIX is the hierarchical file system. It allows files to be organized in a multi-level tree structure. The basic hierarchical file structure has been incorporated into all versions of DOS except V1.

The top-level collection of files on a disk is called a directory. Files in the directory may be data files or a special file called a subdirectory. The subdirectory works and looks just like the main directory. Subdirectories may also contain data files or subdirectory files. Subdirectories always contain at least two special files named '.' and '..'. The first is the current subdirectory and the second is a reference to the parent directory. The latter allows access to files in higher level directories.

File names and subdirectory names still retain the CP/M-style syntax with an eight character file name and an optional three character file type. The file name and type are separated by a period. For example: NAME.TYP or A-NAME. A file name alone refers to a

## Part IV - Basic File Access

file in the current subdirectory. Like the current disk, the current subdirectory allows simple file names to be used without having to explicitly include drive or path information.

A path is a list of subdirectories. This is presented in text form as the file names of the subdirectories separated by a backslash, '\'. The last name in the list is the reference file. Some examples are:

```
\SOURCE\LIST.ASM
\SYSTEM\FORMAT.COM
\LEVEL.1\LEVEL.2\LEVEL.3\DATA
C:\LEVEL.2\LEVEL.3\DATA
..\PARENT.DAT
\A-FILE
```

The path name can be viewed as directions on how a file is to be found and the current subdirectory information as preliminary search information. A current subdirectory is associated with each drive. The current subdirectory information is used only if the first character of the path is not a backslash, otherwise, the search is started from the main directory (on the current disk, if none is specified). The last example listed above (\A-FILE) shows how a file in the main directory is referenced while in a subdirectory.

Subdirectories could, in theory, be created ad infinitum. However, DOS does restrict a path name to 64 characters. This translates to 30 levels of subdirectories if single character subdirectory file names are used and 4 levels if full size file names are used at each level.

Special file names have been delegated to devices because the UNIX-style file functions allow devices to be treated as files. These names may be used in the file open function. The following table lists device names and descriptions.

Device	Description
CCN	Console/Display
AUX	Same as CCNM
CCM1	First serial port
CCM2	Second serial port
PRN	Same as LPT1
LPT1	First printer port
LPT2	Second printer port
NUL	Always end of file on input Throws away output

## FILE NAMES & HANDLES

The CP/M style File Control Block (FCB) contained a file name which was parsed into a special format. Extending this mode of operation would be tedious at best. Instead, the UNIX-style file functions use zero terminated strings and a 16 bit value called a file handle. A program no longer needs to keep an FCB around for each open file.

A file name is stored as an ASCII string with the same syntax for a path name, as described in the previous section. It must not contain any spaces and is followed by (terminated) with a NULL character (a decimal 0). An assembly language constant would be defined as:

```
db '\LEVEL.1\LEVEL.2\DATA',0
```

A pointer to this type of string is normally passed in the DS:DX register pair with the UNIX-style file functions. The file open and create functions return a file handle as a result if a file exists or is created. This handle is then used in subsequent operations such as read, write, and close. The file name string area can be changed after a file handle is acquired since it is not used by DOS unless, of course, the file name is used in a subsequent operation.

A set of predefined handles is provided by DOS. These files are open by default when a program starts and may be used with the read and write functions by using the handle value specified in the following table:

Handle	Description
0	Standard input device
1	Standard output device
2	Standard error device
3	Standard auxiliary device
4	Standard printer device

## UNIX-STYLE FILE FUNCTIONS

The UNIX-style file functions return their result in the AX register. The carry bit is set if an error has



occurred. Pointers to file names are passed as parameters in the DS:DX register pair. Additional parameters are passed the specified name. Otherwise, it truncates an existing file to a length of zero. Read and write access is always enabled for a newly created file.

```
MOV DX,OFFSET FNAME ; DS:DX := file name
MOV CX,0             ; CX := file attrib
MOV AH,3CH           ; AH := create opcode
INT 21H              ; create a file
```

```
FNAME: DB '\SUB-DIR\FNAME',0
```

The file open operation works in a similar fashion except the file attribute parameter is not required but the file access method is passed in the AL register. The file access method may be any of the following:

Access Method	Description
0	Read-only
1	Write-only
2	Read and write

Here is an example of the file open function.

```
MOV DX,OFFSET FNAME ; DS:DX := file name
MOV AX,3D02H        ; AH := open opcode
                    ; AL := r/w access
INT 21H              ; open a file
```

There are four operations which can be done using the file handle returned by the create or open functions. These are: closing a file, reading from the file, writing to the file, and changing the value of the file's read/write pointer.

The close operation takes an open file handle in the BX register and an opcode of 3E hex in the AH register. All buffers associated with the file are written to disk.

The parameters for read and write operations are:

Register	Description
AH	Opcode: 3FH = read 40H = write
BX	File handle
CX	Buffer size in bytes
DS:DX	Buffer address

The number of bytes transferred is returned in the AX register. This value will be less than or equal to the buffer size. A value less than the buffer size on a write indicates an error. On a read, it indicates the end of a file has been reached. On character devices it indicates a partial record. For example, a keyboard input file returns one line at a time.

All file data transfers occur from the current file position which is initially 0 for the start of the file. The position is adjusted by the number of bytes transferred by a read or write operation. Random access to data in a file is done using the file seek function. This function should be called before a read or write operation. The parameters and results for the seek function are:

#### Parameters

Register	Description
AH	42H, seek opcode
AL	Seek method 0 = from beginning of file 1 = from current position 2 = from end of file
BX	File handle
CX:DX	Offset in bytes (CX is the most significant part)

#### Results

Register	Description
DX:AX	New file position (DX is the most significant part)

The most commonly used operations are movement to the start or end of the file. It can also be used to move forward or backward from the current file position allowing access of the next or previous record. The function can also be used to determine the current file position by using method 1 with an offset of 0.

The remaining functions deal with maintenance of files contained within a directory. The first two functions are used to get the names of files within a directory. These functions used the Disk Transfer Area (DTA) used with the CP/M-style functions. The set DTA function must be used before the two UNIX-style file functions are used. The first function is used to find the initial file. The address of the file name string is passed in the DS:DX registers and the search file attribute is passed in the CX register. The latter is the same as the attribute search byte used in the corresponding CP/M-style file function. The file name string may contain wildcard characters (\* and ?) in the file name portion. The DTA is filled with the following information if a matching file is found.

DTA Offset	Description
0-14H	Reserved by DOS
15H	File attribute
16H-17H	File time stamp
18H-19H	File date stamp
1AH-1DH	File size
	(least significant byte first)
1EH-2BH	File name

The file name in the DTA is a zero terminated string containing the name of the first file which matches the path given as the parameter. It does not contain the path or drive names.

The subsequent file function is used to find additional file names which are in the directory selected by the initial search path. The opcode value is 4F hex and it requires no parameters. The results are the same as the initial function. The DTA used by the first function should be selected. Subsequent file names which match are placed into the DTA file name area. The file names should be used (copied) before doing subsequent search

operations. Listing 1 shows a simple example of a directory search program which collects all the matching file names in the buffer FNBUF. The file names are zero terminated and the end of the list is marked by a zero length string.

Changing a file's attributes after it is created is done using the following code:

```
MOV DX,OFFSET FNAME ; DS:DX := string addr
MOV CX,0             ; CX := attrib
MOV AL,1             ; AL := set attrib
MOV AH,43H           ; AH := set opcode
INT 21H              ; set file attrib
```

A file's current attribute can be returned in the CX register by changing the AL register to 0 instead of 1. The value in the CX register before the INT 21H is ignored. See the previous article for a description of the file attribute byte.

A read-only file cannot be deleted. Use the set file attribute function first to enable reading and writing to a file. Then use the following code to delete the file.

```
MOV DX,OFFSET FNAME ; DS:DX := string index
MOV AH,41H           ; AH := delete opcode
INT 21H              ; delete file
```

The file name may contain a drive and path name but not wildcard characters (\* or ?). This function only works with data files. See the first part of this section to see how subdirectories are deleted.

Renaming a file is almost as easy as deleting one except that some additional rules must be followed. First, the strings containing the old name and the new name must have the same drive specification. Do not explicitly use drive A: in one name and drive B: in the other. Also, do not explicitly use drive A: in one name and specify no drive in the other when the current disk is not A:. Second, all subdirectories listed in the old and new file names must exist. No directory creation is performed.

Files may be moved from one subdirectory to another. This is the same as copying the file and deleting the source but it is much quicker. As mentioned before, files cannot be renamed across disks.

```
OLD: DB 'OLD.NAM', 0
NEW: DB 'NEW.NAM', 0
```

```
MOV DX,OFFSET OLD   ; DS:DX := old name
MOV AX,DS
MOV ES,AX
MOV DI,OFFSET NEW   ; ES:DI := new name
MOV AH,56H          ; AH := rename opcode
INT 21H              ; rename file
```

Finally, there is the matter of the file time and date stamps. DOS keeps track of these values and initializes them when the file is created. The values can be examined using the

directory search functions or the values can be returned using the following code.

```
MOV DX,OFFSET FNAME;DS:DX := string index
MOV AH,57H          ;AH := stamp opcode
MOV AL,0            ;AL := get opcode
INT 21H            ;get time/date stamp
```

The time and date stamps are returned in the CX and DX registers respectively. These values are the same as described in the previous article except the bytes are reversed. That is, CH and DH contain the least significant portion of the stamp.

## FILE REDIRECTION

One very useful operation which can be performed using the UNIX-style file functions, but not the CP/M-style file functions, is redirection. This allows a program to change where data is transferred even though a specific routine uses a predefined file. For example, the standard output device is normally attached to the console. Redirection allows this to be changed to the printer or a disk file.

Two functions are provided by DOS to support the redirection feature. One creates a duplicate file handle given a previously opened file handle. The other forces one file handle to refer to another.

The duplicate file handle function takes the open file handle in the BX register and returns a duplicate in the AX register assuming the additional file does not exceed the file open limit. Both handles may be closed independent of the other. However, the file read/write position is the same for both files. Moving the file position using one file changes it for the other file. The following is an example of the code used to make a duplicate file handle.

```
HANDLE: DW 0 ; place open handle here

MOV BX,HANDLE ; BX := open file handle
MOV AH,45H    ; AH := duplicate opcode
INT 21H      ; AX := duplicate handle
```

Although this function is useful in creating a file which can be closed twice (once via each handle). It is most often used to keep a copy of a file so the duplicate handle can be used with the redirection facility.

The redirection file function requires two open file handles. The second file is closed and first file handle is duplicated such that the second file handle is the duplicate. The duplicate follows the same restrictions as duplicates created using the previous function. The following example shows how the standard output can be directed to the printer.

```
MOV BX,4 ; BX := printer handle
MOV AH,45H ; AH := duplicate opcode
INT 21H ; AX := duplicate handle
MOV BX,AX ; BX := a printer handle
MOV CX,1 ; CX := standard output
MOV AH,46H ; AH := redirect opcode
INT 21H ; use printer for output
```

Redirection is not restricted to device files. Either file handle may refer to a device file or a disk file.

## FILE COPY EXAMPLE

A simple file copy program is shown in listing 2. This uses constant file names and creates a new file with the default attribute settings. The error result is not specific, either the file copies or it does not. It uses the file create function so any existing destination file is removed.

More sophisticated error handling,

programmable file names, and status output can be added using functions listed in this and previous articles.

## SUMMARY

The UNIX-style file functions are an obvious improvement over the CP/M-style file functions in power and ease of use both from the programmers and users point of view. The UNIX-style file functions also provide redirection facilities which cannot be duplicated with the CP/M-style file functions.

Subdirectories can be used to organize a large disk into meaningful sections. The UNIX-style file handles and variable length data records also simplifies programming.

### LISTING 1: DIRECTORY SEARCH

```
SFNAME: DB 'C:\SYSTEM\*.*', 0 ; search name
FNBUF: DB 8096 DUP (?) ; name buffer

; Setup loop parameters
; Assumes data is in the DS segment

MOV DX,OFFSET SFNAME
MOV AX,DS
MOV ES,AX
MOV DI,OFFSET FNBUF
MOV CX,0

; DS:DX = search string address
; ES:DI = file name buffer
; CX = search attribute

PUSH ES ; save file buffer index
PUSH DI
PUSH DS ; save string index
PUSH DX
MOV AX,CS ; set local DTA
MOV DS,AX
MOV DX,OFFSET SDTA
MOV AH,1AH
INT 21H
POP DX
POP DS ; DS:DX := string index
MOV AH,4EH ; AH := search opcode
INT 21H ; search for first name
POP DI
POP ES ; ES:DI := buffer index
LOOP: JC ENDCLOOP ; skip if no file found
MOV SI,OFFSET SRESULT
CLOOP: LODSB ; AL := character
STOSB ; add to string
TEST AL,0 ; check for end of string
JNZ CLOOP ; loop until done
PUSH ES ; save buffer index
PUSH DI ; AH := search next opcode
MOV AH,4FH ; AH := search next opcode
INT 21H ; search for next name
POP DI
POP ES ; ES:DI := buffer address
JMP LOOP ; loop until all found

ENDCLOOP: MOV AL,0 ; AL := terminator
STOSB ; add to buffer
RET

SDTA: DB 21 DUP (0) ; reserved area
SATTRIBUTE: DB 0 ; file attribute
STIME: DW 0 ; file time stamp
SDATE: DW 0 ; file date stamp
SSIZE: DW 0 ; file size
SSIZEL: DW 0 ; most significant part
SRESULT: DB 13 DUP (0) ; file name
```

LISTING 2: FILE COPY PROGRAM

```

; Copy file program
; Open files

MOV DX,OFFSET SOURCE      ; DS:DX := file name index
MOV AH,3DH                ; AH := open file opcode
INT 21H                   ; AX := file handle
MOV DX,OFFSET ESOURCE     ; DS:DX := error message
JC PRINT                  ; skip if open failed
PUSH AX                   ; save source handle
MOV DX,OFFSET DEST        ; DS:DX := file name index
MOV AH,3CH                ; AH := create file opcode
INT 21H                   ; AX := file handle
POP BX                    ; BX := source handle
JC ECREATE                ; skip if create failed
MOV CX,AX                 ; CX := destination handle

LOOP:
PUSH BX                   ; save handles
PUSH CX
MOV DX,OFFSET BUFFER      ; DS:DX := buffer address
MOV CX,512                ; CX := buffer size
MOV AH,3FH                ; AH := read opcode
INT 21H                   ; read from source file
POP CX                    ; restore handles
POP BX
JC BAD READ              ; skip if error
TEST AX,0                 ; zero := end of file
JZ DONE                   ; skip if end of file
PUSH AX                   ; save buffer size
PUSH BX                   ; save handles
PUSH CX
MOV BX,CX                 ; BX := destination handle
MOV DX,OFFSET BUFFER      ; DS:DX := buffer address
MOV CX,AX                 ; CX := bytes to write
MOV AH,40H                ; AH := write opcode
INT 21H                   ; write buffer to file
POP CX                    ; restore handles
POP BX
POP DX                    ; DX := read size
JC BAD WRITE             ; skip if error
CMP AX,DX                 ; zero := write successful
JNE BAD WRITE            ; skip if disk full
JMP LOOP                  ; loop until file copied

; Close files and show transfer complete
DONE:
CALL CLOSE                ; close files
MOV DX,OFFSET MDONE       ; DS:DX := done message
PRINT:                    ; DS:DX = string index
MOV AH,9                  ; AH := print string opcode
INT 21H                   ; print string
RET

; Close source (BX) and destination (CX) files
CLOSE:
PUSH CX                   ; save destination handle
MOV AH,3EH                ; AH := close opcode
INT 21H                   ; close source file
POP BX                    ; BX := destination handle
MOV AH,3EH                ; AH := close opcode
INT 21H                   ; close destination handle
RET

; Handle destination create error
ECREATE:
MOV AH,3EH                ; AH := close opcode
INT 21H                   ; close source file
MOV DX,EDEST              ; DS:DX := error message
JMP PRINT                 ; print error message

; Handle error while reading source file
BAD_READ:
CALL CLOSE                ; close both files
MOV DX,OFFSET EREAD       ; DS:DX := error message
JMP PRINT                 ; print error and exit

; Handle error while writing source file
BAD_WRITE:
CALL CLOSE                ; close both files
MOV DX,OFFSET EWRITE      ; DS:DX := error message
JMP PRINT                 ; print error and exit

; File names (In data segment)
SOURCE: DB 'SOURCE',0
DEST:   DB 'DEST',0

; Data buffer for copy operation
BUFFER: DB 512 DUP (?)

; Error and status messages
ESOURCE: DB 'Cannot open source file.$'
EDEST:   DB 'Cannot create destination file.$'
ERead:   DB 'Error reading source file.$'
EWRITE:  DB 'Error writing destination file.$'
MDONE:   DB 'Copy done.$'

```



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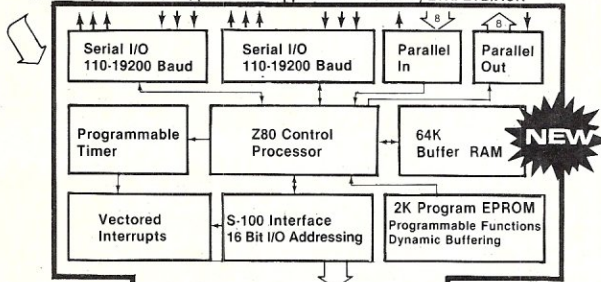


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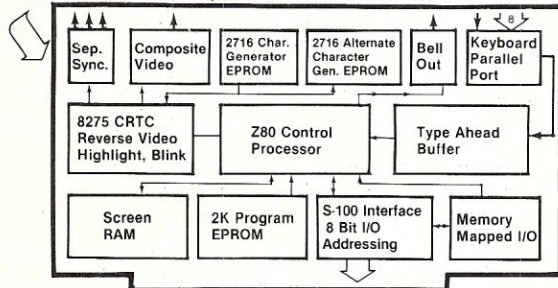
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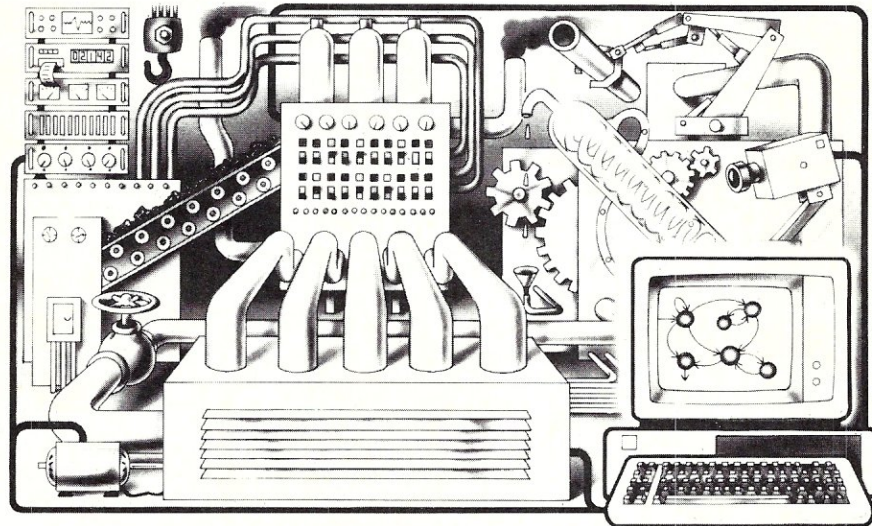
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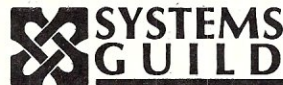
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# The Scientific Computer User

by A.G.W. Cameron

## Editor's Note

We expect "The Scientific User" to be a regular column in Micro/Systems Journal appearing in every other issue. Initial feedback from reader study we are conducting indicates to us that a very large percentage of our readers are scientists and engineers using computer systems in their work. Hence, we feel there will be a great deal of interest in this column. We would appreciate hearing reader reactions to the column. And, we assure the author would also like to hear from readers.

In discussions of computer workstations, the computer-related press has made the most of the business-oriented aspects of the uses of IBM PCs and similar machines. Spreadsheets and data bases and word processors. Bar graphs and pie charts. Links to mainframes. This is not the world of the scientist and the engineer. Nevertheless, the scientist and engineer have much to be thankful for in these developments. They have made the PC workstation affordable for other uses.

Technical people have been working with mainframes and minicomputers for quite a long time now, time-sharing number crunching and data analysis and whatnot. Recently very powerful resources have been put at the disposal of individuals, particularly for such applications as CAD-CAM. Some aspect of system sharing has usually remained, but names such as Apollo and Sun and Masscomp denote very capable workstations, costing typically \$10,000 to \$20,000 for each such station. I shall not be dealing with these, other than as prototypes toward which the IBM PC style of workstation can aspire.

I am a theoretical astrophysicist, and I have been interested for some time in transferring all of my scientific activities to workstations at a lower level of sophistication, the \$2,000 to \$5,000 range represented by IBM PCs and their clones and emulators. The performance of hardware and software that is particularly useful to me in this endeavor has been rapidly improving, and will continue to do so, although most of it is not nearly as well publicised as business-oriented items. This seems to be a useful time to take

## A Look At Scientific Workstations

stock of where we are and where we are going.

### PROCESSING SPEED

Most technical people want to crunch numbers in some form. A fairly common phenomenon recently has been the University departmental DEC VAX 11/780, which I will henceforth simply call a VAX. It is a time-shared resource. At one time at the Center for Astrophysics, when we had only one VAX to handle all our computing, we held the world's record for the number of terminals tied to ports on this VAX, well over 100. I hardly need award you a prize for guessing what response times were like in the middle of the afternoon. Now there are two VAXes tied together, which helps a little, and soon there will be lots of DEC Microvax II's around (a small machine of similar performance costing in the range \$20,000 to \$40,000). So I will use the CPU speed of the VAX with floating point accelerator as a basis for comparison with microcomputer floating point computation speeds.

Some benchmark speed comparisons which have been made at the Center for Astrophysics by those with IBM PCs have shown that the PC runs close to ten percent of the speed of the VAX, using the 8087 and Microsoft Fortran. This was a highly cost effective number in favor of the PC until recently, but DEC has managed to scramble back onto this new cost-performance curve with the Microvax II. I had hoped for a large improvement in computation speed with the advent of the IBM AT. Indeed, the AT proved capable of moving bytes around (a typical business use) at about three times the rate of the PC. But it is a computational disgrace. Benchmarks carried out by Avram Tetewsky of Draper Labs have shown that for number-crunching intensive jobs the IBM XT and AT compute at the same speed! The reasons appear to be the

following. The XT uses the Intel 8088 and 8087 running at 4.77 megahertz with an 8-bit bus. The AT uses the Intel 286 with a 16-bit bus, allowing it to move bytes around twice as fast per clock cycle; it uses a faster clock, and it performs CPU functions in fewer clock cycles than the 8088 or 8086. The problem lies with the 287 numeric coprocessor. This is divided into two parts, a communications part running at the same 6 megahertz clock speed as the 286, and a 4 megahertz computation part that is not enhanced over the 8087. So what advantage the AT gains in communication speed is lost in a slower computation speed.

The lesson for the technical person interested in fast computation is clear. For the near term, it is better to enhance the speed of the PC or look-alike than to invest in an AT. Following this logic, a few months ago I invested in a Number Smasher board from Microway. This runs at 9.54 megahertz (twice the PC clock rate), and it uses on-board 8086 and 8087 chips that have been designed for 8 megahertz and tested at the slightly higher speed. It has an on-board 16-bit bus into which up to 640 kilobytes of memory can be plugged. This board plugs into the 8088 and 8087 sockets on the PC mother board and interacts with all other hardware services through the regular 8-bit bus. With this board I find that I can crunch numbers at 25 percent of the VAX speed.

For certain specialized problems, the PC technical person can do still better by using array processor insert boards. These achieve a faster computational throughput by using pipeline techniques and a faster numeric processor. However, so far these are very limited by 32-bit floating point arithmetic, and I have not been personally interested in them. For more general-purpose computations we must await the (presumably soon-to-be announced) 64-bit array processors using very fast Weitek numeric coprocessor chips.

However, it is already apparent that the Motorola 68020 CPU teamed with the Weitek coprocessor can strongly outperform the VAX. I am indebted to Steve Ward of the Center for Astrophysics engineering staff for giving me the following preliminary benchmark numbers. For a double

precision floating multiply, the VAX with floating point accelerator takes 3.40 microseconds. The 68881 (the Motorola numeric coprocessor for the 68020) takes 4.00 microseconds at 16.67 megahertz and 5.33 microseconds at 12.5 megahertz, so it is slower than the VAX. The National Semiconductor 32081 (coprocessor for the 32016) takes 6.20 microseconds at 10 megahertz and 7.75 microseconds at 8 megahertz. According to trade journal reports, the Weitek 1164+1165 numeric coprocessor chip set takes 0.60 microseconds! This chip set clearly has a very promising future.

Is this the road for future upgrades by the PC workstation user? Does this mean a totally new personal computer architecture or will we get these Weitek chips as parts of insert boards for PCs? In that case what will the software situation be? Or will the IBM commitment to the Intel line mean that we should expect to use the Intel 386 and 387 chips and to migrate our present software base? The answers to these questions may not be clear but the existence of the questions suggests that the individual desktop workstation will continue a rapid evolution in capability.

#### STORAGE

There are two types of storage of vital interest to the workstation user, RAM and permanent storage.

The business PC user has been demanding larger and larger spreadsheets and data bases, and this has spurred several important technical developments. The 640 kilobyte limitation of DOS, which once seemed much more than adequate, has lately been seen as a serious straightjacket. For a while the solution seemed to be to go to the 286 chip, which can address 16 megabytes, but not when it is running DOS. If this were to be the solution, then we would all migrate to XENIX as an operating system. But the large installed base of PCs has brought forward an alternative solution, and since the processing enhancements described above at least temporarily make the PC superior to the AT as a hardware base, it is possible that the new memory developments will maintain DOS as a viable alternative for some considerable time.

The recent announcement of a new proposed hardware and software standard for bank switching of memory by Lotus jointly with Intel is of considerable interest to the scientific workstation user, because many of the Fortran programs that he may have been using on mainframes exceed the 640 kilobyte limit. The Intel

AboveBoard will have many clones and variants which will bring multimegabyte memory resources to our disposal, once our language compilers and linkers have been brought up-to-date to use them. However, I am aware of other technical developments which are in progress, and it may be premature to conclude that the AboveBoard implementation of memory management will turn out to be the best for the scientific workstation user.

The 360 kilobyte floppy disk remains a useful medium of backup storage and program and data exchange, but it is seriously cramping the style of the workstation user who

develops big programs. For example, Microsoft Fortran 3.2 creates intermediate compiler files that are serious memory hogs, leading to a lot of floppy shuffling for those with floppy-only systems. Fortunately, the price of 10 megabyte hard disks has come down very dramatically in the last year, and the new 20 megabyte disks tend to cost only an additional \$300. Many of my colleagues say they have passed the point of no return; having invested in a hard disk, they will be both unable and unwilling to go back to a floppy system, and I feel that way myself. A couple of years ago ten megabytes seemed more than adequate, but with some of the memory

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demands that I will discuss below, I would ordinarily counsel the investment in 20 megabytes.

Of course, there are various hard disk technologies from which to choose. Hard disks tend to come with random access times close to either 30 or 80 milliseconds, and the slower ones are a lot cheaper than the faster ones. I tend to think that for the scientific user larger capacity is more important than a faster access time, and one's investment strategy should be governed accordingly, but there will obviously be situations where the reverse is true. But fast access time can often be

achieved with the use of RAM disks, particularly if one uses a specialized RAM disk board such as the JRAM-2 from Tall Tree Systems, which can hold up to 2 megabytes for this purpose.

An entirely different set of options becomes available when one thinks of hard disks with removable media. Unfortunately these still tend to be rather expensive. In a class by itself is Iomega's Bernoulli Box, a unique technology which is not only safer to use but is also an excellent way to store off-line data bases or other specialized materials in a form that can easily be

loaded into the computer. It is also an excellent form of backup medium, more reliable and faster than magnetic tape. There are also more conventional types of hard disks which are removable or have a removable platter.

Coming up are the laser disks, initially write-once read-many-times, but eventually read and write at will. These will represent another large step upward in storage capacity, and once again we will have the pressure of the business market to thank for driving the development. I think these will be extremely useful to the scientific workstation user. Not only will they enable specialized scientific data bases to be distributed for his use, but it seems likely that one of the outcomes of artificial intelligence research will be knowledge-based expert systems with a convenient prompting system that the user can assemble in modules as needed. This is the kind of development that is likely to be available for workstations compatible with business systems much sooner than for the more expensive and specialized types of workstations mentioned at the beginning of this article.

## LANGUAGES

Fortran remains the workhorse language for most of the scientific and engineering community. Fortran has had its vociferous critics in the computer sciences community, and just about all the nasty things they have said about the language are true. Despite that, it remains my favorite computational language. Why is that so? Partly from familiarity, but mainly because of the large software base associated with it.

Until quite recently, the version of Fortran generally available was the 1966 ANSI standard, usually with some extensions. This lacked the structure of the better modern languages and resulted in what is often called "spaghetti code", a tangled mess of GO TO's. Now on IBM PC's and nearly everywhere else the Fortran available is the 1977 ANSI standard. This still lacks most of the usual control structures, but it does have IF...THEN...ELSE, and you can do nearly everything you want with that. A few years ago I started using a Fortran preprocessor called RATFOR, which introduced C-like control structures into the way one writes code, and which is compiled into standard Fortran. The extra compilation procedure was certainly a nuisance, so I learned to write structured Fortran by mimicking the results of the translation procedures used by RATFOR. Now I simply use IF...THEN...ELSE.

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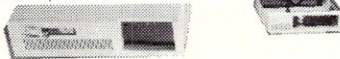
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At last count there were some seven Fortran packages being offered for the IBM PC. Avram Tetewsky of Draper Labs recently ran some benchmark comparisons of the three Fortrans that seemed to be most capable. In decreasing order of execution speed these were the Fortrans prepared by Ryan McFarland (IBM Professional Fortran), Microsoft, and Digital Research, Inc., all of which have nearly transparent procedures for utilizing the full amount of memory available under MSDOS. Under ordinary conditions IBM Professional Fortran would therefore be the preferred choice for most number crunching tasks. However, Microsoft Fortran has been out longer, and there are many libraries of auxiliary routines for various purposes that are designed to link to it, but so far very few of these have released versions that link to Professional Fortran. Thus in many practical cases the Fortran of choice becomes that from Microsoft.

Probably the most useful of the Fortran add-on packages are those that support computational functions that are not included with the standard Fortran. There are in general much more extensive packages that have been produced for Fortran than for other languages.

First (to my knowledge) in the field was a package called MicroSUB:MATH sold by Foehn Consulting. This has a useful set of procedures and routines, but one often wants to change the Fortran source code, and the source code for this is rather expensive.

Then recently the FORTRAN Scientific Subroutine Library, a package from the Professional Software division of John Wiley, the book publisher, appeared. This was a more extensive package which did not provide source code.

On mainframes the most extensive package of subroutines and procedures is from IMSL, who have just brought out subsets of these FORTRAN libraries for the IBM PC. The source code for this is a closely guarded secret, and this limits the usefulness of the package. I have heard that the source code for the IMSL package is quietly circulating "underground" among some IBM PC users.

Probably the most useful package is one that has not yet appeared, a book entitled "Numerical Recipes" (by W. H. Press, B. P. Flannery, S. Teukolsky, and W. T. Vetterling) to be published by Cambridge University Press this fall, and to be accompanied by source code disks which may be obtained in either Fortran or Pascal. In order to include the source code and

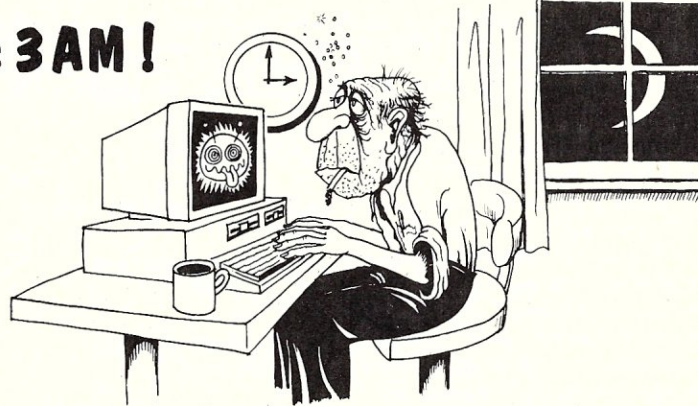
examples of its use on two disks, the authors have stripped out all the commented statements, so that this is a package to be used hand-in-hand with the textbook. The authors have provided a separate summary in Pascal code because of its extensive use in teaching programming, but all the illustrations in the main part of the text are in Fortran. They hope to provide C source code later.

In the last few years I have transported a fair amount of Fortran code from mainframes to minicomputers and from there to IBM PC compatibles. This procedure has turned out to be relatively painless, with most of the effort involved in translating the system calls. It is here that the limitations of MSDOS cause

the most grief. For example, it is frequently painful not to have a Fortran procedure for opening a file for appending. There remains a clear need for more extensive Fortran utilities for dealing with the operating system.

A fair number of scientific and technical people are now using C in laboratory environments for interfacing with equipment, for which it is well adapted and Fortran is not. Not much use of other languages has come to my attention. Some of my colleagues have used Pascal a little bit. Opinions on it are divided. On the positive side, some people like the strong typing in the language, because "it won't let you make a mistake." Others dislike the strong typing in the language because "it is a royal pain." Such people would

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rather use C. Perhaps there will be a drift away from Fortran in coming years as other languages build up a base of mathematical and physical supporting software, but I suspect that any such motion will resemble that of a glacier. It is also likely that Fortran itself will undergo further evolution.

### PLOTTING

There is an incredible number of software programs now available for plotting with IBM PCs. Most of them have been developed for business use. These tend to be screen oriented and pen-plotter oriented, and usually offer a set of utilities for providing bar graphs and pie diagrams and that sort of thing. Very few provide a facility for doing

the kinds of drawings that most scientific people want, with lines and curves and isolated points, perhaps showing least squares fits or spline interpolations. Fewer still provide a decent facility for using a dot matrix printer for plotting (most just do screen dumps with very poor resolution).

For quite a long time I have been looking for a plotting package that will provide a library of Fortran plotting routines and which will use the full resolution of the FX-80 printer. The closest I have yet found is Plot88 from Plotworks. This provides a good set of Fortran plotting routines and supports several Hewlett-Packard pen plotters, the IBM color graphics monitor, the Tektronix 4025, and Epson dot matrix

printers. Unfortunately the FX-80 is only supported for a vertical resolution of 72 dots per inch, one-third of its capability, but it does support up to 240 dots per inch horizontally. That means that you must still use a pen plotter to prepare a reasonably good publishable graph.

There is no fundamental reason why we cannot get plotting programs which make better use of rasterized devices. The need for these will accelerate when cheap laser printers become available and are desired also for plotting uses.

### EDITING AND TEXT PROCESSING

Everyone seems to have a favorite word processor, and arguments about the superior qualities of some other word processor fall on deaf ears. Scientists are no different. However, at least some scientists prefer an editor with extremely powerful macro command capabilities, and that preference is unlikely to be shared by the average person. Many of my colleagues and I share this preference, and our editor of choice is PMATE, distributed by Phoenix Software Associates. Some of my colleagues are interested in little more than the direct entry of text, and they prefer a wide variety of other word processors.

Those word processors that try to integrate editing with spelling checking and hyphenation and text formatting tend not to do any or all of those things as well as other programs do individually. Personally I have for a long time preferred to do such operations separately. Some years ago I started using a hardware text formatter called a Retroscriber, which consisted of a Z80-based board that was inserted into a Diablo 1620 daisy wheel printer. This could be fed text prepared with any editor and it produced better scientific output than any software available at the time. This has evolved into a medley of programs for the IBM PC called the PS Technical Word Processor, and sold by Scroll Systems, Inc., which includes PMATE. In fact, PMATE is merged into the package through the use of about 9 kilobytes of permanent macro commands which give it menus and make it considerably more user-friendly. Until very recently, this combination was unsurpassed for technical text output by any combination short of a minicomputer-driven phototypesetter. Even with this set of programs I still preferred to use The Word Plus from Oasis Systems for spelling checking and also for hyphenation. Although PS does hyphenation, I consider the algorithm used by The Word Plus to be superior.

The situation has very recently been changed by the advent of TEX on the IBM PC. There are two vendors for this: Addison Wesley (MicroTEX) and Personal TEX (PCTEX). TEX is a very elaborate program designed for mathematical typesetting; it has developed a devoted following and is now available on a considerable variety of mainframes and minicomputers, it has been adopted by the American Mathematical Society, and it has its own users' group. The PC implementation does not come cheaply; you can get a minimal working version with 512 kilobytes of RAM, but you are much better off with 640 kilobytes. Right now the principal output device supported by both versions of TEX for PCs is the Epson FX-80, and the storage of the necessary fonts will take 4 to 6 megabytes of hard disk space, depending on the version that you have. This is a very slow output device, and PC TEX users will certainly look forward to obtaining a supported laser printer for output which will also produce superior quality characters. My own expectation is that I will use PS for ordinary material and TEX for very technical material until such an inexpensive laser printer is available, and then I will switch entirely to TEX. However, I am likely to continue to use PMATE with PS macros to prepare text for TEX output.

## OVERVIEW

In this discussion of the scientific workstation I have not attempted to discuss control of laboratory equipment or analysis of the data that results, since I have not had any experience in this area. Nevertheless, that is an important area of scientific workstation activity. I expect this to be even more important in the future. Large data bases of scientific and technical information have become available both within government agencies and on the on-line information resource networks, and PCs can be used for data retrieval from these. I expect laser disks to become available as cheap distribution media for specialized scientific and technical data bases, sort of the on-line technical encyclopedia, and these will be invaluable both for those workstations that are used for laboratory control and for those that are not.

From a general point of view what is important is probably not the specifics of the moment, but the sense of a field rapidly evolving both in the hardware and software senses. Much of the momentum for these changes comes from the business community, but there is also a growing constituency on the technical side. We would not

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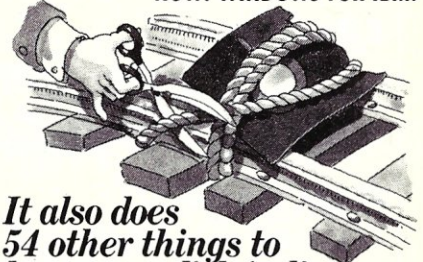
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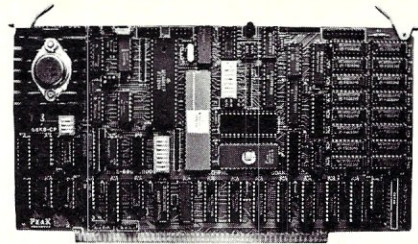
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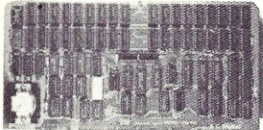
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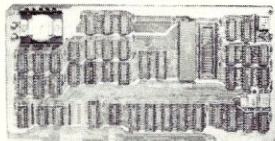
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# The UNIX File

by Ian F. Darwin

*This column discusses the UNIX operating system. If you have comments or questions about UNIX, or this column, please write to Ian Darwin, Box 603, Station F, Toronto, Ontario, Canada M4Y 2L8. If you have access to the uucp network, mail "ihnp4!darwin!ian". I can't always answer immediately, but I will get back to you; electronic mail gets answered first!*

This UNIX File tells how to get the source for a hacker's operating system, shows how to tune programs, and tells about upcoming UNIX conferences.

## HACKER'S OPERATING SYSTEM

Many hackers dream of getting the source to the UNIX system. The GNU system has been promised for some time, but to date GNU has only released an EMACS-like editor. Here's a UNIX-like system that you can get the complete source for. The system is XINU. Its author, Douglas Comer, wrote an excellent book *Operating System Design: The Xinu Approach* (Prentice-Hall, 1984, ISBN 0-13-637539-1; also available via M/SJ -see "The Book Mart"). The book describes how Xinu works, rather than enumerating ways an OS might work.

Xinu is not a complete UNIX-like system. As a teaching/learning tool it consists of a kernel with some UNIX functionality. One important function to be added before you would have working timesharing system is the ability to dynamically load new programs. Instead, your application is linked with Xinu, and the combined module loaded and run. Comer alludes that it would not be hard to add this facility. You'd still have to add a shell and utilities before you'd have full UNIX functionality.

The OS source is included, and a dedicated hacker could type it in. Tom Hartnett (electronic address ihnp4!nvuxd!th), did so and is willing to make the part he typed in available by UNIX electronic mail (or put you in touch with someone near you to whom he's sent it). Tom is setting up a uucp system so you can dial in and pick up his version of the source files; contact him for details. As important, Tom is running an electronic news letters for people playing with Xinu, getting it up on different machines, etc. The first issue summarizes the work needed to port Xinu to a new machine.

## A Hacker's OS & Tuning Unix Programs

Alternately, you can get the complete source on nine-track magnetic tape from the book's publishers for under a hundred dollars. Information on how to get the source tape is not included in the book, so here it is. To order the tape, contact James F. Fegen, Jr., College Editorial, Prentice-Hall, Englewood Cliffs, NJ 07632, phone (201)592-3122. We got our tape with no problems, and have even received minor corrections made since the tape was written.

What it means is that there's an OS that you can get the source for, hack at, and (maybe) expand to a working timesharing system. The operating system, like UNIX, is written in C with an underpinning of assembly language. The *real machine* on which it's running is the ubiquitous LSI-11 micro. Tom Hartnett has it running on a 68000, and through his electronic newsletter you may find it running on other machines by now.

## NEED TO OPTIMIZE?

How much execution time are you willing to trade off for programmer time? How much can you slow down a small system and still consider it usable? There are no hard answers for such questions, of course. But there are techniques for improving execution time of C programs.

Before you even think about optimizing, think about several things. First, the importance of *making it right before you make it faster*. There's no point solving an equation quickly if you get the wrong answer! This often overlooked aspect of program efficiency is emphasized in *The Elements of Programming Style* by Kernighan and Plauger, a book I recommend for all programmers.

Second is the degree of use the program gets. To shave one second off the run time of an accounting program that's used once daily, and at 2 AM at that, is to make an utter waste of your

life's work. The improvement is so useless compared to a day's worth of CPU time that nobody will ever notice. But shave that same second off *grep* or *cat* or some frequently-used user program, and you will contribute some fraction of a percent of CPU time back to system throughput. Two UNIX tools that give numerical data on program performance are *Time* and *prof*. *Time* tells how long a program takes to execute for a given set of inputs. You just say, for example,

```
time cat /unix >/dev/null
```

to see how long the particular *cat* takes to run. *Time* reports three numbers, which are the wall clock time (elapsed time you would see with a stopwatch), the program CPU time, and the amount of CPU time the kernel spent processing requests on behalf of the program.

The sum of the user and system CPU times is what timesharing services conventionally use to bill for *CPU time*. The real or elapsed time must always be greater than (just possibly equal to) the sum of the user and system CPU times. Elapsed time varies with system load. If you had the system to yourself, the elapsed time should be close to the CPU time; if not, there may be time lost waiting for disk swapping, system-provided processes, etc.

*Prof* is used to print an execution profile of a running program. You compile the program with the *-p* option specified to the compiler for each module you want to examine, and for the final *cc* command that loads the modules together. This option causes inclusion of code in your compiled program to indicate where time is being spent, and to write the results to disk at exit for later analysis by *prof* itself (note that if your program is interrupted or dumps core, the counts do not get written).

For example, I have a Research-UNIX-like version of *cat* i.e., no options such as *-s*, *-n*, *-vb*, *-vd* (*cat* is a program to copy files to the standard output; its most common uses are printing files at the terminal and concatenating files together). My version lives in two source files, *main* and *process*, each containing one function with the same name as the file. A testing sequence might look like this:

```

$ make
cc -o -p -c main.c
cc -o -p -c process.c
cc -o -p main.o process.o -o cat
$
$ time ./cat /etc/group >/dev/null

real    2.3
user    0.0
sys     0.8
$ prof cat
memccpy100.00% 0.02sec
process 0.00% 0.00sec
main 0.00% 0.00sec
$ ./cat /unix >/dev/null
$ prof cat
memccpy 78.63% 1.61sec
fgets 9.92% 0.20sec
fputs 6.11% 0.13sec
fstat 2.29% 0.05sec
process 1.53% 0.03sec
filbuf 0.76% 0.02sec
profil 0.76% 0.02sec
main 0.00% 0.00sec
$

```

The command *make* rebuilds the program. Then I run my newly-made *cat* against a short file, and run *prof* to look at the profile. The columns are function name, percent of CPU time, CPU time, and for some modules the number of calls and msec/call. In this case, every measureable bit of CPU went into a routine called *memccpy* that is called from inside the *stdio* (standard I/O) library. As its name suggests, *memccpy* copies data in memory, presumably copying the input buffer to the output buffer.

If you don't know about *stdio*, suffice to say, that there are two sets of calls for doing I/O in UNIX; the system calls (*open*, *read*, *write*) and the 'standard IO' or *stdio* routines. The system calls pass control to the operating system to carry out some request, but system calls only read blocks of data (or read one byte at a time, which is very inefficient). For byte at a time processing, or line-at-a-time processing, you almost invariably should use the *stdio* routines (*fopen*, *fread*, *fwrite*, etc) since they take care of buffering, lines that are stored across block boundaries on disk, etc.

When I run the program on a larger file, although *memccpy* is still the largest component of time (at only 79% of the total CPU), a number of other functions show up with measurable CPU time.

As a general principle of program tuning, you need to run a program like this with one small file, with several files, and with one or more large files. Often this will show different parts of the code dominating the CPU usage.

The first version of *process* was written using *stdio* routines *fgets* and *fputs*. Noticing that *stdio* routines and subordinate library routines dominate the CPU usage, I rewrote the *process* function to use the *read* and *write* system calls. Here's what happened:

```

$ make
cc -o -p -c process.c
cc -o -p main.o process.o -o cat
time ./cat /etc/passwd >/dev/null

real    5.1
user    0.0
sys     0.9
$ prof cat
process 0.00% 0.00sec
main 0.00% 0.00sec
$ time ./cat /unix >/dev/null

real    9.1
user    0.0
sys     2.8
$ prof ./cat
process 0.00% 0.00sec
main 0.00% 0.00sec
$ time ./cat /unix >/dev/null

real    11.5
user    0.0
sys     2.7
$ prof cat
process100.00% 0.06sec
main 0.00% 0.00sec
$

```

The change was so dramatic I ran it several times to be sure. User CPU time was not measurable. Once on copying a large file (*unix*), the system noticed 62 msec (0.06 sec) of CPU time in the program; on the other two runs, the system did not notice any user CPU time. I have since installed this version of *cat* in */bin* on my system.

Now this is not to argue that one should not use *stdio* in general. A good intermediate would have been to use the *fread()* and *fwrite()* library calls. But *cat* is a program that by design does not need to transform or even look at the data it is reading, so it's appropriate to use *read()* and *write()* here. Most programs would want to examine the data in some way; for such programs, *stdio* is definitely the way to go, despite the apparent CPU overhead of using *stdio*. The programmer overhead saved is worth it.

I've shown some quick examples of using *time* and *prof*. These are two main tuning tools that every UNIX/C programmer should know. There are many fancier tools on some versions of UNIX and some that are available as proprietary add-ons; I have limited the discussion to two tools that I can be sure every real UNIX system has. For an alternate method of studying the CPU program usage, see *Dynamic Instruction Counting* by Peter J. Weinberger, AT&T Bell Labs Technical Journal, October 1984, Vol 63, No 8, Part 2, p 1815.

I hope you find this discussion useful; please let me know if you are interested in a similar discussion of standard debuggers or other programming aids.

## CONFERENCES

*USENIX* has scheduled its 1986 winter technical conference for January 15-17, in Denver, Colorado, three weeks before */usr/group's UniForum*

show February 3-7, in Anaheim, California. The two groups couldn't put together a joint conference this year, but continue to cooperate with each other and may do so again at some point in the future.

This *USENIX* will be different from previous *USENIXes*, consisting of three one-day technical workshop sessions with a new topic each day, namely *UNIX and Window Systems*, *UNIX on Big Iron*, and *UNIX and Ada*. This is obviously an experiment; if it works well *USENIX* will probably continue the 'workshop' organization; if not, they may try other approaches or revert to the standard multi-stream conference.

*UniForum*, in February, will be a conventional conference and commercial trade show, including a day of Tutorials (I will be presenting a one-day tutorial on *Effective UNIX Programming*) and a program of technical and commercial papers. *USENIX* will also hold a traditional Summer technical conference in Atlanta, Ga., June 9-13.

For more details, contact *USENIX Association*, Box 7, El Cerrito CA 94530, (415)528-UNIX (528-8649), and */usr/group*, 4655 Old Ironsides, #200, Santa Clara CA 95054, (408)986-8840. Hope to see you there!

For European readers, or those who like to go there, the European *UNIX User's Group* (EUUG) holds conferences periodically. The September 1985 conference was in Copenhagen in September. They planned talks on many topics including the long-awaited 4.3 BSD. I always seem to hear about EUUG gatherings just a little too late to tell you in this column; if you're planning to attend future EUUG conferences, you might write to EUUG, Helen Gibbons, Owles Hall, Buntingford, SG9 9PL, Great Britain, phone +44 763 73039.

That's all for this month. I welcome cards and letters and electronic mail on these and other topics. Cheers!

# Eureka

by Robert Hazelwood

Ever had a bad case of DIR:itis? When you forgot which disk a badly-needed file was on and you wear out your fingers inserting disk after disk and typing DIR: over and over again! Well, I may have found an answer for those of you out there who were like me. It's called *Eureka*, a program that lets you catalog and list all the necessary information about your floppy disk collection. My problem started out just as, I guess, everybody's does. I never tried to catalog my growing disk collection because I never thought it necessary, until I discovered it had grown to over a hundred disks with, at best, scanty comments on the labels. I first tried using index cards, then printing out each disk directory but these methods were too difficult to update and didn't help with duplicate file names.

What I needed was a series of comments for each file and a master alphabetical listing of all the disks. I then tried a few experiments with some of the public domain software for disk catalogs, but was never quite satisfied with the results. I could set up an index file on each disk and place comments in it, but still had to search each listing either manually or use the FIND program to search a cobbled-together, master catalog of all the disks. Then I saw an ad in *Microsystems* for a catalog system called *Eureka* by Mendocino Software Inc. I got a copy of *Eureka* and tried it.

## DOCUMENTATION

The first thing that impressed me about the program was the manual. It was eighty pages of detailed instructions on installation, operation, and explanations about the program. I was so fascinated with the manual that I actually read it before I installed the program!

The manual was well thought out and had an index, table of contents, and several appendices, one of which listed all of the error messages, that were used by the program. With the listing of the error messages there is a set of explanations telling you when you would normally encounter these errors and what probably caused them. The manual is very user friendly!

## A CP/M-80 Disk Cataloging Program

### INSTALLATION

I then followed the step-by-step installation instructions. You must use their program (M-COPY.COM) to install the program on your system as the normal copy programs, pip etc... will not properly copy the program. This made me curious, but I followed their instructions and used M-COPY to copy over EUREKA.COM.

When finished copying *Eureka* to the work-disk the installation program (M-INSTALL) is run. First pick a terminal from the selection which includes most terminals in use. If yours is not on the list, you will have to answer a few questions about your terminal, i.e. its screen width, height, and the code used to clear the screen.

Next are the questions about your printer, i.e. the width and number of lines-per-inch it prints. If your printer cannot handle the ASCII form feed code, you will have to set the printer parameters differently than if your printer used form feeds, but *Eureka* will work either way.

To try to prevent BDOS errors from dumping you out of *Eureka*, the program checks for valid drive names. So in the installation you will need to specify all of the valid drive names you have on your system.

When I installed my copy of *Eureka*, I had to decide which files I didn't want cataloged. As shipped, *Eureka* will not catalog any file with the attribute \$\$\$, BAK, or HEX. To this you can add two more types or change any of the original three for a maximum of five types that can be excluded. All files that are declared to be system files are not cataloged and this cannot be changed from the install program. The remaining installation consists of selecting default toggles for the ACCESS menu. Most of these toggles can be changed from the ACCESS

menu and they affect how the catalog information is presented on the screen and the printer. I left mine with the default settings. The instructions were very easy to understand and I did not have any problems with installation.

### SETTING UP THE CATALOG

Next I had to design a cataloging method for my disk collection. It should be well thought out as you will have to live with it for quite a while. A file containing the contents of each disk's directory is given a name. This "volume label" is preceded by a hyphen and is in the same format as a file name under CP/M, except you are allowed one less character due to the hyphen. *Eureka* searches for this file when it catalogs a disk, so there can be only one file of this type on the disk at a time. *Eureka* uses this file as the name of the disk that is stored in the master catalog.

### USING THE CATALOG

The program itself is very easy to use, as it is menu driven with the selections self-explanatory to the point that you should not really need the manual after you have used *Eureka* a few times. If you get stuck and cannot find a menu selection that helps, hit the escape key to return to the previous menu.

A key feature of *Eureka* is that you can add comments to your catalog listings in two ways. The first (recommended in the manual) is to add the comments to the files on your disk. *Eureka* searches the first 256 bytes of each file and looks for the four identifiers that are part of its cataloging system. These are Desc:, Date:, Vers:, and Auth:. If these are placed in the first 256 bytes of the file, *Eureka* will read them and insert them in the catalog file for that disk. Only the first two of these must be exactly as they are listed. The last two can be any four letters followed by a colon. They must be four letters in length and if the identifier is less than that, you must fill in with blanks to the colon. The first two identifiers can be changed using the install program.

*Eureka* looks only for its special identifiers which can be hidden inside of the file using whatever method will



work with that language or program. Comments inserted in various types of programs look like this:

```
FORTRAN
C Desc:Fortran program to calculate
      distance
C Date:04/27/83
C Vers:3.34
C Auth:R.Hazelwood
```

```
Basic
10 REM Desc:Calculations program
      Date:04/27/83
      Vers:3.34
      Auth:R.Hazelwood
```

```
Pascal
(* Desc:Calculations program *)
(* Date:04/27/85 *)
(* Vers:3.34 *)
(* Auth:RHH *)
```

The manual shows several other methods for other types of programs.

The second method of adding comments to your program is to insert them into the disk name file that was created on the disk. If Eureka searches the disk files for comments and fails to find any, it checks the catalog file to see if there are any comments there. If it finds any, it uses these comments. If you have comments in both places, it uses only the comments inserted in the file itself. These comments are formatted in a slightly different way than the rest of the file so that you can insert comments into files you wouldn't ordinarily be able to comment, such as COM files. Each file name must be on a line by itself and preceded by an asterisk. Then on the following lines the comments are inserted just as before.

```
*FOXTAG.ASM
Desc:New improved game program
Date:04/27/85
Vers:3.99
Auth:R.H & C.K.
```

Eureka's nicest feature is available under the ACCESS menu. "T(ext)" allows you to selectively sort through your disk files, using logical operators which Eureka provides. They allow you to include and exclude various groups of characters from the search string. For instance, if you wanted to search for all the Fortran programs written by RHH and DKT, you would enter "Fortran+RHH+DKT" on the text line. Eureka then searches the comments, looking only for those programs that were Fortran and were written by RHH and DKT. In addition to the text options, you can narrow the search further by using wildcard references when you select the disk title at the ACCESS menu.

It is always nice to have a printed copy of your catalog. Eureka will do this for you in a variety of different

forms. The first shows all of the catalog files alphabetically, both with or without comments. The second prints out a selected disk's files in alphabetical order by disk. The third lists all of the disk titles in alphabetical order. The last method lists disk information by disk title telling you the disk size, number of files cataloged, space used, and space free on each disk. It also shows the last date that the disk was updated. Each of these listings can be modified using the search parameters explained earlier. This allows you to print out just the listings on the disks that have been changed without printing all of the catalog.

### COPY PROTECTION

One last area of concern is that Eureka uses a novel approach to software piracy. When the program is first installed, it reads certain items from your operating system and stores them in the program. If you try to use the program on another machine you will get the following warning message:

```
*** EUREKA! runs on a single system ***
```

When I took my copy of Eureka into work with me and tried to bring it up on the Apple II, all I got when I tried to run Eureka was the above warning message. This does not mean that you cannot make copies of Eureka. One of the selections on the main menu is "Put Eureka on a new disk". When selected, it copies Eureka to the new disk. The copy program works with your current catalog disk and does not require the distribution disk for copying.

My curiosity got the better of me however, so I called the company and was told that additional licenses were fifteen dollars each and included a new disk to install on the other system. I asked about possible problems with ZCPR3. They said that they didn't think there would be any problem as they had ZCPR2 installed on a home system and had not had any problems with Eureka. I asked him about bugs in Eureka and was told they had not received any bug reports in over eighteen months. If any are found they use the registration form to contact users.

There is one problem that I didn't encounter that is warned against in the manual. Certain versions of the BIOS used with CP/M cannot handle mixed-disk densities while you are in Eureka. In this case, you will have to exit Eureka, type control-C and return to Eureka to finish cataloging your disks. Sort your disks before you start cataloging, so as not to have do this

# \$100

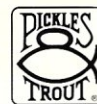


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more than once during your use of Eureka.

Eureka requires CP/M 2.2, 48K of RAM, at least two disk drives, and a terminal that can handle at least 50 columns.

I like the program very much. It is easy to use and searches through the catalog files very quickly. The manual is very good and the people who supply it are friendly and courteous. Eureka should be one of those programs that is automatically supplied with your system. That way you could start cataloging your disks before their number becomes too large to work with easily. If you don't already have a copy of Eureka, go buy one, it's \$50 very well spent. It can be purchased directly from Mendocino Software Inc., Box 1564, Willits, Ca. 95450, (707) 459-9130.

*Robert Hazelwood works as an Electronic Engineer for Atlantic Satellite Communications, designing and maintaining audio, video, and microwave communications systems at their satellite uplink facility in Northvale, NJ. He attended the University of Missouri at Rolla where he majored in Electrical Engineering and Computer Science. He has been involved with microcomputers since the early seventies.*

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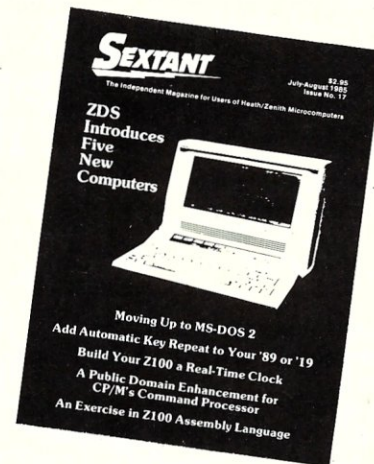
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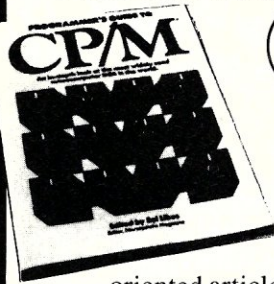
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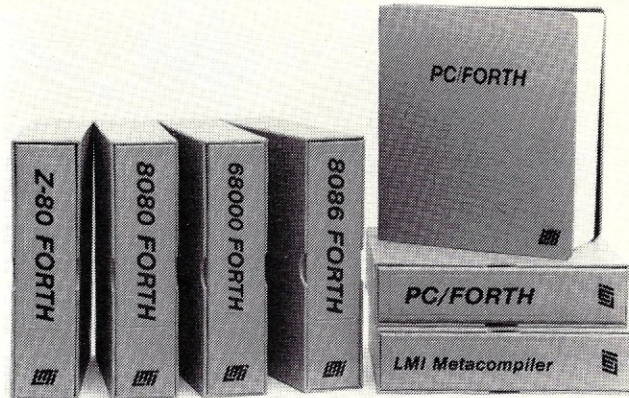
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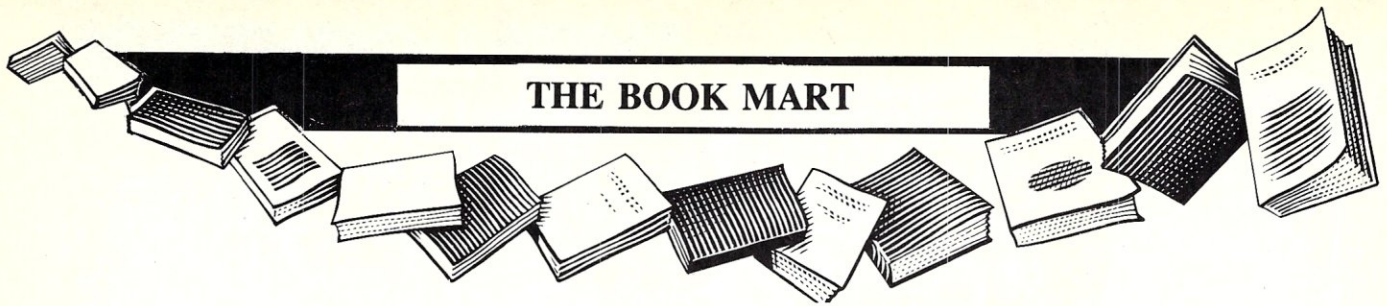
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**IAPX 86/88, 186/188 User's Manual Hardware Reference**, Intel; \$21.95

**IAPX 86/88, 186/188 User's Manual Programmer's Reference**, Intel; \$19.95

**From Basic To 8086/8088 Assembly Language**, Temlepton/Wordware; \$18.95

**The 8086 Book**, Rector/Alexy; \$19.95

#### 80286

**80286 Programmer's Guide**, Childs/Evanczuk; \$15.95

**80286 System Guide**, Childs/Evanczuk; \$15.95

**IAPX 286 Programmer's Reference Manual, Numeric Supplement**, Intel; 17.95

#### 68000

**Self-Guided Tour Through The 68000**, Andrews; \$15.95

**68000 16/32 Bit Microprocessor, 4th Ed.**, Motorola; \$19.95

**68000 Assembly Language Programming**, Kane/Hawkins/Leventhal; \$19.95

#### SCIENTIFIC & ENGINEERING

**Microcomputers For Engineers & Scientists**, Gibson/Liu; \$37.95

**Basic Programming For Scientists & Engineers**, Hubin; \$21.95

**IBM PC Basic For Scientists & Engineers**, Weinman/Kurshan; \$20.95

#### IBM PC/XT

**Business Graphics For the IBM PC & XT**, Glau; \$18.95

**Complete Guide To IBM PC Graphics**, Hyman; \$20.95

**Assembly Language Routines For The IBM**, Dorner; \$20.95, companion disk \$30

**Assembly Language For The IBM PC/XT**, Scanlon; \$22.95, companion disk \$30

**Input/Output Assembler Programming For IBM-PC DOS**, Germain; \$25.95

**Programming Tools For The IBM PC: Screen Design, Code Generator, and High Memory Access**, Fugate; \$20.95

#### CP/M

**A Programmer's Notebook: Utilities For CP/M Plus**, Cortesi; \$18.95

**CP/M Solutions: Improving CP/M**, Barbier; \$15.95

**CP/M Assembly Language Programming**, Barbier; \$13.95

**CP/M Techniques**, Barbier; \$20.95

**The Programmer's CP/M handbook**, Johnson-Laird; \$22.95

**CP/M-86 User's Guide**, Sachs; \$19.95

**Inside CP/M**, Cortesi; \$27.50

**Inside CP/M-Plus**, Cortesi; \$19.95

**Inside CP/M-86**, Cortesi; \$18.95

**Inside Concurrent CP/M**, Cortesi; \$18.95

#### C

**C Programmer's Handbook**, AT&T; \$15.95

**C Programming Language**, Kernighan/Richie; \$23.50

**Learning To Program In C**, Plum; \$26.00

#### HARDWARE

**Interfacing to S-100/IEEE-696 Microcomputers**, Libes/Garetz; no longer published. We have only a limited supply; \$19.95

**Designer's Guide To Disk Drives**, Teja/Gonnella; \$20.95

**RS-232 Made Easy**, Seyer; \$19.95

**Guide To Local Area Networks**, Byers; \$16.95

#### WORDPROCESSING

**Getting The Most From Wordstar & Mailmerge**, Stone; \$15.95

#### dBASE-II

**The dBasell Cash Manager: Cash Receipts/Cash Diskbursements for the Small Owner or Accountant**; Heiser/Pickney; \$15.95

**Advanced dBasell User's Guide**, Green; \$30

**dBase Guide For Small Business**, Schadema/Dickey; \$25.95

**Using dBase III**, Jones; \$18.95

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Structured Programming  
With The Microsoft  
M80 Assembler

see pages 26-36

Build an  
S-100 to PC Bus  
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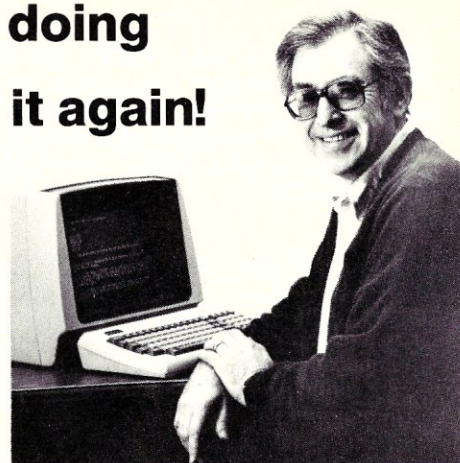
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**MARCH/APRIL 1985 (Vol 1., No. 1):** Bringing Up CP/M Plus, Assembly Language Extensions for MS-Basic, New Tricks for CP/M2.2, Building an IBM/PC or XT Clone, Extended Single Density Storage, Variable Size Arrays in C; REVIEWS: dBase-III and 16-Bit Lisp & ProLog-Part I.

**MAY/JUNE 1985 (Vol 1., No. 2):** Build an S-100 to PC-Bus Converter, Interfacing to MS-DOS Part-1, Loadable Drivers for CP/M2.2, Roll Your Own PC-Clone, Bringing Up ZCPR-3, C & Godbout Disk-1 Controller, Writing Translation Programs in C and Turbo Pascal; REVIEWS: 16-Bit Lisp & ProLog-Part II.

**July/August 1985 (Vol 1., No. 3):** Structured Programming With Microsoft M80 Assembler, Local Variables In Forth, Interfacing to MS-DOS Part-II, Data Translation with Turbo Pascal, Implementing Sets with Bit Operations in C, A Unix Mail List System; REVIEWS: Scientific & Technical Word Processors - Part I, Macrotech MI-286 S-100 CPU Card, Slicer System, Concurrent PC-DOS, Concurrent PC-DOS, Coherent Operating System.

**September/October 1985 (Vol. 1., No. 4):** Who Prints on Printer With CCP/M, Interrupt Borrowing With Turbo Pascal, Upgrading CompuPro I/O Boards, Program Interfacing to MS-DOS Part-III, SIG/M & PC/Blue Public Domain Software Distribution Points, TurboDos INSTALL program; REVIEWS: CompuPro 10+, TEX.

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### 1984

**FEBRUARY:** Using WordStar to Create Mailmerge/dBase-II files; Moving data files between CP/M software packages; Datestamp dBase-II; CP/M 2.2 Deblocking; Building S-100 diagnostic hardware; Enhance CP/M+ with RSX; REVIEWS: dBase-II, S-100 Mainframes, DRI Display Manager, AutoDex, Turbo Pascal.

**JANUARY:** Enhancing MP/M - Part 1; Installing MP/M; Add Concurrency to MP/M; Two Users on CP/M; Relocating Assemblers & Linkage Editors - Part 3; S-100 Wait States; REVIEWS: MP/M-8/16, ProComp-8, Paragraphics Game Board, ProLog.

### 1983

**DECEMBER:** CP/M Software Directory; A Debug Subroutine; Implement IOBYTE on North Star; Floppy Disk Problems; Improve Trig Functions in CBasic-80; Build Cheap S-100 Memory; Extended Memory Management; CP/M-86 BDOS Calls; REVIEWS: XLISP, LISP/80, TLC LISP, APC Basic, Microdynamics S-100 EProm Programmer, Ackerman S-100 Digital Synthetalker, Digital Research 16K & 32K S-100 Memory cards.

**NOVEMBER:** Intro to 80286, 68000, and 16032 Microprocessors; Intro to Local Area Networks - Part 2; Extended Memory Management for older S-100 Systems; Notes on Microsoft Fortran-80; Building S-100 Parallel Ports; REVIEWS: CompuPro CPU-68K, System 8/16, Xenith Z-100, Nevada & Ellis Computing Fortran.

**OCTOBER:** Intro to Local Area Networks, Part-1; Build Low-Cost LAN; Build S-100 Bubble Memory Card; Use Radio Shack Model 100 portable with a CP/M system; Write Menu-Driven Utility for Setting Printer Options; North Star Improvement; True Z-80 Random Number

Function; Hide Code in Basic REM statements; Machine Code loader for MBasic; Increase Single-Density Disk Formatting; Relocating Assembler & Linkage Editors, Part-2; Run MX-80 with North Star; User Group Directory; CP/M-86 Versus CP/M-80; REVIEWS: CP/NET, QBAX, S-Basic.

**AUGUST:** XERA Program; Logging-On CP/M; WordStar Date/Time Patch; Find Location of Variable in NorthStar Basic; Prevent System Crashes During Warm Boot; Enhance Spreadsheet Print Files; Plotting Package-Part 3; Run WordStar under TP/M; 50-line Text Formatter; Using the LU Utility; User Areas under CP/M; REVIEWS: Stiff Upper Lisp, MuLisp-80, Supersoft Lisp, Cromenco C-10, Access Manager, Fancy Font, Computime SBC-880 S-100 card.

**JULY:** Using RCPMs; RCPM Directory; PIP Data Between Computers; Toward Smarter Modem Programs; Interface MX-80 via Parallel Interface; Digital Audio On CP/M System; Customize CP/M CBIOS; Plotting Package Part-2; REVIEWS: DRI PL/I-86 and PL/I-80, S-100 PMMI MM-VT1.

**JUNE:** Plotting Package Part 1; Drive HP Plotter; Laboratory Graphics Applications; Console Keypressed interrupts; Cutomize Wordprocessor Keyboard; WordStar Patch hor H-19/Z-19 Terminal; Relocatable Code; REVIEWS: Graftalk, JES S-100 Graphics Controller, ZCPR2.

### 1982

**NOVEMBER/DECEMBER:** CP/M Vs MS/DOS; CP/M-86 Vs MS-DOS; Intro to ADA Part 2; Virtual Disk for NorthStar; CP/M Program Auto-execute; Macros & Macro-Assemblers; REVIEWS: Janus, Aztec-C, C/80, Morrow S-100 M26 Hard Disk System, Teleram S-100 Bubble Memory Card, Jade S-100 Bus Probe.



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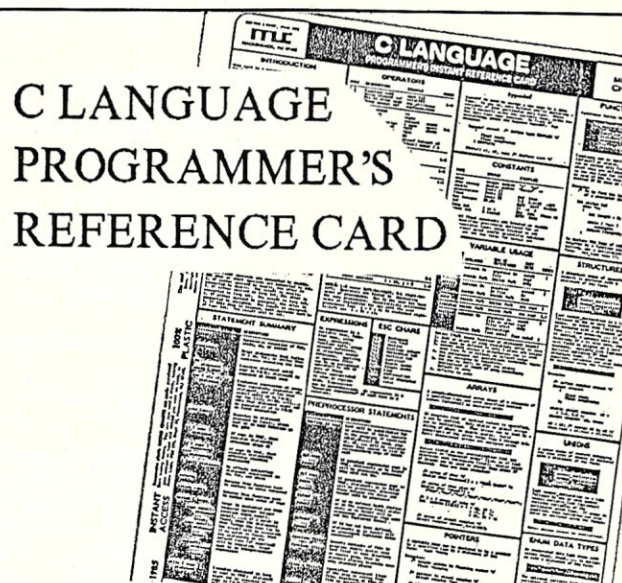
**JULY/AUGUST:** Hardware Random Byte Generator; Error Detection & Correction Codes; Getfile CP/M Utility Program; CP/M Patches; CP/M Application Notes; Run old NorthStar programs under new DOS; Cloning Disk Drives; Low Cost Floppy Disk Power Supply; Intro to Computer Graphics; Using Supersub Utility; **REVIEWS:** D80, RAID-8080, Three Macro-Assemblers, PDS, Cer-Tek S-100 UniProm Board; GrafPak.

**MAY/JUNE:** Intro to DBMS; Three ways to implement a mail list; Cursor Addressing; Structured Programming in Basic; Replacement for CP/M Submit; CP/M Disk Directory & Table Secrets; Mods for SDS VDB-8024; Run NorthStar Basic with CP/M; **REVIEWS:** DataStar, MDBS, TIM, Mince, ZDM.

### 1981

**JULY/AUGUST:** 16-Bit Disk Operating Systems; Input Queuing For NorthStar; Variable Speed Automatic Slow Step; Build S-100 Clock/Calendar Card; **REVIEWS:** TEC-86 System, Seattle Computer 8086 System, AlphaMicro, Godbout Dual Processor, CP/M-86, Televideo 920-C Terminal.

**NOVEMBER/DECEMBER:** Introduction to the C Language, Virtual Segment Procedures, Little-Ada Part-II, A Disk Alignment Routine, Northstar DOS/BIOS Directory & File Conversion using UCSD Pascal; **REVIEWS:** BDS-C, Small-C, Tiny-C and Whitesmiths-C; Tarbell Double-Density Disk Controller



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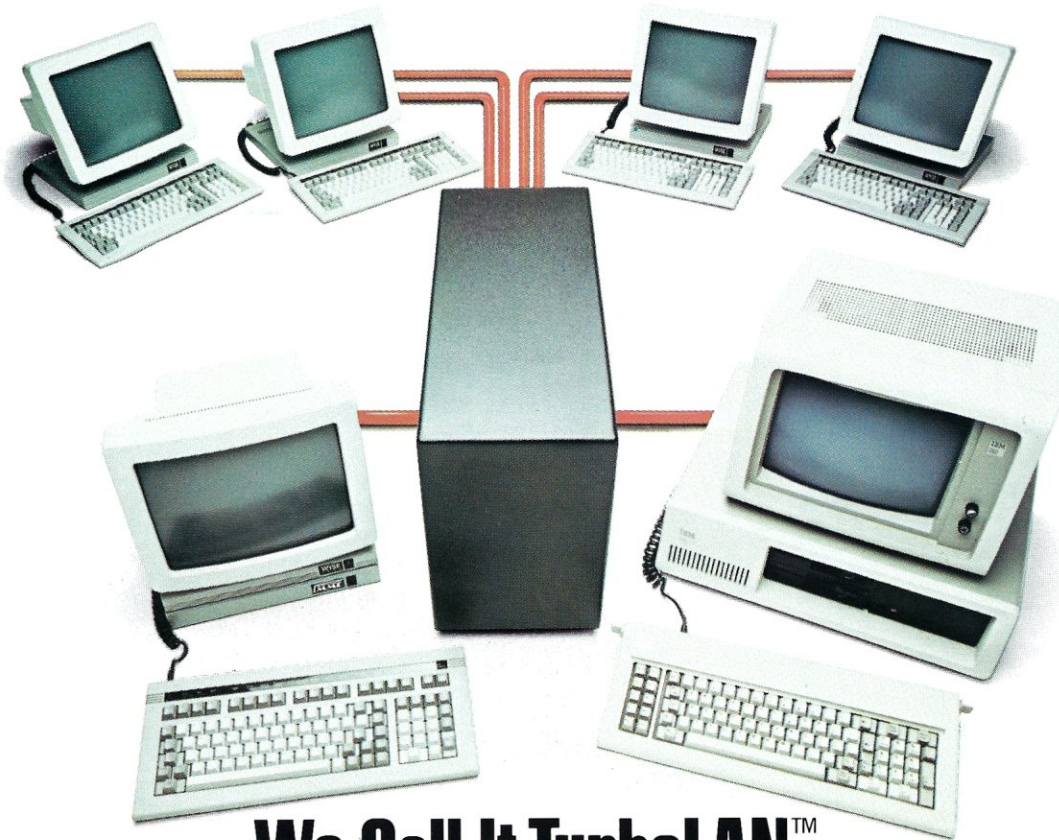
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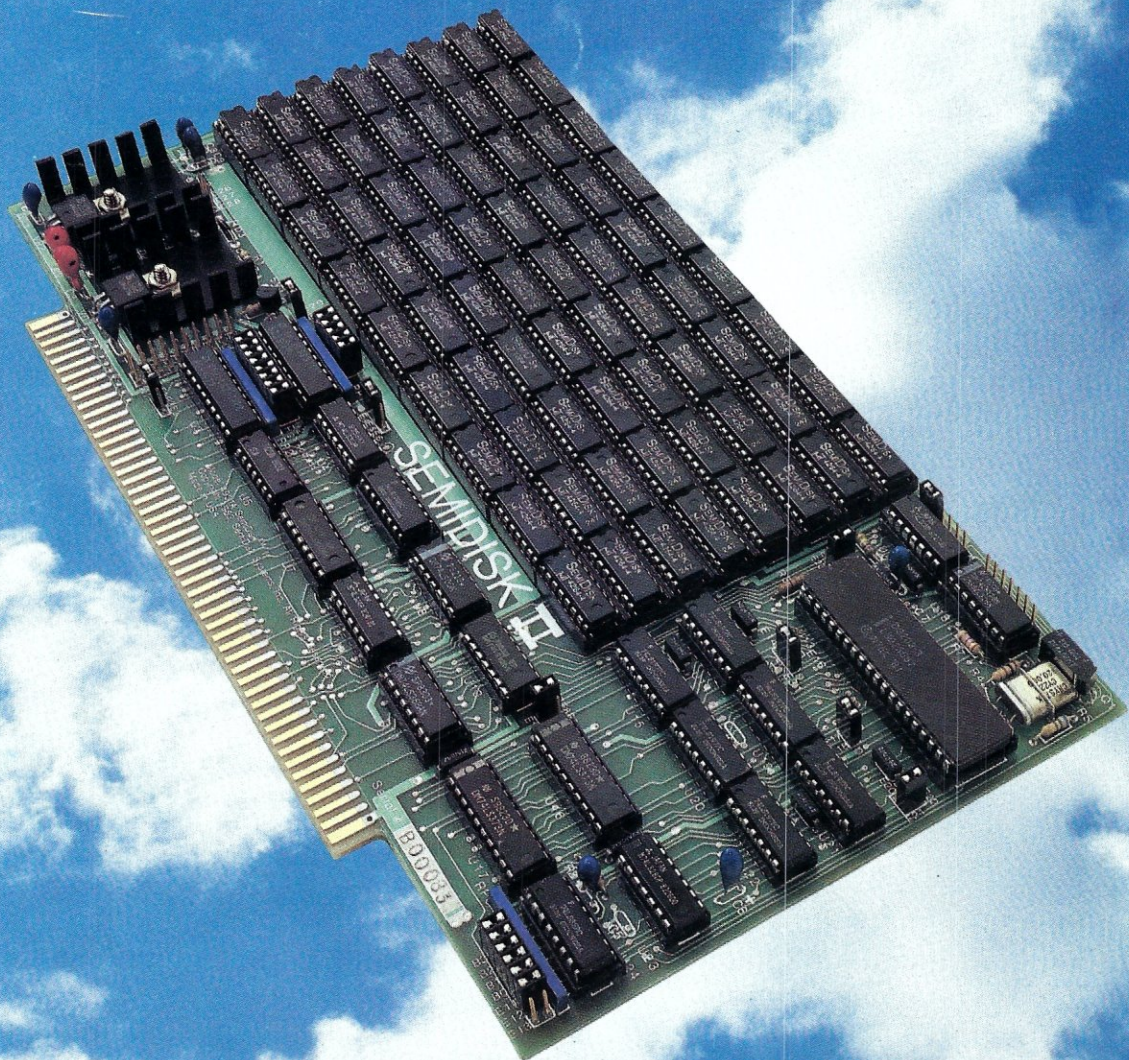
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